

UNIVERSIDAD AUTÓNOMA AGRARIA ANTONIO NARRO  
SUBDIRECCIÓN DE POSTGRADO



EXISTENCIA Y UNICIDAD DE PRUEBAS MÁS POTENTES  
EN MODELOS ESTADÍSTICOS PARAMÉTRICOS

Tesis

Que presenta MAGALY ARISBÉ AGUILERA GONZÁLEZ  
como requisito parcial para obtener el Grado de  
MAESTRA EN ESTADÍSTICA APLICADA

Saltillo, Coahuila

Diciembre de 2015

EXISTENCIA Y UNICIDAD DE PRUEBAS MÁS POTENTES  
EN MODELOS ESTADÍSTICOS PARAMÉTRICOS

Tesis

Elaborada por MAGALY ARISBÉ AGUILERA GONZÁLEZ como requisito parcial para obtener el Grado de MAESTRA EN ESTADÍSTICA APLICADA con la supervisión y aprobación del Comité de Asesoría

---

Dr. Rolando Cavazos Cadena  
Asesor Principal

---

Dr. Mario Cantú Sifuentes  
Asesor

---

M. C. Luis Rodríguez Gutiérrez  
Asesor

---

Dr. Alberto Sandoval Rangel  
Subdirector de Postgrado  
UAAAN

Saltillo, Coahuila

Diciembre de 2015

# Acknowledgement

A **Dios**, quien me da todo.

A mis hijas, por ser los seres capaces de hacer que explote al máximo todas mis capacidades, supere todas las dificultades y busque ser mejor persona cada día.

A mis maestros, por su dedicación, por su don de compartir y motivar.

A mi mamá, por compartir mis anhelos.

A mis hermanos, por estar siempre conmigo.

A mis amigos, por su estímulo, por creer en mí.

Al Dr. *Rolando Cavazos Cadena*, por su guía, entrega, entusiasmo, paciencia y valiosos consejos a lo largo del camino. Por su admirable existencia que ha quedado grabada en mi memoria como un ejemplo a seguir.

# Dedication

A mis hijas, por ser el motor principal de mi existencia, y por el apoyo incondicional y estímulo que me brindaron durante la realización de mis estudios de postgrado.

A mis padres, por haberme dado la oportunidad de recorrer este magnífico camino que se llama vida, y por haberme dado todas las herramientas para recorrerlo de la mejor manera posible.

# COMPENDIO

## EXISTENCIA Y UNICIDAD DE PRUEBAS MÁS POTENTES EN MODELOS ESTADÍSTICOS PARAMÉTRICOS

Por

MAGALY ARISBÉ AGUILERA GONZÁLEZ

MAESTRÍA EN

ESTADÍSTICA APLICADA

UNIVERSIDAD AUTÓNOMA AGRARIA  
ANTONIO NARRO

BUENAVISTA, SALTILLO, COAHUILA, Diciembre de 2015

Dr. Rolando Cavazos Cadena –Asesor–

**Palabras clave:** Modelos estadísticos paramétricos, Pruebas uniformemente más potentes, Pruebas de Neyman-Pearson, Propiedad de insesgamiento, Errores de decisión, Cota inferior para la suma de probabilidades de decisiones incorrectas.

Este trabajo trata sobre dos aspectos fundamentales en la teoría de *prueba de hipótesis* para modelos estadísticos paramétricos, a saber, (i) la posibilidad de cometer errores al decidir sobre la validez de una hipótesis dada o su hipótesis complementaria, y (ii) la noción de insesgamiento de una prueba. Los principales objetivos son (i) establecer una cota inferior para las probabilidades de decidir incorrectamente entre dos hipótesis complementarias dadas, y (ii) demostrar que una prueba de Neyman-Pearson es insesgada en el sentido estricto. La exposición inicia con una descripción breve del problema de prueba de hipótesis en modelos paramétricos, para continuar con una discusión de los posibles errores en que se puede incurrir al tratar de determinar la validez de una hipótesis o de su complementaria basándose en una observación aleatoria; el resultado principal que se obtiene es una cota inferior para la suma de los posibles errores de decisión, mostrando que dicha cota es, generalmente, positiva y que, bajo condiciones menores, es igual a uno. Adicionalmente, se discute la construcción de pruebas de Neyman-Pearson para decidir entre dos hipótesis simples y se establece el insesgamiento estricto de dichas pruebas.

ABSTRACT

EXISTENCE AND UNIQUENESS OF MOST POWERFUL TESTS  
IN PARAMETRIC STATISTICAL MODELS

BY

MAGALY ARISBÉ AGUILERA GONZÁLEZ

MASTER IN

APPLIED STATISTICS

UNIVERSIDAD AUTÓNOMA AGRARIA  
ANTONIO NARRO

BUENAVISTA, SALTILLO, COAHUILA, December, 2015

Dr. Rolando Cavazos Cadena –Advisor–

**Key Words:** Parametric statistical models, Uniformly most powerful tests, Neyman-Pearson tests, Unbiasedness property, Decision Errors, Lower bound for the sum of probabilities of incorrect decisions.

This work is concerned with two basic aspects in the theory of *hypothesis testing* in the context of parametric statistical models, namely, (i) the possibility of taking incorrect decisions when the validity of one of a pair of complementary hypothesis is assessed, and (ii) the idea of *unbiased test*. The main objectives of the thesis are (i) to establish a lower bound for the probabilities of deciding incorrectly between to given complementary hypothesis, and (ii) to prove that a Neyman-Pearson test is strictly unbiased. La exposition begins with a brief description of the testing problem for parametric models, and continues discussing the potential errors that can occur when a random observation vector is used to decide between to complementary hypothesis; the main result established in this direction is that the sum of the probabilities of the possible errors is bounded below by a number that, generally, is positive and, moreover, under mild conditions it is shown that such a bound is equal to 1. Additionally, the existence and construction of a Neyman-Pearson test is discussed, and it is proved that such a test is strictly unbiased.

# Contents

<b>1. This Work in Perspective</b> .....	<b>1</b>
1.1 Introduction .....	1
1.2 Testing a Parametric Hypothesis .....	2
1.3 Main Objectives and Contributions .....	3
1.4 The Origin of This Work .....	4
1.5 The Organization .....	5
<b>2. Test of Hypothesis</b> .....	<b>7</b>
2.1 Statistical Hypothesis .....	7
2.2 Classification of Hypothesis .....	10
2.3 Deterministic and Randomized Tests .....	12
2.4 Incorrect Decisions .....	17
2.5 Null Hypothesis .....	20
2.6 Examples .....	23
<b>3. Neyman-Pearson Theory</b> .....	<b>29</b>
3.1 Likelihood Ratio Tests .....	29
3.2 Existence of Neyman-Pearson tests .....	31
3.3 Construction of Neyman-Pearson Tests .....	33
3.4 Examples .....	35
<b>4. Uniqueness of Neyman-Pearson Tests</b> .....	<b>45</b>
4.1 An Example .....	45
4.2 Comparing two Tests .....	47
4.3 Strict Unbiasedness .....	51
4.4 Monotone Likelihood Ratio .....	53
4.5 Exponential Families .....	56

4.6 Testing Composite Hypothesis .....	59
4.7 Applications .....	63
4.8 Additional Examples .....	66
<b>References .....</b>	<b>78</b>

# Chapter 1

## This Work in Perspective

In this chapter a brief description of this work is given, the main objectives are established and the organization of the subsequent material . The main contributions are clearly stated.

### 1.1. Introduction

This work is concerned with a form of parametric statistical inference known as *hypothesis testing*, which is a basic part of the the classical statistical methodology. The problem to be studied in this work arises frequently in applications, where it of interest to decide whether or not the underlying phenomenon has a certain property. For instance, assume that a new vaccine has been produced and let  $\theta$  be the probability that that a person protected by this new formula

it is For instance, the most basic statistical technique used in agriculture is the so called *analysis of variance*, which is widely used to compare the effects of diverse treatments applied to experimental units; when an analysis of variance is performed, the first objective is to decide whether or not the treatments produce different effects on the experimental units, that is, *to test* the claim of absence of treatments effects. In the area of *quality control*, an important problem is *to test* that the real characteristic  $\mathbf{X}$  of a product has the value  $\delta$  stipulated by the design, and that such a characteristic does not change substantially among the different products. Two graphical devices are used in industry—the  $\bar{\mathbf{X}}$  and  $R$  charts—to decide if the real characteristic coincides in the average with  $\delta$  and to check if the variability of the relevant characteristic is not larger than the admissible tolerance. Every time that that those charts are used, a test of a statistical hypothesis is performed

(Montgomery, 2011).

On the other hand, due to its practical and theoretical relevance, every treatise on Statistics dedicates a good amount of space to study the problem of hypothesis testing, analyzing the construction of statistical tests with optimality properties (Dudewicz and Mishra 1988, Wackerly *et al.* 2009, Lehmann and Romano 1999, or Graybill 2000).

The topics studied in the following chapters are mainly concentrated on three aspects of the theory of hypothesis testing:

- (i) The analysis of the errors that can occur when a statistical test is used;
- (ii) The existence and construction of optimal tests for a given problem of hypothesis testing, and
- (iii) The dependence of an optimal statistical test on sufficient statistics.

Each one of the results presented below are illustrated by detailed examples.

## 1.2. Testing a Parametric Hypothesis

The purpose of a statistical analysis is to use the observed data *to gain knowledge* about some unknown aspect of the process generating the observations. The observable data  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is thought of as a random vector whose distribution is not completely known. Rather, theoretical or modeling considerations lead to assume that the distribution of  $\mathbf{X}$ , say  $P_{\mathbf{X}}$ , belongs to a certain family  $\mathcal{F}$  of probability measures defined on (the Borel class of)  $\mathbb{R}^n$ :

$$P_{\mathbf{X}} \in \mathcal{F}. \tag{1.2.1}$$

This is a statistical model, and in any practical instance it is necessary to include a precise definition of the family  $\mathcal{F}$ . In this work, the main interest concentrates on *parametric models*, for which the family  $\mathcal{F}$  can be indexed by a  $k$ -dimensional vector  $\theta$  whose components are real numbers; in such a case the set of possible values of  $\theta$ , which is referred to as the parameter space, will be denoted by  $\Theta$  and  $\mathcal{F}$  can be written as

$$\mathcal{F} = \{P_{\theta} \mid \theta \in \Theta\}.$$

In this context the model (1.2.1) ensures that *there exists some parameter*  $\theta^* \in \Theta$  such that  $P_{\mathbf{X}} = P_{\theta^*}$ , that is, for every (Borel) subset  $A$  of  $\mathbb{R}^n$

$$P[X \in A] = P_{\mathbf{X}}[A] = P_{\theta^*}[A]. \tag{1.2.2}$$

The parameter  $\theta^*$  satisfying this relation for every (Borel) subset of  $\mathbb{R}^n$  is *the true parameter value*. Notice that the model prescribes the existence of  $\theta^* \in \Theta$  such that the above equality always holds, but does not specify which is the parameter  $\theta^*$ ; it is only supposed that  $\theta^*$  belongs to the parameter space  $\Theta$ . Indeed, the lack of exact knowledge of  $\theta^*$  represents ‘the

aspects that are not completely known' to the analyst about the real process generating the observation vector  $\mathbf{X}$ . One way of getting knowledge about the unknown true parameter value  $\theta^*$  can be described as follows: Suppose that the researcher has reasons to think that  $\theta^*$  belongs to a certain subset  $\Theta_0$  of the parameter space  $\Theta$ , *i.e.*, that

$$\mathcal{H}: \theta^* \in \Theta_0; \tag{1.2.3}$$

such an statement is a (parametric) hypothesis and the objective of the analyst is to use the observed values of the data vector  $\mathbf{X}$  to decide whether or not  $\mathcal{H}$  occurs. If based on the observed value of  $\mathbf{X}$  it is decided that  $\mathcal{H}$  is a correct statement, that is, that  $\theta^* \in \Theta_0$ , then knowledge is gained about  $\theta^*$ : originally, it was known that  $\theta \in \Theta$ , but after the observation of  $\mathbf{X}$  it is declared that  $\theta$  belongs to the smaller subset  $\Theta_0$ , so that *the statement  $\theta \in \Theta_0$  represents less uncertainty than  $\theta \in \Theta$* . On the other hand, if the observation  $\mathbf{X}$  leads the analyst to conclude that  $\mathcal{H}$  is false, then it will be declared that  $\theta^*$  does not belong to  $\Theta_0$ ; since  $\theta$  is assumed to be a member of  $\Theta$ , the conclusion is that the statement

$$\mathcal{K}: \theta \in \Theta \setminus \Theta_0$$

holds; since the set  $\Theta \setminus \Theta_0$  is smaller than  $\Theta_0$ , the above statement also represents less uncertainty than the original inclusion  $\theta \in \Theta$ . In short, assuming that after the observation of  $X$  the analyst can declare that  $\mathcal{H}$  is a correct or an incorrect statement, knowledge about  $\Theta$  will be improved after the experiment. However, in practice a definitive conclusion about the validity of a hypothesis like  $\mathcal{H}$  above can not be established, that is, it is possible to take an incorrect decision, and two errors are possible:

- To declare that  $\mathcal{H}: \theta \in \Theta_0$  is false when it is true, and
- To declare that  $\mathcal{K}: \theta \in \Theta \setminus \Theta_0$  is false when it is true.

The (largest) probabilities of incurring in these errors are denoted by  $\mathcal{E}(\mathcal{H})$  and  $\mathcal{E}(\mathcal{K})$ , respectively, and it will be shown explicitly that both error probabilities  $\mathcal{E}(\mathcal{H})$  and  $\mathcal{E}(\mathcal{K})$  can not be made simultaneously small. Indeed, a positive lower bound for the sum  $\mathcal{E}(\mathcal{H}) + \mathcal{E}(\mathcal{K})$  will be obtained, so that if  $\mathcal{E}(\mathcal{H})$  is 'small', then  $\mathcal{E}(\mathcal{K})$  is necessarily 'large'. It follows that designing a rule to decide which of  $\mathcal{H}$  or  $\mathcal{K}$  is valid is a complex and interesting problem, a fact that provides the motivation for this work.

### 1.3. Main Objectives and Contributions

As already mentioned, this note is concerned with the hypothesis testing problem which can be roughly described as follows: Given a statistical model for an observation vector  $\mathbf{X}$  whose distribution depends on an unknown parameter  $\theta$ , it is desired to decide whether or not a statement of the form  $\mathcal{H}: \theta \in \Theta_0$  is valid. Any rule based on the observed value of  $\mathbf{X}$  that is used to take a decision about the validity of  $\mathcal{H}$  is called a *test*, and *the general objective of this work is to study the construction and properties of a 'good' test*.

The main specific goals of the thesis are as follows:

- (i) To establish a lower bound for the (largest) probabilities of taking an incorrect decision when the validity of a hypothesis  $\mathcal{H}: \theta \in \Theta_0$  or the complementary statement  $\mathcal{K}: \theta \in \Theta \setminus \Theta_0$  are being assessed. The lower bound established below is explicit and holds for every possible decision rule (test) that is used by the analyst.
- (ii) To prove that that, for the testing problem  $\mathcal{H}: \theta = \theta_0$  versus  $\mathcal{K}: \theta = \theta_1$ , the optimal test is strictly unbiased; the unbiasedness property is a desirable property of any test, and the result in this direction is an improvement of the conclusions usually stated in classical treatises.
- (iii) To illustrate the diverse ideas studied below using carefully analyzed examples.

The *main contributions* presented below can be briefly described as follows: As for the first objective, it is established that the largest error probabilities  $\mathcal{E}(\mathcal{H})$  and  $\mathcal{E}(\mathcal{K})$  satisfy

$$\mathcal{E}(\mathcal{H}) + \mathcal{E}(\mathcal{K}) \geq \ell(\mathcal{H}, \mathcal{K})$$

where  $\ell(\mathcal{H}, \mathcal{K})$  is a generally positive number depending on the model, but not on the test used to decide whether or not  $\mathcal{H}$  is a valid claim; moreover, it is shown that under the mild condition that the sets  $\Theta_0$  and  $\Theta \setminus \Theta_0$  share a boundary point, such a lower bound is equal to 1. Concerning the second objective, the main conclusion establishes that, for the problem of testing  $\mathcal{H}: \theta = \theta_0$  versus  $\mathcal{K}: \theta = \theta_1$ , the relation  $\mathcal{E}(\mathcal{H}) < 1 - \mathcal{E}(\mathcal{K})$  occurs, improving the inequality  $\mathcal{E}(\mathcal{H}) \leq 1 - \mathcal{E}(\mathcal{K})$  that is usually presented in the literature. Finally, it is worth mentioning that the examples presented below are analyzed in full detail, paying attention to all relevant technical arguments, a feature that makes the presentation self-contained.

#### 1.4. The Origin of This Work

This work may be considered as a product of the activities developed in the project *Mathematical Statistics: Elements of Theory and Examples*, started on July 2011 by the Graduate Program in Statistics at the Universidad Autónoma Agraria Antonio Narro; the founder students were Mary Carmen Ruiz Moreno and Alfonso Soto Almaguer, and other participants include Ana Paula Isais, Alberto Aguilar, María Elena Berlanga, Julieta Bautista, and María de Jesús Pinales Chávez. The basic aims of the project are:

- (i) To be a framework where statistical problems can be freely and fruitfully discussed;
- (ii) To promote the *understanding* of basic statistical and analytical tools through the analysis and detailed solution of exercises.
- (iii) To develop the *writing skills* of the participants, generating an organized set of neatly solved examples, which can be used by other members of the program, as well as by the statistical communities in other institutions and countries.

(iv) To develop the *communication skills* of the students and faculty through the regular participation in seminars, were the results of their activities are discussed with the members of the program.

The activities of the project are concerned with fundamental statistical theory at an intermediate (non-measure theoretical) level, as in the book *Mathematical Statistics* by Dudewicz and Mishra (1998). When necessary, other more advanced references that have been useful are Lehmann and Casella (1998), Borobkov (1999) and Shao (2002), whereas deeper probabilistic aspects have been studied in the classical text by Loève (1984). On the other hand, statistical analysis requires algebraic and analytical tools, and in these directions the basic references in the project are Apostol (1980), Fulks (1980), Khuri (2002) and Royden (2003), which concern mathematical analysis, whereas the algebraic aspects are covered in Graybill (2001) and Harville (2008). Initially, the project was concerned with the theory of Point Estimation and, starting on July 20012, the Theory of Hypothesis Testing has been studied; these work, as well as the one in Pinales Chávez (2013), may be considered as a product of all the activities of the project during the last year, and reflect the discussions and different perspectives of analysis of all the participants. In particular, it is a real pleasure to thank to my classmate, Alfonso Soto Almaguer, by his generous help and clever suggestions.

## 1.5. The Organization

The remainder of this work has been organized as follows:

In Chapter 2 the basic ideas and terminology involved in the study of hypothesis testing are introduced. The presentation begins with a brief description of a parametric statistical model, and then the notion of statistical hypothesis is introduced. Next, after presenting the ideas of simple, composite and complementary hypothesis, the notion of (deterministic, non-randomized) *test* is formally defined, and the exposition concludes studying the concept of randomized test.

Next, in Chapter 3 the possibility of taking an incorrect decision when testing a hypothesis  $\mathcal{H}$  is studied. The main conclusion to be established below is that, regardless of the test  $\gamma$  used by the analyst, the possibility of an erroneous decision can not be generally avoided. The main contributions of this work are stated in Theorem 3.1, and Lemmas 3.2.1 and 3.3.1.

Then, Chapter 4 is concerned with parametric statistical models whose parameter space consists of two points  $\theta_0$  and  $\theta_1$ , and the problem of testing the hypothesis  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$  is studied. For this problem, the existence of an optimal (most powerful) test is rigorously established and it is proved that such a test is unbiased.

Finally, the exposition concludes in Chapter 5 analyzing two basic properties that are satisfied by a most powerful test. The first one concerns a natural and intuitive condition: Under a reasonable test, the probability of rejecting the null hypothesis when it is false must be at least equal to the probability of rejection when  $\mathcal{H}_0$  is true; a test with this property is called *unbiased*. The second property refers to the information that must be gathered in order to apply a most powerful test. The main result in this direction establishes that, when a simple hypothesis is being tested versus another simple hypothesis, a most powerful test can be always specified in terms of a sufficient statistic. The main contribution of this chapter is Theorem 5.4.1, establishing that a Neyman-Pearson test is strictly unbiased.

# Chapter 2

## Test of Hypothesis

In this chapter the basic ideas and terminology involved in the study of hypothesis testing are introduced. The presentation begins with a brief description of a parametric statistical model, and then the notion of statistical hypothesis is introduced. Next, after presenting the ideas of simple, composite and complementary hypothesis, the notion of (deterministic, non-randomized) *test* is formally defined, and the exposition concludes studying the concept of randomized test.

### 2.1. Statistical Hypothesis

A statistical model for a random vector postulates that the distribution of the vector belongs to a certain family of probability measures. As it was already mentioned, in this work it will be assumed that the class of potential distributions of the observation vector  $\mathbf{X}$  is indexed by a parameter  $\theta$  whose components are real numbers, and  $P_\theta$  stands for the distribution associated with  $\theta$ . Thus, a statistical model may be written as

$$\mathbf{X} \sim P_\theta, \quad \theta \in \Theta, \tag{2.1.1}$$

where  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is the observation vector and, for each  $\theta$  in the parameter space  $\Theta \subset \mathbb{R}^k$ , the probability measure  $P_\theta$  is defined on (the Borel sets of)  $\mathbb{R}^n$ . This model prescribes that the distribution  $P_{\mathbf{X}}$  of the observation vector  $\mathbf{X}$  is  $P_\theta$  for some  $\theta \in \Theta$ , that is,

there exists  $\theta \in \Theta$  such that for ‘any set  $A \subset \mathbb{R}^n$ ’ the probability that  $\mathbf{X}$  belongs to  $A$  is  $P_{\mathbf{X}}[A] = P_\theta[A]$ .

More explicitly, there exists  $\theta \in \Theta$  such that

(i) If  $P_\theta$  is a continuous distribution with density  $f(\mathbf{x}; \theta)$ , then

$$P_X[A] = P[\mathbf{X} \in A] = \int_A f(\mathbf{x}; \theta) d\mathbf{x},$$

and

(ii) If  $P_\theta$  is a discrete distribution with probability function  $f(\mathbf{x}; \theta)$ , then

$$P_X[A] = P[\mathbf{X} \in A] = \sum_{\mathbf{x} \in A} f(\mathbf{x}; \theta).$$

The following basic *identifiability* condition is enforced throughout the remainder.

**Assumption 2.1.1.** For each  $\theta_0, \theta_1 \in \Theta$  with  $\theta_0 \neq \theta_1$ , the corresponding distributions are different. More explicitly, if  $\theta_0 \neq \theta_1$ , then there exists a set  $A$  such that

$$P_{\theta_0}[A] \neq P_{\theta_1}[A].$$

In words, this condition establishes that, for the model (2.1.1), different parameters correspond to different distributions.

**Remark 2.1.1.** Usually, a statistical model is specified by giving a condition that allows to determine a family of probability measures containing the distribution of the observation vector  $\mathbf{X}$ . A common situation is as follows:

- (i) It is supposed that the components of  $\mathbf{X}$  are independent and identically distributed with common density or probability function  $f(\cdot; \theta)$ , and
- (i) The unknown parameter  $\theta$  is a member of a given set  $\Theta$ ,

requirements that are summarized as

$$X_1, X_2, \dots, X_n \sim i.i.d. \ f(x; \theta), \quad \theta \in \Theta. \quad (2.1.2)$$

When the common density or probability function of the variables  $X_i$  is  $f(x; \theta)$ , the independence property in condition (i) yields that the distribution of  $\mathbf{X}$  is the probability measure  $P_\theta$  specifying that, for each (Borel) set  $A \subset \mathbb{R}^n$ ,

$$P_\theta[A] = \begin{cases} \int_A f(x_1; \theta) f(x_2; \theta) \cdots f(x_n; \theta) d\mathbf{x}, & \text{if } f(\cdot; \theta) \text{ is a density,} \\ \sum_{\mathbf{x} \in A} f(x_1; \theta) f(x_2; \theta) \cdots f(x_n; \theta), & \text{if } f(\cdot; \theta) \text{ is a probability function,} \end{cases}$$

where

$$\mathbf{x} = (x_1, x_2, \dots, x_n) \quad \text{and} \quad d\mathbf{x} = dx_1 dx_2 \cdots dx_n;$$

since condition (ii) establishes that  $\theta$  is an arbitrary element of parameter space  $\Theta$ , the statement (2.1.2) is equivalent to (2.1.1). On the other hand, the above conditions (i) and (ii) are frequently summarized as

$$\mathbf{X} \text{ is a sample of } f(x; \theta), \quad \theta \in \Theta,$$

so that this statement and (2.1.2) are equivalent; if the distribution corresponding to  $f(\cdot; \theta)$  is denoted by  $\mathcal{D}(\theta)$ , then the above display and

$$\mathbf{X} \text{ is a sample of } \mathcal{D}(\theta), \quad \theta \in \Theta$$

are equivalent statements. □

Notice that the specific parameter value  $\theta$  that corresponds to the distribution of  $\mathbf{X}$  is *unknown*, because the model prescribes only that such a parameter belongs to the space  $\Theta$ . The objective of performing the experiment rendering the vector  $\mathbf{X}$  is to use the observed value  $\mathbf{X} = \mathbf{x}$  to obtain ‘information’ about the *precise* or *true* value of  $\theta$  such that  $P_{\mathbf{X}} = P_{\theta}$ ; the statistical procedures using the observed values of  $\mathbf{X}$  to obtain ‘conclusions’ about the true parameter value constitute that is called *statistical inference*. This chapter studies a particular form of statistical inference called *hypothesis testing* which can be described as follows:

Originally, the model prescribes that the distribution  $P_{\mathbf{X}}$  of  $\mathbf{X}$  is a member of the family  $\{P_{\theta}, \theta \in \Theta\}$ , and the problem consists in deciding whether or not the observed values of  $\mathbf{X}$  support the assertion that the distribution of  $\mathbf{X}$  belongs to the smaller family  $\{P_{\theta}, \theta \in \Theta_0\}$ , where  $\Theta_0$  is a *subset* of  $\Theta$ .

**Definition 2.1.1.** Consider the statistical model (2.1.1) for the observation vector  $\mathbf{X}$ . A hypothesis  $\mathcal{H}$  is a statement of the form

$$\mathcal{H} : \theta \in \Theta_0, \tag{2.1.3}$$

where  $\Theta_0$  is a subset of the parameter space  $\Theta$ .

The hypothesis (2.1.3) is interpreted as the assertion that the distribution of  $\mathbf{X}$  belongs to the reduced family  $\{P_{\theta}, \theta \in \Theta_0\}$ , and represents conditions whose validity is of interest for the analyst

**Example 2.1.1.** To study the labor security in a local factory, the number of accidents  $X_1, X_2, \dots, X_n$  occurring in  $n$  weeks is recorded. Suppose that the variables  $X_i$  are independent and identically distributed random variables with Poisson distribution:

$$X_1, X_2, \dots, X_n \text{ is a sample of } \mathcal{P}(\theta), \quad \theta > 0.$$

In this case the parameter space is  $\Theta = (0, \infty)$  and the (unknown) parameter  $\theta$  is the expected number of accidents in a week. Several hypothesis might be of interest. For instance, suppose that in other countries the expected number of accidents in similar factories is 3.

(i) The condition that the security in the national factory is higher than the one in foreign factories is expressed by the hypothesis  $\mathcal{H} : \theta \in (0, 3)$ , that is,

$$\mathcal{H} : \theta < 3.$$

(ii) The hypothesis

$$\mathcal{H} : \theta = 3$$

is interpreted as the assertion that the security in the local factory is the same as in the foreign ones, whereas

(iii) The assertion that the security in the local factory is worse than the one in foreign factories is expressed as

$$\mathcal{H} : \theta > 3$$

In each one of these cases the problem is to see if the observed value of the variables  $X_1, X_2, \dots, X_n$  support the validity of the corresponding hypothesis.  $\square$

## 2.2. Classification of Hypothesis

In this section a simple classification of hypothesis is formulated and the idea of complementary hypothesis is introduced.

**Definition 2.2.1.** A hypothesis  $\mathcal{H} : \theta \in \Theta_0$  is *simple* if  $\Theta_0 = \{\theta_0\}$  is a singleton, so that  $\mathcal{H}$  can be expressed as

$$\mathcal{H} : \theta = \theta_0,$$

whereas  $\mathcal{H}$  is *composite* when  $\Theta_0$  has two or more elements.

In the context of Example 2.1.1 the Hypothesis in parts (i) and (iii) are composite, whereas the Hypothesis  $\mathcal{H} : \theta = 3$  in part (ii) is simple. The following examples discuss the ideas in Definition 2.2.1.

**Exercise 2.2.1.** Suppose that  $X_1, X_2, \dots, X_n$  is a sample of  $\mathcal{N}(\mu, \sigma^2)$ .

(i) If  $\sigma^2$  is *known*, determine whether each hypothesis is simple or composite, where  $\mu_0$  is a known constant.

(a)  $\mathcal{H} : \mu = \mu_0$ ;

(b)  $\mathcal{H} : \mu > \mu_0$ ;

(c)  $\mathcal{H} : \mu \neq \mu_0$ ;

(d)  $\mathcal{H} : \mu \in I$ , where  $I$  is a specified interval with positive length.

(ii) If  $\sigma^2$  is *unknown*, determine whether each of the four hypothesis formulated above is simple or composite.

**Solution.** (i) Notice that the parameter is  $\mu$ , and the parameter space is  $(-\infty, \infty)$ . In case (a) the value of the parameter is completely determined by the hypothesis, which can be written as  $\mathcal{H} : \mu \in \{\mu_0\}$ , and then the hypothesis is simple. However, in cases (b), (c) and (d), the hypothesis is composite, since it does not determine exactly the value of the parameter. For instance,  $\mathcal{H}$  can be written as

$$\mathcal{H} : \mu \in (\mu_0, \infty)$$

in case (b), and as

$$\mathcal{H} : \mu \in (-\infty, \mu_0) \cup (\mu_0, \infty)$$

in case (c).

(ii) In this context, the parameter is  $\theta = (\mu, \sigma^2)$  and

$$\Theta = \{(\mu, \sigma^2) \mid \mu \in \mathbb{R}, \sigma^2 > 0\} = \mathbb{R} \times (0, \infty).$$

is the parameter space. Neither of the hypothesis determines the value of  $\theta = (\mu, \sigma^2)$  exactly, and then all of the hypothesis are composite. For instance,  $\mathcal{H}$  can be written as  $\mathcal{H} : \theta = (\mu, \sigma^2) \in \Theta_0 = \{0\} \times (0, \infty)$  in case (a), and then, since  $\Theta_0$  contains more than one element, it follows that  $\mathcal{H}$  is composite.  $\square$

**Remark 2.2.1.** Other common formulation of the idea of simple hypothesis is the following:

A hypothesis  $\mathcal{H}$  is simple if, under  $\mathcal{H}$ , the distribution of the observation vector is uniquely determined.

Notice that if  $\mathcal{H}$  can be expressed as  $\mathcal{H} : \theta = \theta_0$  (where  $\theta_0$  is known), then under  $\mathcal{H}$  the distribution of  $\mathbf{X}$  is uniquely determined and is equal to  $P_{\theta_0}$ .  $\square$

**Exercise 2.2.2.** Are the following hypothesis simple or composite?

(a)  $\mathcal{H} : \mathbf{X}$  is a sample of an exponential distribution with some parameter  $\theta$ ;

(b) If  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of size  $n$  of  $\mathcal{N}(\mu, \sigma^2)$ , where  $\theta = (\mu, \sigma^2) \in \mathbb{R} \times (0, \infty)$ ,

$$\mathcal{H} : \frac{E_{\theta}[X_1]}{\text{Var}_{\theta}[X_1]} = c_0$$

where  $c_0$  is a known constant.

(c) If  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of size  $n$  of *Bernoulli*( $\theta$ ) where  $\theta \in (0, 1)$ ,

$$\mathcal{H} : \frac{E_\theta[X_1]}{\text{Var}_\theta[X_1]} = c_0$$

where  $c_0$  is a known constant.

**Solution.** (a) Under  $\mathcal{H}$  the distribution of the variables  $X_i$  is exponential, but the parameter of the distribution is unknown; thus, under  $\mathcal{H}$  the distribution of the observation vector  $\mathbf{X}$  is not uniquely determined, and then  $\mathcal{H}$  is composite.

(b) Since  $E_\theta[X_1] = \mu$  and  $\text{Var}_\theta[X_1] = \sigma^2$ , the hypothesis can be explicitly written as

$$\mathcal{H} : \frac{\mu}{\sigma^2} = c_0, \quad \text{or} \quad \mathcal{H} : \mu = c_0 \sigma^2.$$

Therefore, under  $\mathcal{H}$  the parameter  $\theta = (\mu, \sigma^2)$  is not uniquely determined, and then  $\mathcal{H}$  is composite.

(c) Using that  $E_\theta[X_1] = \theta$  and  $\text{Var}_\theta[X_1] = \theta(1 - \theta)$ , in the present case  $\mathcal{H}$  can be stated as

$$\mathcal{H} : \frac{\theta}{\theta(1 - \theta)} = c_0,$$

that is,

$$\mathcal{H} : \theta = 1 - \frac{1}{c_0}.$$

Consequently, under  $\mathcal{H}$  the distribution of  $\mathbf{X}$  is uniquely determined, so that  $\mathcal{H}$  is a simple hypothesis.  $\square$

A natural companion to a hypothesis  $\mathcal{H}$  is the statement that the property stipulated by  $\mathcal{H}$  does not occur.

**Definition 2.2.2.** Let  $X \sim P_\theta$ ,  $\theta \in \Theta$  be a statistical model. Given a hypothesis  $\mathcal{H} : \theta \in \Theta_0$ , the corresponding *complementary* hypothesis is

$$\mathcal{K} : \theta \in \Theta \setminus \Theta_0.$$

**Example 2.2.1.** The following examples show a hypothesis  $\mathcal{H}$  and the corresponding complementary hypothesis  $\mathcal{K}$ .

(i)  $\mathcal{H} : \mu > \mu_0$ ,  $\mathcal{K} : \mu \leq \mu_0$ .

(ii)  $\mathcal{H} : \frac{\mu}{\sigma^2} = c_0$ ,  $\mathcal{K} : \frac{\mu}{\sigma^2} \neq c_0$ .

(iii)  $\mathcal{H} : \mu + 1.96\sigma \leq 3$ ,  $\mathcal{K} : \mu + 1.96\sigma > 3$ .  $\square$

### 2.3. Deterministic and Randomized Tests

As already mentioned, given a statistical hypothesis  $\mathcal{H}$ , the main objective of the analyst is to decide whether or not the observed data support the properties of the parameter stipulated by  $\mathcal{H}$ . The classical theory faces this problem as a decision between the validity of the original hypothesis  $\mathcal{H}$  and the complementary hypothesis  $\mathcal{K}$ , that is, if it is decided that the observed data support the validity of  $\mathcal{H}$ , then  $\mathcal{H}$  is ‘accepted’ and, consequently,  $\mathcal{K}$  is ‘rejected’; of course, when according to the criterion of the analyst the available data do not support  $\mathcal{H}$ , then  $\mathcal{H}$  is ‘rejected’ and  $\mathcal{K}$  is ‘accepted’.

**Definition 2.3.1.** Given a statistical model  $\mathbf{X} \sim P_\theta$ ,  $\theta \in \Theta$ , consider a hypothesis  $\mathcal{H} : \theta \in \Theta_0$  and the corresponding complementary hypothesis  $\mathcal{K} : \theta \in \Theta \setminus \Theta_0$ . Let  $\mathcal{X}$  be the set of possible values of the observation vector  $\mathbf{X}$ , that is,

$$\mathcal{X} = \{\mathbf{x} \mid f(\mathbf{x}; \theta) > 0 \text{ for some } \theta \in \Theta\}, \quad (2.3.1)$$

and notice that

$$P_\theta[\mathbf{X} \in \mathcal{X}] = 1, \quad \theta \in \Theta. \quad (2.3.2)$$

A test  $\gamma$  of  $\mathcal{H}$  versus  $\mathcal{K}$  is a partition of  $\mathcal{X}$  into two sets  $\mathcal{A}$  and  $\mathcal{R} (= \mathcal{X} \setminus \mathcal{A} = \mathcal{A}^c)$ , called the *acceptance and rejection* regions, respectively. When using  $\gamma$ , the decision taken after observing  $\mathbf{X} = \mathbf{x}$  is denoted by  $\gamma(\mathbf{x})$  and is determined as follows:

$$\gamma(\mathbf{x}) = \begin{cases} \text{Accept } \mathcal{H} \text{ (equivalently, Reject } \mathcal{K}), & \text{if } \mathbf{x} \in \mathcal{A} \\ \text{Reject } \mathcal{H} \text{ (equivalently, Accept } \mathcal{K}), & \text{if } \mathbf{x} \in \mathcal{R} \end{cases}$$

Thus, after observing  $\mathbf{X}$ , the analyst always ends up with a decision about the validity of  $\mathcal{H}$ ; the properties stipulated by  $\mathcal{H}$  are ‘accepted’ or ‘rejected’.

**Example 2.3.1.** Let  $\mathbf{X} = (X_1, X_2, \dots, X_{16})$  be a sample of the *Poisson*( $\theta$ ) distribution, where  $\theta \in (0, \infty)$ , and consider the hypothesis

$$\mathcal{H} : \theta \leq 12,$$

as well as the companion complementary hypothesis  $\mathcal{K} : \theta > 12$ . Observing that  $\theta$  is the mean of the variables  $X_i$ , it is natural to estimate the unknown value of  $\theta$  by the sample average  $\bar{\mathbf{X}} = (X_1 + X_2 + \dots + X_{16})/16$ , which is taken as an approximation of the true parameter value. Since according to  $\mathcal{H}$  the parameter does not exceed 12, it is natural to reject  $\mathcal{H}$  if  $\bar{\mathbf{X}}$  is ‘substantially’ larger than 12, for instance if  $\bar{\mathbf{X}} > 15$ . These considerations lead to formulate the following procedure to reject or accept  $\mathcal{H}$ :

$$\gamma(\mathbf{X}) = \begin{cases} \text{Accept } \mathcal{H} : \theta \leq 12 \text{ (equivalently, Reject } \mathcal{K} : \theta > 12), & \text{if } \bar{\mathbf{X}} \leq 15 \\ \text{Reject } \mathcal{H} : \theta \leq 12 \text{ (equivalently, Accept } \mathcal{K} : \theta > 12), & \text{if } \bar{\mathbf{X}} > 15. \end{cases} \quad (2.3.3)$$

Notice that in the present case the set of possible values of the observation vector  $\mathbf{X}$  is

$$\mathcal{X} = \{\mathbf{x} = (x_1, x_2, \dots, x_{16}) | x_i \text{ is a nonnegative integer, } i = 1, 2, \dots, 16\},$$

and that the acceptance and rejection regions corresponding to the test  $\gamma$  are given by

$$\mathcal{A} = \{\mathbf{x} \in \mathcal{X} | \bar{x} \leq 15\}, \quad \mathcal{R} = \{\mathbf{x} \in \mathcal{X} | \bar{x} > 15\},$$

where  $\bar{x} = (x_1 + x_2 + \dots + x_{16})/16$ . □

**Example 2.3.2.** Suppose now that  $\mathbf{X} = (X_1, X_2, \dots, X_{16})$  is a sample of the  $\mathcal{N}(\theta, 1)$  distribution, where  $\theta \in \mathbb{R}$  and, consider the hypothesis

$$\mathcal{H} : 10 \leq \theta \leq 12$$

as well as the complementary hypothesis

$$\mathcal{K} : \theta < 10 \quad \text{or} \quad \theta > 12.$$

Since  $\theta$  is the mean of the variables  $X_i$ , the sample average  $\bar{\mathbf{X}} = (X_1 + X_2 + \dots + X_{16})/16$  is a natural estimator of  $\theta$ . On the other hand, because according to  $\mathcal{H}$  the true parameter lies between 10 and 12, it is natural to reject  $\mathcal{H}$  if  $\bar{\mathbf{X}}$  is ‘substantially’ far from the interval  $[10, 12]$ , say if  $\bar{\mathbf{X}} > 15$  or  $\bar{\mathbf{X}} < 7$ , and this leads to formulate the following testing procedure to reject or accept  $\mathcal{H}$ :

$$\gamma(\mathbf{X}) = \begin{cases} \text{Accept } \mathcal{H} : 10 \leq \theta \leq 12, & \text{if } 7 \leq \bar{\mathbf{X}} \leq 15 \\ \text{Reject } \mathcal{H} : 10 \leq \theta < 12, & \text{if } \bar{\mathbf{X}} < 7 \quad \text{or} \quad \bar{\mathbf{X}} > 15. \end{cases} \quad (2.3.4)$$

In this example the set of possible values of the observation vector  $\mathbf{X}$  is

$$\mathcal{X} = \{\mathbf{x} = (x_1, x_2, \dots, x_{16}) | x_i \in \mathbb{R} \text{ for all } i = 1, 2, \dots, 16\} = \mathbb{R}^{16},$$

whereas that the acceptance and rejection regions corresponding to the test  $\gamma$  are given by

$$\mathcal{A} = \{\mathbf{x} \in \mathcal{X} | 7 \leq \bar{x} \leq 15\}, \quad \mathcal{R} = \{\mathbf{x} \in \mathcal{X} | \bar{x} < 7 \text{ or } \bar{x} > 15\}$$

where, as before,  $\bar{x}$  is the average of the components of  $\mathbf{x}$ . □

The above idea of test is generalized to include the so called *randomized tests*.

**Definition 2.3.2.** Let  $\mathbf{X} \sim P_\theta$ ,  $\theta \in \Theta$  be a statistical model, and let  $\mathcal{X}$  be the set of possible values of the observation  $\mathbf{X}$ ; see (2.3.2).

- (i) A mapping  $\varphi: \mathcal{X} \rightarrow [0, 1]$  is referred to as a *critical function*.
- (ii) Consider a hypothesis  $\mathcal{H} : \theta \in \Theta_0$  and the complementary hypothesis  $\mathcal{K} : \theta \in \Theta \setminus \Theta_0$ . The randomized test  $\gamma_\varphi \equiv \gamma$  corresponding to a critical function  $\varphi$  is the random variable  $\gamma(\mathbf{X})$  whose conditional distribution given  $\mathbf{X}$  is determined as follows:  $\gamma(\mathbf{X})$  takes on the two values ‘Accept  $\mathcal{H}$ ’ and ‘Reject  $\mathcal{H}$ ’, and

$$P[\gamma(\mathbf{X}) = \text{Reject } \mathcal{H} | \mathbf{X}] = \varphi(\mathbf{X}),$$

whereas

$$P[\gamma(\mathbf{X}) = \text{Accept } \mathcal{H} | \mathbf{X}] = 1 - \varphi(\mathbf{X}).$$

For a given critical function  $\varphi$ , the value  $\varphi(\mathbf{X})$  may be thought of as the strength of the evidence to reject  $\mathcal{H}$  that, according to the analyst’s criterion, is provided by the observation vector  $\mathbf{X}$ .

**Remark 2.3.1.** (i) An observer using the randomized test  $\gamma_\varphi$  corresponding to a critical function  $\varphi$  operates as follows:

If  $\mathbf{X} = \mathbf{x}$  is observed, then

- $\mathcal{H}$  is rejected when  $\varphi(\mathbf{x}) = 1$ ,
- $\mathcal{H}$  is accepted if  $\varphi(\mathbf{x}) = 0$ ,
- When  $0 < \varphi(\mathbf{x}) < 1$ , a Bernoulli experiment with success probability  $\varphi(\mathbf{x})$  is performed, and if the result of the experiment is ‘success’, the hypothesis  $\mathcal{H}$  is rejected, whereas  $\mathcal{H}$  is accepted when the result is ‘failure’.

As it will be shown later, randomized tests have a great theoretical importance.

(ii) It is interesting to observe that the (non-randomized) tests in Definition 2.3.1 are a particular class of randomized tests. Indeed, let  $\gamma$  be a test in the sense of Definition 2.3.1, and let  $\mathcal{R}$  be the corresponding rejection region. Define  $\varphi: \mathcal{X} \rightarrow [0, 1]$  as the indicator function of  $\mathcal{R}$ , that is,

$$\varphi(\mathbf{x}) = I_{\mathcal{R}}(\mathbf{x}) = \begin{cases} 1, & \text{if } \mathbf{x} \in \mathcal{R} \\ 0, & \text{if } \mathbf{x} \in \mathcal{X} \setminus \mathcal{R} = \mathcal{A}. \end{cases}$$

Now, consider the randomized test  $\gamma_\varphi$  corresponding to this critical function  $\varphi$ , so that

$$P[\gamma_\varphi(\mathbf{X}) = \text{Reject } \mathcal{H} | \mathbf{X}] = \begin{cases} 1, & \text{if } \varphi(\mathbf{X}) = 1, \text{ that is, if } \mathbf{X} \in \mathcal{R}, \\ 0, & \text{if } \varphi(\mathbf{X}) = 0, \text{ i.e., if } \mathbf{X} \in \mathcal{A}. \end{cases}$$

It follows that the decision  $\gamma_\varphi(\mathbf{X})$  is ‘Reject  $\mathcal{H}$ ’ when  $\mathbf{X} \in \mathcal{R}$ , and  $\gamma_\varphi(\mathbf{X})$  is ‘Accept  $\mathcal{H}$ ’ if  $\mathbf{X} \in \mathcal{A} = \mathcal{X} \setminus \mathcal{R}$ ; thus,  $\gamma_\varphi$  is the test  $\gamma$  with rejection region  $\mathcal{R}$  and acceptance region

A. This argument shows that the tests described in Definition 2.3.1 correspond to critical functions attaining exclusively the values 0 and 1.  $\square$

Some examples illustrating the ideas recently introduced are presented below.

**Example 2.3.3.** (i) As in Example 2.3.1, let  $\mathbf{X} = (X_1, X_2, \dots, X_{16})$  be a sample of the *Poisson*( $\theta$ ) distribution, where  $\theta \in (0, \infty)$ , and consider the hypothesis  $\mathcal{H} : \theta \leq 12$ . The test in (2.3.3) corresponds to the critical function

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \bar{\mathbf{X}} > 15 \\ 0, & \text{if } \bar{\mathbf{X}} \leq 15; \end{cases}$$

using the notation of indicator functions,  $\varphi(\mathbf{X}) = I_{(15, \infty)}(\bar{\mathbf{X}})$ .

(ii) Suppose again that  $\mathbf{X} = (X_1, X_2, \dots, X_{16})$  is a sample of the *Poisson*( $\theta$ ) distribution with  $\theta > 0$ . An example of a randomized test for  $\mathcal{H} : \theta \leq 12$  has the following critical function:

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \bar{\mathbf{X}} > 15 \\ 1/2 & \text{if } \bar{\mathbf{X}} = 15 \\ 0, & \text{if } \bar{\mathbf{X}} < 15 \end{cases}$$

The test  $\gamma_\varphi$  corresponding to this critical function rejects  $\mathcal{H}$  when  $\bar{\mathbf{X}} > 15$  and accepts  $\mathcal{H}$  if  $\bar{\mathbf{X}} < 15$ ; however, when  $\bar{\mathbf{X}} = 15$  a Bernoulli experiment with success probability 1/2 is performed, and  $\mathcal{H}$  is rejected if a success is obtained, whereas a failure leads to acceptance of  $\mathcal{H}$ . With the notation of indicator function  $\varphi$  can be specified by

$$\varphi(\mathbf{X}) = I_{(15, \infty)}(\bar{\mathbf{X}}) + \frac{1}{2} I_{\{15\}}(\bar{\mathbf{X}}).$$

(iii) Continuing with Example 2.3.2, suppose that  $\mathbf{X} = (X_1, X_2, \dots, X_{16})$  is a sample of the  $\mathcal{N}(\theta, 1)$  distribution, where  $\theta \in \mathbb{R}$  and, consider the hypothesis

$$\mathcal{H} : 10 \leq \theta \leq 12$$

and the complementary

$$\mathcal{K} : \theta < 10 \quad \text{or} \quad \theta > 12.$$

The test  $\gamma$  in (2.3.4) is associated to the critical function

$$\varphi(\mathbf{X}) = \begin{cases} 0, & \text{if } 7 \leq \bar{\mathbf{X}} \leq 15 \\ 1, & \text{if } \bar{\mathbf{X}} < 7 \quad \text{or} \quad \bar{\mathbf{X}} > 15; \end{cases}$$

notice that the test  $\gamma$  is non-randomized, and for this reason the critical function takes only the values 0 and 1. With the notation of indicator functions,

$$\varphi(\bar{\mathbf{X}}) = I_{(-\infty, 7) \cup (15, \infty)}(\bar{\mathbf{X}}).$$

(iv) In the context of the previous part, a ‘reasonable’ randomized test will be now described. Recall that  $\bar{\mathbf{X}}$  is a ‘good’ estimator of the mean  $\theta$  of the  $\mathcal{N}(\theta, 1)$  distribution, and suppose that the analyst considers the distance between  $\bar{\mathbf{X}}$  and  $[7, 10]$  as a measure of the evidence provided by that data against  $\mathcal{H}$ ; as the distance gets larger, the evidence against  $\mathcal{H}$  increases. Moreover, assume that the analyst considers a distance of three or less units as an event due to chance, but a distance of size five or more units is regarded as a definitive evidence against  $\mathcal{H}$ . For distances from 3 to 5, the evidence against  $\mathcal{H}$  increases linearly from 0 to 1. These considerations lead to formulate the critical function of the analyst as follows:

$$\varphi(\mathbf{X}) = \begin{cases} 0, & \text{if } 7 \leq \bar{\mathbf{X}} \leq 15 \\ 1, & \text{if } \bar{\mathbf{X}} < 5 \text{ or } \bar{\mathbf{X}} > 17 \\ (7 - \bar{\mathbf{X}})/2, & \text{if } 5 \leq \bar{\mathbf{X}} < 7 \\ (\bar{\mathbf{X}} - 15)/2, & \text{if } 15 < \bar{\mathbf{X}} \leq 17. \end{cases}$$

This function  $\varphi$  attains values in  $[0, 1]$  and then it is a critical function determining a genuine test.  $\square$

**Remark 2.3.2.** A test  $\gamma$  and the corresponding critical function determine each other, and they will be identified in the subsequent development.  $\square$

To conclude this section, it will be shown that the (unconditional) probability of rejecting a hypothesis  $\mathcal{H}$  when using a test  $\gamma$ , can be evaluated by taking the expectation of the corresponding critical function.

**Lemma 2.3.1.** Given a statistical model  $\mathbf{X} \sim P_\theta$ ,  $\theta \in \Theta$ , consider a hypothesis  $\mathcal{H} : \theta \in \Theta_0$  and let  $\gamma$  be a test with corresponding critical function  $\varphi$ , so that

$$P[\gamma(\mathbf{X}) = \text{Reject } \mathcal{H} | \mathbf{X}] = \varphi(\mathbf{X}).$$

In this case, for each  $\theta \in \Theta$

$$P_\theta[\gamma(\mathbf{X}) = \text{Reject } \mathcal{H}] = E_\theta[\varphi(\mathbf{X})].$$

The proof of this result can be seen in Ruiz Moreno (2013).

## 2.4. Incorrect Decisions

To begin with, consider a hypothesis

$$\mathcal{H} : \theta \in \Theta_0$$

and its complement

$$\mathcal{K} : \theta \in \Theta \setminus \Theta_0.$$

Recall now that after observing the vector  $\mathbf{X}$  a test  $\gamma$  attains two possible values, namely, ‘Reject  $\mathcal{H}$ ’, and ‘Accept  $\mathcal{H}$ ’, and let  $\varphi$  be the critical function associated to  $\gamma$ .

- The decision  $\gamma(\mathbf{X}) = \text{‘Reject } \mathcal{H}\text{’}$  is an error when  $\theta \in \Theta_0$ , and the probability of incurring in this error is  $E_\theta[\varphi(\mathbf{X})]$ , by Lemma 2.3.1. The largest probability of rejecting  $\mathcal{H}$  incorrectly is

$$\mathcal{E}_\gamma[\mathcal{H}] = \max_{\theta_0 \in \Theta_0} E_{\theta_0}[\varphi(\mathbf{X})] \quad (2.4.1)$$

- The decision  $\gamma(\mathbf{X}) = \text{‘Accept } \mathcal{H}\text{’}$ —which is equivalent to ‘Reject  $\mathcal{K}$ ’—is incorrect when  $\theta \in \Theta \setminus \Theta_0$ . By Lemma 2.3.1 the probability of accepting  $\mathcal{H}$  is  $1 - E_\theta[\varphi(\mathbf{X})] = E_\theta[1 - \varphi(\mathbf{X})]$ , so that the largest probability of rejecting  $\mathcal{K}$  incorrectly is

$$\mathcal{E}_\gamma[\mathcal{K}] = \max_{\theta_1 \in \Theta \setminus \Theta_0} E_{\theta_1}[1 - \varphi(\mathbf{X})] \quad (2.4.2)$$

In the remainder of the section a lower bound for the sum  $\mathcal{E}_\gamma[\mathcal{H}] + \mathcal{E}_\gamma[\mathcal{K}]$  will be determined. The starting point is the following idea.

**Definition 2.4.1.** Consider a statistical model  $\mathbf{X} \sim P_\theta$ ,  $\theta \in \Theta$  where the observation vector  $\mathbf{X}$  has dimension  $n$ , and let  $\mathcal{H}$  and  $\mathcal{K}$  be the complementary hypothesis given by

$$\mathcal{H}: \theta \in \Theta_0, \quad \mathcal{K}: \theta \in \Theta \setminus \Theta_0,$$

where  $\Theta_0$  is a subset of  $\Theta$ . The number  $\ell(\mathcal{H}, \mathcal{K})$  corresponding to the pair of hypothesis  $\mathcal{H}$  and  $\mathcal{K}$  is defined as follows:

- (i) If  $P_\theta$  is a continuous distribution with density  $f(\mathbf{x}; \theta)$  for each  $\theta \in \Theta$

$$\ell(\mathcal{H}, \mathcal{K}) := \max_{\theta_0 \in \Theta_0, \theta_1 \in \Theta \setminus \Theta_0} \int_{\mathbb{R}^n} \min\{f(\mathbf{x}; \theta_0), f(\mathbf{x}; \theta_1)\} d\mathbf{x},$$

whereas

- (ii) If  $P_\theta$  is a discrete with probability function  $f(\mathbf{x}; \theta)$  for each  $\theta \in \Theta$

$$\ell(\mathcal{H}, \mathcal{K}) := \max_{\theta_0 \in \Theta_0, \theta_1 \in \Theta \setminus \Theta_0} \sum_{\mathbf{x} \in \mathbb{R}^n} \min\{f(\mathbf{x}; \theta_0), f(\mathbf{x}; \theta_1)\}.$$

The following result was established in Ruiz Moreno (2013).

**Theorem 2.4.1.** In the context of Definition 2.4.1, for any test  $\gamma$  the largest probabilities  $\mathcal{E}_\gamma[\mathcal{H}]$  and  $\mathcal{E}_\gamma[\mathcal{K}]$  of an incorrect rejection of  $\mathcal{H}$  and  $\mathcal{K}$ , respectively, satisfy that

$$\mathcal{E}_\gamma[\mathcal{H}] + \mathcal{E}_\gamma[\mathcal{K}] \geq \ell(\mathcal{H}, \mathcal{K}).$$

As it is shown below, in general  $\ell(\mathcal{H}, \mathcal{K})$  is a positive number.

**Lemma 2.4.1.** In the context of Definition 2.4.1 the following assertions (i) and (ii) hold.

(i) Suppose that  $P_\theta$  is a continuous distribution with density  $f(\mathbf{x}; \theta)$ , and that there exist parameters  $\theta_0 \in \Theta_0$  and  $\theta_1 \in \Theta \setminus \Theta_0$  as well as a point  $\mathbf{x} \in \mathbb{R}^n$  such that

$$\begin{aligned} &\text{The densities } f(\cdot; \theta_0) \text{ and } f(\cdot; \theta_1) \text{ are continuous at } \mathbf{x}, \text{ and} \\ &f(\mathbf{x}; \theta_0) > 0 \quad \text{and} \quad f(\mathbf{x}; \theta_1) > 0. \end{aligned} \tag{2.4.3}$$

In this case,  $\ell(\mathcal{H}, \mathcal{K}) > 0$ .

(ii) Suppose that  $P_\theta$  is a discrete distribution with probability function  $f(\mathbf{x}; \theta)$ , and that for some parameters  $\theta_0 \in \Theta_0$  and  $\theta_1 \in \Theta \setminus \Theta_0$  and a point  $\mathbf{x} \in \mathbb{R}^n$

$$f(\mathbf{x}; \theta_0) > 0 \quad \text{and} \quad f(\mathbf{x}; \theta_1) > 0.$$

In this framework,

$$\ell(\mathcal{H}, \mathcal{K}) > 0.$$

On the other hand,

(iii) The relation

$$\ell(\mathcal{H}, \mathcal{K}) \leq 1,$$

is always valid.

For a proof see Ruiz Moreno (2013).

**Remark 2.4.1.** The essential condition in Lemma 2.4.1 is that the supports of some distributions  $P_{\theta_0}$  and  $P_{\theta_1}$  with  $\theta_0 \in \Theta_0$  and  $\theta_1 \in \Theta \setminus \Theta_0$  have nonempty intersection. This requirement is very weak and is practically satisfied in *all* models considered in applications. Thus, the conclusion of Lemma 2.4.1 allows to establish the following assertion:

Regardless of the test  $\gamma$  being used to decide which of the complementary hypothesis  $\mathcal{H}$  and  $\mathcal{K}$  holds, *in practically all interesting applications the largest error probabilities  $\mathcal{E}_\gamma[\mathcal{H}]$  and  $\mathcal{E}_\gamma[\mathcal{K}]$  satisfy the inequality*

$$\mathcal{E}_\gamma[\mathcal{H}] + \mathcal{E}_\gamma[\mathcal{K}] \geq \ell(\mathcal{H}, \mathcal{K}) > 0.$$

This inequality shows that, given an observation vector  $\mathbf{X}$ , the maximum error probabilities  $\mathcal{E}_\gamma[\mathcal{H}]$  and  $\mathcal{E}_\gamma[\mathcal{K}]$  can not be made *simultaneously* ‘small’.  $\square$

The following result is a refinement of the previous lemma, and provides conditions under which the number  $\ell(\mathcal{H}, \mathcal{K})$  is equal to 1.

**Lemma 2.4.2.** In the context of Definition 2.4.1, let  $f(\mathbf{x}; \theta)$  be the density or probability function corresponding to  $P_\theta$ , and suppose that there exists  $\theta^* \in \Theta$  satisfying that

- (i)  $\lim_{\theta \rightarrow \theta^*} \int_{\mathbb{R}^n} |f(\mathbf{x}; \theta) - f(\mathbf{x}; \theta^*)| d\mathbf{x} = 0$  if  $P_\theta$  is a continuous continuous, or  
 $\lim_{\theta \rightarrow \theta^*} \sum_{x \in \mathbb{R}^n} |f(\mathbf{x}; \theta) - f(\mathbf{x}; \theta^*)| = 0$  if the distribution  $P_\theta$  is discrete.
- (ii) There exist sequences  $\{\theta_{0,n}\} \subset \Theta_0$  and  $\{\theta_{1,n}\} \subset \Theta \setminus \Theta_0$  such that

$$\lim_{n \rightarrow \infty} \theta_{0,n} = \theta^* = \lim_{n \rightarrow \infty} \theta_{1,n}$$

In this case,  $\ell(\mathcal{H}, \mathcal{K}) = 1$ .

A proof of this lemma can be found in Ruiz Moreno (2013)

**Remark 2.4.2.** Assume that each distribution  $P_\theta$  is continuous, and that the  $\{P_\theta\}_{\theta \in \Theta}$  is a location-scale family, that is,  $P_\theta$  is the distribution of  $A\mathbf{Z} + \mu$  where  $\mathbf{Z}$  has a fixed (known) continuous distribution, whereas  $A$  is an invertible matrix and  $\mu$  is a vector. In this case, condition (i) in Lemma 2.4.2 holds; this fact can be verified by using the following analytical results: If  $g(\cdot)$  is an integrable function, then

$$\int_{\mathbb{R}^n} |g(\mathbf{x} + \mu) - g(\mathbf{x})| d\mathbf{x} \rightarrow 0 \quad \text{as } \mu \rightarrow 0,$$

and

$$\int_{\mathbb{R}^n} |g(A\mathbf{x}) - g(\mathbf{x})| d\mathbf{x} \rightarrow 0 \quad \text{as } A \rightarrow I,$$

where  $I$  is the identity matrix. On the other hand, the second condition in Lemma 2.4.2 is satisfied when the sets  $\Theta_0$  and its complement  $\Theta \setminus \Theta_0$  share a common boundary point. For instance, suppose that  $\Theta_0 = [0, 4]$  and  $\Theta \setminus \Theta_0 = (4, \infty)$ . In this case  $\theta^* = 4$  can be approximated using points in  $\Theta_0$  and points in  $\Theta \setminus \Theta_0$ . In discrete models, the two above displayed relations can be verified using the dominated convergence theorem, or Weierstrass  $M$ -test for the convergence of series. In short, in common applications the conditions in Lemma 2.4.2 are valid, so that  $\ell(\mathcal{H}, \mathcal{K}) = 1$ , and then  $\mathcal{E}_\gamma[\mathcal{H}] + \mathcal{E}_\gamma[\mathcal{K}] \geq 1$ .  $\square$

## 2.5. Null Hypothesis

When a test  $\gamma$  is used to decide which of the complementary hypothesis  $\mathcal{H}$  or  $\mathcal{K}$  occurs, the objective of the analyst is to select the correct hypothesis. However, the results in the previous section showed that, regardless of the test  $\gamma$ , the largest probabilities of rejecting incorrectly  $\mathcal{H}$  or  $\mathcal{K}$ —which are given by  $\mathcal{E}_\gamma[\mathcal{H}]$  and  $\mathcal{E}_\gamma[\mathcal{K}]$ , respectively—can not be made arbitrarily small *simultaneously*. The theory handles this problem by choosing the

hypothesis whose incorrect rejection is ‘more serious’, and selecting a test that makes the probability of that serious error ‘small’, while trying to keep the probability of the other error as small as possible.

**Definition 2.5.1.** Given two complementary hypothesis  $\mathcal{H}$  and  $\mathcal{K}$ ,

- (i) The *null hypothesis* is the one whose incorrect rejection represents the more serious error; the null hypothesis is denoted by  $\mathcal{H}_0$ .
- (ii) The hypothesis that is complementary to  $\mathcal{H}_0$  is referred to as the *alternative hypothesis* and is denoted by  $\mathcal{H}_1$ .

**Example 2.5.1.** A disease is prevented by a vaccine in 95% of the cases. A new vaccine has been produced and it is claimed that it is effective in at least 98% of the cases, an assertion that must be verified by the Health Department before proceeding to massive application of the new formula. The following hypothesis are considered:

$$\mathcal{H}: \theta \in [0.98, 1], \quad \text{and} \quad \mathcal{K}: \theta \in [0, 0.98),$$

where  $\theta \in \Theta = [0, 1]$  is the proportion of cases in which the new vaccine is effective. When using a test, two possible errors are possible:

- $\mathcal{H}$  is rejected when  $\mathcal{H}$  is true.

In this case the new vaccine is effective in 98% or more of the cases, but the test fails in detecting the improvement with respect to the vaccine that is currently in use. Thus, the Health Department keeps on using the old vaccine, missing the opportunity to obtain at least 3% more protection.

- $\mathcal{K}$  is rejected when  $\mathcal{K}$  is true.

In this case the new vaccine is effective in less than 98% of the cases—in particular, it may be effective in less than 95% of the cases—but according to the test it is declared that it is 3% or more effective than the vaccine presently used. Thus, the Health Department eagerly recommends the massive application of the new vaccine, but this decision may diminish the protection of the population against the disease.

In short:

- If  $\mathcal{H}$  is incorrectly rejected, an improvement of 3% in the protection rate is missed;
- If  $\mathcal{K}$  is incorrectly rejected, the protection of the population against the disease may decrease below the present level.

Between these errors, the second one (rejecting  $\mathcal{K}$  incorrectly) seems to have the most serious consequences, and then the null hypothesis is  $\mathcal{K}$ , that is,

$$\mathcal{H}_0: \theta \in [0, 0.98)$$

and the alternative hypothesis is  $\mathcal{H}_1: \theta \in [0.98, 1]$ .  $\square$

After selecting the null and alternative hypothesis, the performance of a test is measured by the power function, an idea that is now introduced.

**Definition 2.5.2.** Let  $\mathbf{X} \sim P_\theta$ ,  $\theta \in \Theta$  be a statistical model and consider a null hypothesis

$$\mathcal{H}_0: \theta \in \Theta_0$$

as well as the corresponding alternative hypothesis.

$$\mathcal{H}_1: \theta \in \Theta \setminus \Theta_0.$$

Let  $\gamma$  be a given test.

(i) The *power function* of the test  $\gamma$  is denoted by  $\pi_\gamma$  and is defined by

$$\pi_\gamma(\theta) = P_\theta[\gamma(\mathbf{X}) = \text{Reject } \mathcal{H}_0], \quad \theta \in \Theta.$$

(ii) An *error of type I* occurs if  $\mathcal{H}_0$  is rejected when  $\mathcal{H}_0$  is true and, when  $\theta \in \Theta_0$ , the probability of incurring in such an error is denoted by  $\alpha_\gamma(\theta)$ , that is,

$$\alpha_\gamma(\theta) = P_\theta[\gamma(\mathbf{X}) = \text{Reject } \mathcal{H}], \quad \theta \in \Theta_0.$$

(iii) An *error of type II* occurs if  $\mathcal{H}_1$  is rejected when  $\mathcal{H}_1$  holds—equivalently, if  $\mathcal{H}_0$  is accepted when  $\mathcal{H}_0$  is false—and, for each  $\theta \in \Theta \setminus \Theta_0$ , the probability of incurring in an error of type II is denoted by  $\beta_\gamma(\theta)$ , *i.e.*,

$$\beta_\gamma(\theta) = P_\theta[\gamma(\mathbf{X}) = \text{Accept } \mathcal{H}], \quad \theta \in \Theta \setminus \Theta_0;$$

equivalently,

$$\beta_\gamma(\theta) = 1 - \pi_\gamma(\theta), \quad \theta \in \Theta \setminus \Theta_0; \tag{2.5.1}$$

(iv) The power of the test  $\gamma$  against the alternative value  $\theta \in \Theta \setminus \Theta_0$  is

$$\pi_\gamma(\theta) = 1 - \beta_\gamma(\theta), \quad \theta \in \Theta \setminus \Theta_0. \tag{2.5.2}$$

(v) The *size of the test*  $\gamma$  is denoted by  $\alpha^\gamma$  and is defined by

$$\alpha^\gamma = \max_{\theta \in \Theta_0} \alpha_\gamma(\theta) = \max_{\theta \in \Theta_0} P_\theta[\gamma(\mathbf{X}) = \text{Reject } \mathcal{H}_0]. \tag{2.5.3}$$

The size of a test measures the risk of incurring in an error of type I—the most serious error—and the first objective of the analyst is to use a test that has a ‘small’ size, say less

than or equal to a specified number  $\alpha \in (0, 1)$ . After this property is granted, the next goal is to have a probability of incurring in an error of type II as small as possible. A test that satisfies these properties is formally described below:

**Definition 2.5.3.** Consider the null hypothesis  $\mathcal{H}_0: \theta \in \Theta_0$  and the corresponding alternative  $\mathcal{H}_1: \theta \in \Theta \setminus \Theta_0$ . A test  $\gamma$  is *uniformly most powerful* of size (less than or equal to)  $\alpha$  if the following conditions (i) and (ii) hold:

(i) The size of  $\gamma$  does not exceed  $\alpha$ , that is,

$$\alpha^\gamma = \max_{\theta \in \Theta_0} \pi_\gamma(\theta) \leq \alpha;$$

(ii) If  $\tilde{\gamma}$  is an arbitrary test with size less than or equal to  $\alpha$ , then the probability of incurring in an error of type II is smaller under  $\gamma$  than under  $\tilde{\gamma}$ :

$$\beta_\gamma(\theta) \leq \beta_{\tilde{\gamma}}(\theta), \quad \theta \in \Theta \setminus \Theta_0,$$

that is,

$$\pi_\gamma(\theta) \geq \pi_{\tilde{\gamma}}(\theta), \quad \theta \in \Theta \setminus \Theta_0;$$

see (2.5.2).

The construction of uniformly most powerful tests will be illustrated in the following sections.

**Remark 2.5.1.** When a test  $\gamma$  is used to test the hypothesis  $\mathcal{H}_0$  versus  $\mathcal{H}_1$ , the probability of an error of type I is less than or equal to the size  $\alpha^\gamma$ , that is, rejecting  $\mathcal{H}_0$  when it is true has a probability at most  $\alpha^\gamma$ . Thus, when the null hypothesis is rejected by a test  $\gamma$  with a small size, then the analyst will be confident that the rejection is correct. This comments signals a useful rule to select which of two complementary conditions on the parameter should be selected as the null hypothesis: If it is desired to declare confidently that a condition  $\mathcal{C}$  on the parameter holds, select the null hypothesis as the opposite of the condition  $\mathcal{C}$ :

$$\mathcal{H}_0: \text{Condition } \mathcal{C} \text{ does not occur.}$$

With this selection, once  $\mathcal{H}_0$  is rejected by a test with ‘small’ size, the alternative  $\mathcal{H}_1$ —which asserts that Condition  $\mathcal{C}$  occurs—will be established on ‘firm’ grounds.  $\square$

## 2.6. Examples

In this section the diverse concepts introduced above will be illustrated.

**Exercise 2.6.1.** An urn contains 10 balls, of which  $\theta$  balls are blue (the rest being red and white). To test the null hypothesis  $\mathcal{H}_0: \theta = 3$  versus  $\mathcal{H}_1: \theta = 4$ , a sample of size 3 balls is taken and the color of the balls in the sample is recorded. The test  $\gamma$  used in this problem rejects  $\mathcal{H}_0$  if all three balls drawn are blue. Compute the probabilities  $\alpha$  and  $\beta$  of incurring in an error of type I and II, respectively, if

(i) Sampling is done without replacement.

(ii) Sampling is done with replacement.

**Solution.** Let  $X$  be the number of blue balls contained in the sample of size 3.

(i) When the sampling is without replacement,  $X$  has *Hipergeometric*  $(10, \theta, 3)$  distribution, where  $\theta \in \Theta = \{3, 4\}$ , that is,

$$P_{\theta}[X = x] = \frac{\binom{\theta}{x} \binom{10 - \theta}{3 - x}}{\binom{10}{3}}.$$

The power function  $\pi$  corresponding to  $\gamma$  is given by

$$\begin{aligned} \pi(\theta) &= P_{\theta}[\gamma(X) = \text{'Reject } \mathcal{H}_0\text{'}] \\ &= P_{\theta}[X = 3] \\ &= \frac{\binom{\theta}{3} \binom{10 - \theta}{3 - 3}}{\binom{10}{3}} = \frac{\binom{\theta}{3}}{\binom{10}{3}} = \frac{\theta(\theta - 1)(\theta - 2)}{10(9)(8)}, \quad \theta \in \{3, 4\} \end{aligned}$$

Therefore,

$$\alpha = \pi(3) = \frac{1}{120}, \quad \text{and} \quad \beta = 1 - \pi(4) = 1 - \frac{1}{30} = \frac{29}{30}.$$

(ii) Under sampling with replacement,  $X$  has *Binomial*  $\left(3, \frac{\theta}{10}\right)$  distribution, where  $\theta \in \Theta = \{3, 4\}$ , that is,

$$P_{\theta}[X = x] = \binom{3}{x} \left(\frac{\theta}{10}\right)^x \left(1 - \frac{\theta}{10}\right)^{3-x}.$$

The power function  $\pi$  corresponding to  $\gamma$  is given by

$$\begin{aligned} \pi(\theta) &= P_{\theta}[\gamma(X) = \text{'Reject } \mathcal{H}_0\text{'}] \\ &= P_{\theta}[X = 3] \\ &= \binom{3}{3} \left(\frac{\theta}{10}\right)^3 \left(1 - \frac{\theta}{10}\right)^{3-3} = \frac{\theta^3}{1000}, \quad \theta \in \{3, 4\}. \end{aligned}$$

so that  $\alpha = \pi(3) = 27/1000$  and  $\beta = 1 - \pi(4) = 1 - 64/1000 = 936/1000$ .  $\square$

**Exercise 2.6.2.** The manufacturer of an imported automobile claims that the average miles per gallon (mpg) of this type of car is at least 30. Suppose that the mpg of a randomly selected car is a normally distributed random variable with mean  $\mu$  and variance  $\sigma^2 = 25$ . To check the claim, consider the testing problem:

$$\mathcal{H}_0: \mu < 30 \quad \text{versus} \quad \mathcal{H}_1: \mu \geq 30.$$

A sample of 36 cars of the manufacturer's output is taken and the the average mpg  $\bar{\mathbf{X}}$  for the sampled cars is determined. Suppose it is decided to reject  $\mathcal{H}_0$  if, and only if,  $\bar{\mathbf{X}} \geq 32$ .

- (i) Compute the size of the critical region (*i.e.*,  $\alpha$ ).
- (ii) Compute the power  $\pi(\mu)$  of the test against each alternative value  $\mu \geq 30$ , and then find  $\beta(\mu)$ , the probability of an error of type II.

**Solution.** Since  $\bar{\mathbf{X}}$  is the average of 36 independent and normally distributed random variables with mean  $\mu$  and variance  $\sigma^2 = 25$ , it follows that  $\bar{\mathbf{X}} \sim \mathcal{N}(\mu, 25/36)$ . On the other hand, the test rejects  $\mathcal{H}_0$  when  $\bar{\mathbf{X}} \geq 32$ , and then the power function is given by

$$\pi(\mu) = P_\mu[\bar{\mathbf{X}} \geq 32] = P_\mu \left[ \frac{\bar{\mathbf{X}} - \mu}{5/6} \geq \frac{32 - \mu}{5/6} \right] = P \left[ Z \geq \frac{32 - \mu}{5/6} \right],$$

where  $Z$  is a random variable with the standard normal distribution. Thus,

$$\pi(\mu) = 1 - \Phi \left( \frac{32 - \mu}{5/6} \right) \quad \text{for every } \mu \tag{2.6.1}$$

where, as usual,  $\Phi$  is the cumulative distribution function of the standard normal distribution; notice that  $\pi(\cdot)$  is an *increasing* function.

- (i) The null hypothesis is rejected when  $\bar{\mathbf{X}} \geq 32$ . Thus, the *rejection or critical region* is  $\mathcal{R} = \{\mathbf{x} \mid \bar{\mathbf{x}} \in [32, \infty)\}$ . Observing that the expressions 'size of the critical region' and 'size of the test' are synonymous, it follows that

$$\alpha = \max_{\mu < 30} \pi(\mu) = \max_{\mu < 30} \left[ 1 - \Phi \left( \frac{32 - \mu}{5/6} \right) \right] = 1 - \Phi \left( \frac{32 - 30}{5/6} \right) = 1 - \Phi(2.4)$$

- (ii) Combining (2.5.1) and (2.6.1), it follows that the probability of an error of type II at each alternative parameter  $\mu$  is given by

$$\beta(\mu) = \Phi \left( \frac{32 - \mu}{5/6} \right), \quad \mu \geq 30;$$

notice that  $\beta(\mu)$  is decreasing, and then the largest value of  $\beta(\mu)$  is attained at  $\mu = 30$ :  $\beta(30) = \Phi(2.4)$ . It follows that the sum of the largest probability of an error of type I—the size of the test, which is given by  $1 - \Phi(2.4)$ —and the largest possible probability of an error of type II is equal to 1, as it is typical in most interesting testing problems, where the

sets specified by the null and alternative hypothesis share a boundary point; in the present context such a point is  $\mu = 30$ .  $\square$

**Exercise 2.6.3.** It is desired to test  $\mathcal{H}_0: \mu \leq 10$  versus  $\mathcal{H}_1: \mu > 10$  on the basis of a random sample  $\mathbf{X}$  of size 25 from a normal population with unknown mean  $\mu$  and variance  $\sigma^2 = 4$ . If the (largest) probability of an error of type I is to be  $\alpha = 0.25$  and the test is determined by the critical function  $\varphi(\mathbf{X}) = 1$  if  $\bar{\mathbf{X}} > c$  and  $\varphi(\mathbf{X}) = 0$  otherwise,

- (i) Find  $c$  (and hence the critical region), and
- (ii) Find  $\beta(\mu)$ .

**Solution.** The sample mean  $\bar{\mathbf{X}}$  has the normal distribution  $\mathcal{N}(\mu, 4/25)$ . The power function of the test is

$$\begin{aligned} \pi(\mu) &= E_\mu[\varphi(\mathbf{X})] \\ &= P_\mu[\bar{\mathbf{X}} > c] \\ &= P_\mu \left[ \frac{\bar{\mathbf{X}} - \mu}{\sqrt{4/25}} > \frac{c - \mu}{\sqrt{4/25}} \right] \\ &= P \left[ Z > \frac{5}{2}(c - \mu) \right] = 1 - \Phi \left( \frac{5}{2}(c - \mu) \right), \quad \mu \in \mathbb{R}. \end{aligned}$$

(i) Observe that (regardless of the value of  $c$ ) the power function is an increasing function of  $\mu$ . Since the null hypothesis states that  $\mu \leq 10$ , the size of the test is

$$\alpha = \max_{\mu \leq 10} \pi(\mu) = \max_{\mu \leq 10} \left[ 1 - \Phi \left( \frac{5}{2}(c - \mu) \right) \right] = 1 - \Phi \left( \frac{5}{2}(c - 10) \right).$$

Therefore, the condition  $\alpha = 0.025$  leads to

$$1 - \Phi \left( \frac{5}{2}(c - 10) \right) = 0.025, \quad \text{i.e.,} \quad \Phi \left( \frac{5}{2}(c - 10) \right) = 0.975.$$

It follows that

$$\frac{5}{2}(c - 10) = \Phi^{-1}(0.975) = 1.96,$$

and then  $c = 10 + 3.92/5 = 10.7805$ . This specifies completely the power function:

$$\pi(\mu) = 1 - \Phi \left( \frac{5}{2}(10.7805 - \mu) \right), \quad \mu \in \mathbb{R}.$$

(ii) The probability of an error of type II is

$$\beta(\mu) = 1 - \pi(\mu) = \Phi \left( \frac{5}{2}(10.7805 - \mu) \right)$$

for each  $\mu \in (10, \infty)$ . □

**Exercise 2.6.4.** It is desired to test  $\mathcal{H}_0: p = .2$  versus  $\mathcal{H}_1: p = .4$  for a binomial distribution with  $n = 10$ . For the test  $\gamma$  with critical function  $\varphi(X) = 1$  if  $X \leq 3$  (and  $= 0$  otherwise), find  $\alpha$  and  $\beta$ . Can you find a better test (*i.e.*, with improved probabilities of type I and II errors) with the same  $n = 10$ ?

**Solution.** The power function of  $\gamma$  is

$$\pi_\gamma(p) = P_p[X \leq 3] = (1-p)^{10} + 10(1-p)^9 p + 45(1-p)^8 p^2 + 120(1-p)^7 p^3.$$

Therefore,

$$\alpha = \pi_\gamma(.2) = 0.8791 \quad \text{and} \quad \beta = 1 - \pi_\gamma(.4) = 1 - 0.3823 = 0.6177.$$

Notice that  $\gamma$  rejects  $\mathcal{H}_0$  when  $X \leq 3$ . Intuitively, it is more reasonable to reject  $H_0$  when  $X$  is ‘large’. Consider now the test  $\tilde{\gamma}$  with critical function  $\tilde{\varphi}(X) = 1$  if  $X \geq 4$  and zero otherwise; notice that  $\tilde{\varphi} = 1 - \varphi$ , so that

$$\pi_{\tilde{\gamma}}(p) = 1 - \pi_\gamma(p),$$

and then

$$\tilde{\alpha} = \pi_{\tilde{\gamma}}(.2) = 0.1209 \quad \text{and} \quad \tilde{\beta} = 1 - \pi_{\tilde{\gamma}}(.4) = 1 - 0.6177 = 0.3823;$$

since  $\tilde{\alpha} < \alpha$  and  $\tilde{\beta} < \beta$ , the test  $\tilde{\gamma}$  is better than  $\gamma$ . □

**Exercise 2.6.5.** Let  $\mathbf{X} = (X_1, X_2, X_3)$  be a sample of the *Exponential*( $\lambda$ ) distribution, where  $\lambda \in \{1/2, 1/3\}$ . Consider testing  $\mathcal{H}_0: \lambda = 1/2$  versus  $\mathcal{H}_1: \lambda = 1/3$ , and let  $\gamma$  be the test with critical function

$$\varphi(\mathbf{x}) = 1 \quad \text{if} \quad \frac{\prod_{i=1}^3 f(x_i; 1/3)}{\prod_{i=1}^3 f(x_i; 1/2)} \geq 1$$

(and  $\varphi(\mathbf{x}) = 0$  otherwise), where  $f(x; \lambda) = \lambda e^{-\lambda x} I_{[0, \infty)}(x)$  is the exponential density with parameter  $\lambda$ . Find  $\alpha$  and  $\beta$  for this test.

**Solution.** Notice that

$$\frac{\prod_{i=1}^3 f(x_i; 1/3)}{\prod_{i=1}^3 f(x_i; 1/2)} = \frac{(1/3)^3 e^{-(x_1+x_2+x_3)/3}}{(1/2)^3 e^{-(x_1+x_2+x_3)/2}} = \frac{8}{27} e^{(x_1+x_2+x_3)/6}.$$

Therefore, the critical function  $\varphi$  can be explicitly written as

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } x_1 + x_2 + x_3 \geq 6 \log(27/8) \\ 0, & \text{otherwise,} \end{cases}$$

and the corresponding critical function  $\pi$  is given by

$$\pi(\lambda) = P_\lambda[X_1 + X_2 + X_3 \geq 6 \log(27/8)].$$

To compute the above probability, notice that

- If  $Y \sim \text{Exponential}(\lambda)$ , then  $2\lambda Y \sim \text{Exponential}(1/2) = \Gamma(1, 1/2) = \chi_2^2$ .

Since  $X_1, X_2, X_3$  are independent with the  $\text{Exponential}(\lambda)$  distribution, it follows that  $2\lambda X_1, 2\lambda X_2, 2\lambda X_3$  is a sample of the  $\chi_2^2$  distribution, and then

$$2\lambda X_1 + 2\lambda X_2 + 2\lambda X_3 \sim \chi_6^2.$$

Consequently,

$$\pi(\lambda) = P_\lambda[2\lambda X_1 + 2\lambda X_2 + 2\lambda X_3 \geq 12\lambda \log(27/8)] = P[W \geq 12\lambda \log(27/8)],$$

where

$$W \sim \chi_6^2.$$

Therefore,

$$\alpha = \pi(1/2) = P[W \geq 6 \log(27/8)] = 0.2941,$$

and

$$\beta = 1 - \pi(1/3) = 1 - P[W \geq 4 \log(27/8)] = 1 - 0.5612 = 0.4388 .$$

Notice that  $\alpha + \beta < 1$ , a relation that can be traced back to the fact that the null subset  $\{1/2\}$  and the alternative subset  $\{1/3\}$  do not share a boundary point.  $\square$

# Chapter 3

## Neyman-Pearson Theory

Throughout this chapter a statistical model  $\mathbf{X} \sim P_\theta$  is considered, where the parameter space consists of two points  $\theta_0$  and  $\theta_1$ , *i.e.*,  $\Theta = \{\theta_0, \theta_1\}$ , and the problem of testing the hypothesis  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$  will be considered. A most powerful test for this problem will be constructed and it will be proved that such a test is strictly unbiased.

### 3.1. Likelihood Ratio Tests

Consider the problem of testing the following simple null and alternative hypothesis:

$$\mathcal{H}_0: \theta = \theta_0, \quad \mathcal{H}_1: \theta = \theta_1. \quad (3.1.1)$$

It is supposed that *both distributions*  $P_{\theta_0}$  and  $P_{\theta_1}$  are (i) *continuous* or (ii) *discrete*, and  $f(\mathbf{x}; \theta_i)$  stands for the density or probability function of  $P_{\theta_i}$ ,  $i = 1, 2$ . Recall that

$f(\mathbf{x}; \theta_i)$  is the likelihood of  $\theta_i$  given  $\mathbf{X} = \mathbf{x}$ .

Hence, if  $f(\mathbf{x}; \theta_1)$  is ‘substantially’ larger than  $f(\mathbf{x}; \theta_0)$  it is natural to decide that  $\theta_1$  is the true parameter value. *i.e.*, that  $\mathcal{H}_1$  holds. A class of tests based on this idea is introduced below.

**Definition 3.1.1.** Let  $k \in [0, \infty)$  and  $\psi: \mathcal{X} \rightarrow [0, 1]$  be arbitrary but fixed. The Neyman-Pearson test for  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$  determined by  $k$  and  $\psi$  is the function  $\varphi_{k, \psi}: \mathcal{X} \rightarrow [0, 1]$  given by

$$\varphi_{k, \psi}(\mathbf{x}) \equiv \varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0) \\ 0, & \text{if } f(\mathbf{x}; \theta_1) < kf(\mathbf{x}; \theta_0) \\ \psi(\mathbf{x}), & \text{if } f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0) \end{cases} \quad (3.1.2)$$

**Remark 3.1.1.** An analyst using the test  $\varphi_{k,\psi}$  operates as follows: After observing  $\mathbf{X} = \mathbf{x}$ ,

- (i) If  $f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)$  the null hypothesis is rejected;
- (ii) If  $f(\mathbf{x}; \theta_1) < kf(\mathbf{x}; \theta_0)$  the null hypothesis is accepted;
- (iii) If  $f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)$  then a Bernoulli experiment with success probability  $\psi(\mathbf{x})$  is performed. If the outcome of the experiment is ‘success’, then the null hypothesis is rejected, and if the outcome is ‘faliure’, then  $\mathcal{H}_0$  is accepted.  $\square$

The following theorem (known as the Neyman-Pearson lemma) shows that a Neyman-Pearson test is most powerful.

**Theorem 3.1.1.** Given  $k \in [0, \infty)$  and  $\psi: \mathcal{X} \rightarrow [0, 1]$ , let  $\varphi_{k,\psi}$  be the critical function specified in (3.1.2). If  $\tilde{\varphi}$  is other critical function satisfying

$$E_{\theta_0}[\tilde{\varphi}(\mathbf{X})] \leq E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})],$$

then

$$E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] \leq E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})].$$

In words, if

$$E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] = \alpha$$

then

$$\varphi_{k,\psi} \text{ is a most powerful test of size } \alpha$$

for the testing problem (3.1.1).

**Proof.** It will be shown that

$$[\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] \geq 0. \quad (3.1.3)$$

To verify this assertion, consider the following three exhaustive cases:

(i)  $f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0) > 0$ . In this context, (3.1.2) yields that  $\varphi_{k,\psi}(\mathbf{x}) = 1$ , so that  $\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x}) = 1 - \tilde{\varphi}(\mathbf{x}) \geq 0$ , since the critical function  $\tilde{\varphi}$  takes values in  $[0, 1]$ . It follows that (3.1.3) occurs in this case.

(ii)  $f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0) < 0$ . Under this condition, (3.1.2) implies that  $\varphi_{k,\psi}(\mathbf{x}) = 0$ , and then  $\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x}) = 0 - \tilde{\varphi}(\mathbf{x}) \leq 0$  and, again, (3.1.3) follows.

(iii)  $f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0) = 0$ . In this context, the left-hand side of (3.1.3) is null.

From (3.1.3) it follows that

$$\varphi_{k,\psi}(\mathbf{x})f(\mathbf{x}; \theta_1) - \tilde{\varphi}(\mathbf{x})f(\mathbf{x}; \theta_1) \geq k[\varphi_{k,\psi}(\mathbf{x})f(\mathbf{x}; \theta_0) - \tilde{\varphi}(\mathbf{x})f(\mathbf{x}; \theta_0)];$$

taking the summation or the integral with respect to  $\mathbf{x}$  in the discrete or continuous case, respectively, it follows that

$$E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] \geq k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]]; \quad (3.1.4)$$

since  $k$  is nonnegative, this relation shows that

$$E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] \geq E_{\theta_0}[\tilde{\varphi}(\mathbf{X})] \Rightarrow E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] \geq E_{\theta_1}[\tilde{\varphi}(\mathbf{X})],$$

concluding the argument.  $\square$

### 3.2. Existence of Neyman-Pearson tests

The above theorem leads naturally to the following question: If  $\alpha \in (0, 1)$  is arbitrary, are there  $k \in [0, \infty)$  and a function  $\psi: \mathcal{X} \rightarrow [0, 1]$  such that the Neyman-Pearson test  $\varphi_{k,\psi}$  has size  $\alpha$ ? The following result shows that the answer is positive.

**Theorem 3.2.1.** Given  $\alpha \in (0, 1)$ , there exist  $k \in [0, \infty)$  and a function  $\psi: \mathcal{X} \rightarrow [0, 1]$  such that the Neyman-Pearson  $\varphi_{k,\psi}$  has size  $\alpha$ , i.e.,  $E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] = \alpha$ .

The proof of this theorem relies on the following preliminary result.

**Lemma 3.2.1.** Given  $\alpha \in (0, 1)$  there exists  $k \in (0, \infty)$  such that

$$P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}] \leq \alpha \quad (3.2.1)$$

and

$$P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq kf(\mathbf{x}; \theta_0)\}] \geq \alpha. \quad (3.2.2)$$

**Proof.** For each constant  $c$ , define

$$S_c = \{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > cf(\mathbf{x}; \theta_0)\} \quad (3.2.3)$$

and let

$$S = \{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > 0\}$$

be the support of  $f(\mathbf{x}; \theta_0)$ , so that

$$P_{\theta_0}[S] = 1. \quad (3.2.4)$$

Observe that  $S_{c_1} \subset S_c$  when  $c_1 \geq c$ , that is, the sets  $S_c$  decrease as  $c$  increases. The monotonicity and continuity properties of a probability measure imply that

$$P_{\theta_0}[S_{c_1}] \leq P_{\theta_0}[S_c] \quad \text{if } c_1 \geq c, \quad (3.2.5)$$

and

$$\lim_{c \nearrow \infty} P_{\theta_0}[S_c] = P_{\theta_0}[S^*] = P_{\theta_0}[S^* \cap S], \quad \text{where } S^* = \bigcap_{c \geq 0} S_c. \quad (3.2.6)$$

Notice now that

$$\begin{aligned} S \cap S^* &= \{\mathbf{x} \mid f(\mathbf{x}; \theta_0) > 0 \text{ and } f(\mathbf{x}; \theta_1) > cf(\mathbf{x}; \theta_0) \text{ for all } c > 0\} \\ &= \{\mathbf{x} \mid f(\mathbf{x}; \theta_0) > 0 \text{ and } f(\mathbf{x}; \theta_1) = \infty\} = \emptyset, \end{aligned}$$

where the last equality is due to the fact that a density or probability function attains only finite values. Therefore, by (3.2.6),  $P_{\theta_0}[S^* \cap S] = 0$  and then

$$\lim_{c \nearrow \infty} P_{\theta_0}[S_c] = 0. \quad (3.2.7)$$

Next, given  $\alpha \in (0, 1)$ , define

$$\mathcal{A} = \{c > 0 \mid P_{\theta_0}[S_c] \leq \alpha\} \quad (3.2.8)$$

and observe that (3.2.5) and (3.2.7) yield that  $\mathcal{A}$  is a nonempty ray pointing to the right. Let  $k$  be the origin of the ray  $\mathcal{A}$ , so that

$$(k, \infty) \subset \mathcal{A} \subset [k, \infty), \quad (3.2.9)$$

where

$$k = \inf \mathcal{A}; \quad (3.2.10)$$

consequently,

$$c > k \Rightarrow c \in \mathcal{A} \Rightarrow P_{\theta_0}[S_c] \leq \alpha. \quad (3.2.11)$$

On the other hand, the specification of the sets  $S_c$  yields that

$$S_c \cap S \nearrow S_k \cap S \quad \text{as } c \searrow k,$$

and, *via* (3.2.4), the continuity property of a probability measure leads to

$$\lim_{c \searrow k} P_{\theta_0}[S_c] = \lim_{c \searrow k} P_{\theta_0}[S_c \cap S] = P_{\theta_0}[S_k \cap S] = P_{\theta_0}[S_k].$$

Combining this fact with (3.2.11) it follows that

$$P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}] = P_{\theta_0}[S_k] \leq \alpha,$$

*i.e.*, (3.2.1) holds. Next, it will be shown that (3.2.2) occurs by analyzing the following two exhaustive cases about the value of  $k$ :

(i) If  $k = 0$ , then

$$\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq 0f(\mathbf{x}; \theta_0)\} = \{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq 0\} = \mathbb{R}^k,$$

so that (3.2.2) is equivalent to the inequality  $1 \geq \alpha$ , a relation that is true.

(ii) Suppose now that  $k$  is positive. In this case, for any sufficiently large integer  $m$  the inclusion  $k - 1/m \in (0, k)$  holds, and then  $k - 1/m \notin \mathcal{A}$ , by (3.2.9). In this case the specification of  $\mathcal{A}$  and (3.2.4) yield that

$$P_{\theta_0}[S \cap S_{k-1/m}] = P_{\theta_0}[S_{k-1/m}] \geq \alpha. \quad (3.2.12)$$

On the other hand, notice that

$$S \cap S_{k-1/m} = \{\mathbf{x} \mid f(\mathbf{x}; \theta_0) > 0, f(\mathbf{x}; \theta_1) > (k - 1/m)f(\mathbf{x}; \theta_0)\},$$

an expression that immediately implies that, as  $m \rightarrow \infty$ ,

$$\begin{aligned} S \cap S_{k-1/m} &\searrow \{\mathbf{x} \mid f(\mathbf{x}; \theta_0) > 0, f(\mathbf{x}; \theta_1) \geq kf(\mathbf{x}; \theta_0)\} \\ &= S \cap \{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq kf(\mathbf{x}; \theta_0)\} \end{aligned}$$

Using the continuity property of a probability measure, this last display and (3.2.12) lead to

$$\begin{aligned} P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq kf(\mathbf{x}; \theta_0)\}] &= P_{\theta_0}[S \cap \{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq kf(\mathbf{x}; \theta_0)\}] \\ &= \lim_{m \rightarrow \infty} P_{\theta_0}[S \cap S_{k-1/m}] \geq \alpha, \end{aligned}$$

completing the verification of (3.2.2).  $\square$

**Proof of Theorem 3.2.1.** Let  $k$  be as in Lemma 3.2.1, so that

$$P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) \geq kf(\mathbf{x}; \theta_0)\}] \geq \alpha \geq P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}],$$

and let  $\psi(\cdot) \equiv \psi$  be the constant function defined as follows:

$$\psi = \begin{cases} 1, & \text{if } P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}] = 0 \\ \frac{\alpha - P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}]}{P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}]} & \text{if } P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}] \neq 0. \end{cases} \quad (3.2.13)$$

Let  $\varphi_{k,\psi}$  be the Neyman-Pearson critical function associated to this pair  $(k, \psi)$  as in (3.1.2) and observe that

$$\begin{aligned} E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] &= P_{\theta_0}[\varphi_{k,\psi}(\mathbf{X}) = 1] + \psi P_{\theta_0}[\varphi_{k,\psi}(\mathbf{X}) = \psi] \\ &= P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}] \\ &\quad + \left( \frac{\alpha - P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}]}{P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}]} \right) P_{\theta_0}[\{\mathbf{x} \mid f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}] \\ &= \alpha, \end{aligned}$$

that is,  $\varphi_{k,\psi}$  has size  $\alpha$ , completing the proof.  $\square$

### 3.3. Construction of Neyman-Pearson Tests

The results in Theorems 3.1.1 and 3.2.1 can be summarized as follows: For the testing problem (3.1.1), given  $\alpha \in (0, 1)$ , there exists a Neyman-Pearson test with size  $\alpha$ , and such a test is most powerful. Also, the proof of Lemma 3.2.1 and Theorem 3.2.1 allow to state the following procedure to construct a most powerful test of size  $\alpha \in (0, 1)$  for the testing problem (3.1.1). Let  $\mathcal{X}$  be the set of possible values of the observation vector  $\mathbf{X}$  under the condition that  $\theta$  is  $\theta_0$  or  $\theta_1$ , that is,

$$\mathcal{X} = \{\mathbf{x} \mid f(\mathbf{x}; \theta_0) > 0 \text{ or } f(\mathbf{x}; \theta_1) > 0\}.$$

- **Step 1:** For each  $k \geq 0$ , find the region  $\mathcal{R}_k = \{\mathbf{x} \in \mathcal{X} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\}$ .
- **Step 2:** Determine the size of each region  $\mathcal{R}_k$ , which is given by  $P_{\theta_0}[\mathbf{X} \in \mathcal{R}_k]$ .
- **Step 3:** Find the region  $\mathcal{R}_{k^*}$  such that

$$P_{\theta_0}[\mathbf{X} \in \mathcal{R}_{k^*}] \leq \alpha \quad \text{and} \quad P_{\theta_0}[\mathbf{X} \in \mathcal{R}_k] \geq \alpha \quad \text{for} \quad k < k^*;$$

notice that

$$k^* \text{ is the } \textit{smallest} \text{ nonnegative number } k \text{ such that } P_{\theta_0}[\mathbf{X} \in \mathcal{R}_k] \leq \alpha, \quad (3.3.1)$$

and that, if  $\mathcal{R}_k$  is expressed in terms of a statistic with continuous distribution, in common models the region  $\mathcal{R}_{k^*}$  is determined by solving the equation

$$P_{\theta_0}[\mathbf{X} \in \mathcal{R}_{k^*}] = \alpha. \quad (3.3.2)$$

- **Step 4:** Define the constant  $\psi^*$  as in (3.2.13) with  $k^*$  instead of  $k$ , and
- **Step 5:** Finally, perform the test using the Neyman-Pearson critical function  $\varphi_{k^*,\psi^*}$  given by

$$\varphi_{k^*,\psi^*}(\mathbf{x}) = \begin{cases} 1, & \text{if } f(\mathbf{X}; \theta_1) > k^* f(\mathbf{X}; \theta_0) \\ \psi^*, & \text{if } f(\mathbf{X}; \theta_1) = k^* f(\mathbf{X}; \theta_0) \\ 0, & \text{if } f(\mathbf{X}; \theta_1) < k^* f(\mathbf{X}; \theta_0) \end{cases}$$

The application of this test leads to the following operation rule:

- ▷ Reject  $\mathcal{H}_0$  if  $f(\mathbf{X}; \theta_1) > k^* f(\mathbf{X}; \theta_0)$
- ▷ Accept  $\mathcal{H}_0$  if  $f(\mathbf{X}; \theta_1) < k^* f(\mathbf{X}; \theta_0)$
- ▷ Randomize the decision when  $f(\mathbf{X}; \theta_1) = k^* f(\mathbf{X}; \theta_0)$

▷ ▷ Reject  $\mathcal{H}_0$  with probability  $\psi^*$ ,

▷ ▷ Accept  $\mathcal{H}_0$  with probability  $1 - \psi^*$ .

(ii) When  $P_{\theta_0}[\{\mathbf{x} \in \mathcal{X} | f(\mathbf{x}; \theta_1) > k^* f(\mathbf{x}; \theta_0)\}] = 0$ , the constant  $\psi^*$  does not have any influence in the size of the test and, usually,  $\psi^*$  is set equal to 1; with this assignment the above test has critical function

$$\varphi_{k^*, \psi^*}(\mathbf{x}) = \begin{cases} 1, & \text{if } f(\mathbf{X}; \theta_1) \geq k^* f(\mathbf{X}; \theta_0) \\ 0, & \text{if } f(\mathbf{X}; \theta_1) < k^* f(\mathbf{X}; \theta_0). \end{cases}$$

This procedure to construct a most powerful test will be illustrated in the following section.

**Remark 3.3.1.** Define

$$\frac{a}{0} = \infty \quad \text{when } a > 0$$

and, as before, let  $\mathcal{X}$  be the set where at least one of the densities (or probability functions)  $f(\mathbf{x}; \theta_1)$  and  $f(\mathbf{x}; \theta_0)$  is positive. In this case, for every  $\mathbf{x} \in \mathcal{X}$ , the relation  $f(\mathbf{x}; \theta_1) > k f(\mathbf{x}; \theta_0)$  is equivalent to

$$\frac{f(\mathbf{x}; \theta_1)}{f(\mathbf{x}; \theta_0)} > k.$$

### 3.4. Examples

In this section the construction of a Neyman-Pearson test will be illustrated for some common models.

**Example 3.4.1.** Let  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be a sample of the  $\mathcal{N}(\mu, \sigma_0^2)$  distribution, where  $\sigma_0$  is a known positive number,  $\mu \in \{\mu_0, \mu_1\}$  and  $\mu_1 > \mu_0$ . Consider the the testing problem

$$\mathcal{H}_0: \mu = \mu_0 \quad \text{versus} \quad \mathcal{H}_1: \mu = \mu_1.$$

To determine the Neyman-Pearson test with level  $\alpha$ , first notice that the density of the sample vector  $\mathbf{X}$  when  $\mu$  is the parameter value is given by

$$\begin{aligned} f(\mathbf{x}; \mu) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_0^2}} e^{-(x_i - \mu)^2 / 2\sigma_0^2} \\ &= \frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-[\sum_{i=1}^n x_i^2 + n\mu^2] / (2\sigma_0^2)} e^{\mu \sum x_i / \sigma_0^2} \end{aligned}$$

Next, the desired test will be obtained by an application of the procedure in Remark 3.3.

**Step 1:** Notice that

$$\begin{aligned}
f(\mathbf{x}; \mu_1) > k f(\mathbf{x}; \mu_0) &\iff \frac{f(\mathbf{x}; \mu_1)}{f(\mathbf{x}; \mu_0)} > k \\
&\iff \frac{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-[\sum_{i=1}^n x_i^2 + n\mu_1^2]/(2\sigma_0^2)} e^{\mu_1 \sum x_i/\sigma_0^2}}{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-[\sum_{i=1}^n x_i^2 + n\mu_0^2]/(2\sigma_0^2)} e^{\mu_0 \sum x_i/\sigma_0^2}} > k \\
&\iff e^{n(\mu_0^2 - \mu_1^2)/(2\sigma_0^2)} e^{(\mu_1 - \mu_0) \sum x_i/\sigma_0^2} > k \\
&\iff e^{(\mu_1 - \mu_0) \sum_{i=1}^n x_i/\sigma_0^2} > k e^{n(\mu_1^2 - \mu_0^2)/(2\sigma_0^2)} \\
&\iff \frac{(\mu_1 - \mu_0) \sum_{i=1}^n x_i}{\sigma_0^2} > \log \left( k e^{n(\mu_1^2 - \mu_0^2)/(2\sigma_0^2)} \right)
\end{aligned}$$

and then, recalling that  $\mu_1 > \mu_0$ ,

$$f(\mathbf{x}; \mu_1) > k f(\mathbf{x}; \mu_0) \iff \bar{\mathbf{x}} = \frac{1}{n} \sum_{i=1}^n x_i > \tilde{k}$$

where

$$\tilde{k} = \frac{\sigma_0^2}{n(\mu_1 - \mu_0)} \log \left( k e^{n(\mu_1^2 - \mu_0^2)/(2\sigma_0^2)} \right).$$

Thus,  $\mathcal{R}_k = \{\mathbf{x} \mid \bar{\mathbf{x}} > \tilde{k}\}$ .

**Step 2:** The size of the critical region  $\mathcal{R}_k$  when  $\theta_0$  is the true parameter value is given by

$$P_{\theta_0}[\mathbf{X} \in \mathcal{R}_k] = P_{\theta_0}[\bar{\mathbf{X}} > \tilde{k}] = P_{\theta_0} \left[ \frac{\bar{\mathbf{X}} - \theta_0}{\sqrt{\sigma_0^2/n}} > \frac{\tilde{k} - \theta_0}{\sqrt{\sigma_0^2/n}} \right] = 1 - \Phi \left( \frac{\tilde{k} - \theta_0}{\sqrt{\sigma_0^2/n}} \right),$$

where it was used that, under  $\mathcal{H}_0$ , the standardized sample mean  $(\bar{\mathbf{X}} - \theta_0)/\sqrt{\sigma_0^2/n}$  has the standard normal distribution.

**Step 3:** The critical region  $\mathcal{R}_k$  is expressed in terms of  $\bar{\mathbf{X}}$ , whose distribution is continuous.

To find  $k^*$ —or equivalently,  $\tilde{k}$ —the following equation must be solved:

$$1 - \Phi \left( \frac{\tilde{k} - \theta_0}{\sqrt{\sigma_0^2/n}} \right) = \alpha;$$

see (3.3.2). It follows that

$$\frac{\tilde{k} - \theta_0}{\sqrt{\sigma_0^2/n}} = \Phi^{-1}(1 - \alpha) = z_{1-\alpha},$$

and then

$$\tilde{k} = \theta_0 + \frac{\sigma_0}{\sqrt{n}} z_{1-\alpha},$$

**Step 4:** Since  $P_{\theta_0}[\{\mathbf{X} \in \mathcal{X} | f(\mathbf{X}; \theta_1) = k^* f(\mathbf{x}; \theta_0)\}] = P_{\theta_0}[\bar{\mathbf{X}} = \tilde{k}] = 0$ , the constant  $\psi^*$  is set equal to 1; see Remark 3.3(ii).

**Step 5:** The most powerful test with level  $\alpha$  is determined by the following critical function:

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \bar{\mathbf{x}} \geq \theta_0 + \frac{\sigma_0}{\sqrt{n}} z_{1-\alpha} \\ 0, & \text{otherwise,} \end{cases}$$

concluding the construction. □

**Example 3.4.2.** Let  $\mathbf{X} = (X_1, X_2, X_3, X_4)$  be a sample of the *Poisson*( $\lambda$ ) distribution where  $\lambda \in \{1, 2.5\}$ . To construct a most powerful test of level  $\alpha = 0.05$  for the problem

$$\mathcal{H}_0: \lambda = 2.5 \quad \text{versus} \quad \mathcal{H}_1: \lambda = 1,$$

first notice that  $\mathbf{X}$  takes values in

$$\mathcal{X} = \{\mathbf{x} = (x_1, x_2, x_3, x_4) | x_i \text{ is a nonnegative integer}\},$$

and that for  $\mathbf{x} \in \mathcal{X}$ ,

$$f(\mathbf{x}; \lambda) = \prod_{i=1}^4 \frac{\lambda^{x_i}}{x_i!} e^{-\lambda} = \lambda^{\sum_{i=1}^4 x_i} \frac{e^{-4\lambda}}{x_1! x_2! x_3! x_4!}.$$

Therefore,

$$\frac{f(\mathbf{x}; \lambda_1)}{f(\mathbf{x}; \lambda_0)} = \frac{\lambda_1^{\sum_{i=1}^4 x_i} \frac{e^{-4\lambda_1}}{x_1! x_2! x_3! x_4!}}{\lambda_0^{\sum_{i=1}^4 x_i} \frac{e^{-4\lambda_0}}{x_1! x_2! x_3! x_4!}} = \left(\frac{\lambda_1}{\lambda_0}\right)^{\sum_{i=1}^4 x_i} e^{-4(\lambda_1 - \lambda_0)}.$$

Using this expression, the Neyman-Pearson test is constructed as follows:

**Step 1:** Since  $\lambda_1 = 1$  and  $\lambda_0 = 2.5$ , it follows that for  $\mathbf{x} \in \mathcal{X}$

$$\begin{aligned} f(\mathbf{x}; \lambda_1) > k f(\mathbf{x}; \lambda_0) &\iff \frac{f(\mathbf{x}; \lambda_1)}{f(\mathbf{x}; \lambda_0)} > k \\ &\iff \left(\frac{\lambda_1}{\lambda_0}\right)^{\sum_{i=1}^4 x_i} e^{-4(\lambda_1 - \lambda_0)} > k \\ &\iff \left(\frac{1}{2.5}\right)^{\sum_{i=1}^4 x_i} e^{-6} > k \\ &\iff (2.5)^{\sum_{i=1}^4 x_i} < \frac{1}{k e^6} \\ &\iff \log(2.5) \sum_{i=1}^4 x_i < \log\left(\frac{1}{k e^6}\right) \end{aligned}$$

and then

$$f(\mathbf{x}; \lambda_1) > kf(\mathbf{x}; \lambda_0) \iff \sum_{i=1}^4 x_i < \tilde{k} \iff \bar{\mathbf{x}} < \tilde{k}/4$$

where

$$\tilde{k} = \frac{1}{\log(2.5)} \log\left(\frac{1}{ke^6}\right).$$

Thus,  $\mathcal{R}_k = \{\mathbf{x} \in \mathcal{X} \mid f(\mathbf{x}; \lambda_1) > kf(\mathbf{x}; \lambda_0)\} = \{\mathbf{x} \in \mathcal{X} \mid \bar{\mathbf{x}} < \tilde{k}\}$ ; notice that  $\tilde{k}$  is a decreasing function of  $k$ .

**Step 2:** Under  $\mathcal{H}_0$ , the random variables  $X_i$  are independent with common *Poisson*(2.5) distribution, so that  $\sum_{i=1}^4 X_i \sim \text{Poisson}(10)$ , and then the size of the critical region  $\mathcal{R}_k$  when  $\lambda = 2.5$  is given by

$$P_{\lambda_0}[\mathbf{X} \in \mathcal{R}_k] = P_{\lambda_0}[X_1 + X_2 + X_3 + X_4 < \tilde{k}] = \sum_{0 \leq t < \tilde{k}} e^{-10} \frac{10^t}{t!}.$$

**Step 3:** If  $\tilde{k}^*$  corresponds to  $k^*$  in (3.3.1), then  $\tilde{k}^*$  is the largest value  $\tilde{k}$  such that

$$P_{\lambda_0} \left[ \sum_{i=1}^4 X_i < \tilde{k} \right] \leq 0.05,$$

since  $\tilde{k}$  is a decreasing function of  $k$ . A glance at the portion of the table corresponding to the *Poisson*(10) distribution displayed below shows that

$$P_{\lambda_0} \left[ \sum_{i=1}^4 X_i < 5 \right] = 0.0293, \quad \text{and} \quad P_{\lambda_0} \left[ \sum_{i=1}^4 X_i < 6 \right] = .0671.$$

so that  $\tilde{k}^* = 5$ .

$n$	$P[Y = n]$	$P[Y \leq n]$	$P[Y > n]$
0	0.0000	0.0000	1.0000
1	0.0005	0.0005	0.9995
2	0.0023	0.0028	0.9972
3	0.0076	0.0103	0.9897
4	0.0189	0.0293	0.9707
5	0.0378	0.0671	0.9329
6	0.0631	0.1301	0.8699
7	0.0901	0.2202	0.7798

**Step 4:** Since  $P_{\theta_0}[\{\mathbf{X} \in \mathcal{X} \mid f(\mathbf{X}; \theta_1) = k^* f(\mathbf{x}; \theta_0)\}] = P_{\theta_0}[\sum_{i=1}^4 X_i = \tilde{k}^*] = P_{\theta_0}[\sum_{i=1}^4 X_i = 5] = 0.0378$ , it follows that

$$\psi^* = \frac{.05 - P_{\lambda_0}[\bar{X} < 5]}{P_{\lambda_0}[\bar{X} = 5]} = \frac{.05 - .0293}{.0378} = .5476.$$

**Step 5:** The most powerful test with level  $\alpha = 0.5$  is determined by the following critical function:

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \bar{\mathbf{x}} < 5/4 \\ .5476, & \text{if } \bar{\mathbf{x}} = 5/4, \\ 0, & \text{if } \bar{\mathbf{x}} > 5/4. \end{cases}$$

The application of this test is as follows: If  $\bar{\mathbf{X}} < 5/4$  (respectively,  $\bar{\mathbf{X}} > 5/4$ ) is observed, then the null hypothesis is rejected (respectively, accepted), whereas if  $\bar{\mathbf{X}} = 5/4$  occurs, then a Bernoulli experiment with success probability is performed, and the null hypothesis is rejected if the outcome of the Bernoulli experiment is ‘success’, while  $\mathcal{H}_0$  is ‘accepted’ when a ‘failure’ occurs.  $\square$

In Example 3.4.1, when  $\mathcal{H}_0$  is valid, the decision maker will not use any randomized procedure to decide which of the null or the alternative hypothesis is true. On the other hand, in Example 3.4.2, the analyst will take a randomized decision when  $\bar{\mathbf{X}} = 5/4$ , an event that has probability .0378 if  $\mathcal{H}_0$  is true. In the following example, the decision maker *always* uses randomization to decide which of the null or alternative hypothesis holds.

**Example 3.4.3.** Let  $X$  be a random variable with the *Uniform*(0,  $\theta$ ) distribution, where  $\theta \in \{1, 2\}$ , and consider the problem of testing  $\mathcal{H}_0: \theta = 1$  versus  $\mathcal{H}_1: \theta = 2$ . A test with level  $\alpha = .05$  is constructed as follows:

Notice that, since the parameter space is  $\{1, 2\}$ , then  $X$  takes values in

$$\mathcal{X} = (0, 2)$$

and that for  $x \in \mathcal{X}$ ,

$$f(x; \theta) = \frac{1}{\theta} I_{(0, \theta)}(x).$$

Therefore,

$$\frac{f(x; \theta_1)}{f(x; \theta_0)} = \frac{\frac{1}{\theta_1} I_{(0, \theta_1)}(x)}{\frac{1}{\theta_0} I_{(0, \theta_0)}(x)} = \frac{\theta_0 I_{(0, \theta_1)}(x)}{\theta_1 I_{(0, \theta_0)}(x)} = \begin{cases} \infty, & \text{if } x \in [1, 2) \\ 1/2, & \text{if } x \in (0, 1) \end{cases} \quad (3.4.1)$$

where the last equality used that  $\theta_0 = 1$  and  $\theta_1 = 2$ . Using this expression, the Neyman-Pearson test is constructed as follows:

**Step 1:** Observe that for each  $x \in \mathcal{X}$  and  $k \in [0, \infty)$

$$f(x; \theta_1) > k f(x; \theta_0) \iff \frac{f(x; \theta_1)}{f(x; \theta_0)} > k$$

and then

$$\mathcal{R}_k = \{x \in \mathcal{X} \mid f(x; \theta_1) > k f(x; \theta_0)\} = \begin{cases} [1, 2), & \text{if } k \geq 1/2 \\ (0, 2), & \text{if } k \in [0, 1/2). \end{cases}$$

**Step 2:** Under  $\mathcal{H}_0$ , the random variable  $X$  has the *Uniform*(0, 1) distribution, so that the size of the region  $\mathcal{R}_k$  is given by

$$P_{\theta_0}[X \in \mathcal{R}_k] = \begin{cases} P_{\theta_0}[X \in [1, 2)] = 0, & \text{if } k > 1/2 \\ P_{\theta_0}[X \in (0, 2)] = 1, & \text{if } k \leq 1/2, \end{cases}$$

**Step 3:** According to the previous display, the minimum (infimum)  $k^*$  of all the values  $k$  such that  $P_{\theta_0}[X \in \mathcal{R}_k] \leq \alpha = 0.05$  is

$$k^* = 1/2.$$

**Step 4:** By (3.4.1),

$$\begin{aligned} P_{\theta_0}[f(X; \theta_1) = k^* f(X; \theta_0)] &= P_{\theta_0} \left[ \frac{f(X; \theta_1)}{f(X; \theta_0)} = k^* \right] \\ &= P_{\theta_0} \left[ \frac{f(X; \theta_1)}{f(X; \theta_0)} = \frac{1}{2} \right] \\ &= P_{\theta_0}[X \in (0, 1)] = 1; \end{aligned}$$

Observing that  $P_{\theta_0}[f(X; \theta_1) > k^* f(X; \theta_0)] = P_{\theta_0}\{X \in [1, 2)\} = 0$  it follows that

$$\psi^* = \frac{.05 - P_{\lambda_0}[X \in [1, 2)]}{P_{\lambda_0}[X \in (0, 1)]} = \frac{.05 - 0}{1} = .05.$$

**Step 5:** Observing that  $\{f(X; \theta_1) < k^* f(X; \theta_0)\} = \emptyset$ , the most powerful test with level  $\alpha = 0.5$  is determined by the following critical function:

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } x \in [1, 2) \\ .05, & \text{if } x = (0, 1). \end{cases}$$

Notice that under  $\mathcal{H}_0$  the variable  $X$  takes values in  $(0, 1)$  with probability 1, so that, when the null hypothesis is true, the analyst will always decide which of the null or alternative hypothesis holds using a random mechanism.  $\square$

**Remark 3.4.1.** Suppose that  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of the density

$$f(x; \theta) = \frac{1}{\beta^\alpha \Gamma(\alpha)} x^{\alpha-1} e^{-x/\beta} I_{(0, \infty)}(x).$$

which corresponds to the *Gamma*( $\alpha, \beta$ ) distribution. In this case

- (i)  $X_1 + X_2 + \dots + X_n \sim \text{Gamma}(n\alpha, \beta)$ ,
- (ii)  $(X_1 + X_2 + \dots + X_n)/\beta \sim \text{Gamma}(n\alpha, 1)$ , and
- (iii)  $2(X_1 + X_2 + \dots + X_n)/\beta \sim \text{Gamma}(n\alpha, 1/2)$ .

Also,

(iv) The  $\text{Gamma}(k/2, 1/2)$  distribution is referred to as the *chi squared distribution with  $k$  degrees of freedom*, and is denoted as  $\chi_k^2$ .  $\square$

**Example 3.4.4.** Suppose that  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of the  $\text{Gamma}(\alpha, \beta)$  distribution ( $\alpha, \beta > 0$ ), which has density

$$f(x; \alpha, \beta) = \frac{1}{\Gamma(\alpha)\beta^\alpha} x^{\alpha-1} e^{-x/\beta} I_{(0, \infty)}(x), \quad x \in \mathbb{R},$$

and assume that  $\alpha$  is a *known* positive number.

(a) For the testing problem  $\mathcal{H}_0: \beta = 1$  versus  $\mathcal{H}_1: \beta = 2$

(i) Show explicitly that the best (most powerful) test at a specified level  $a_0$  is based on the sufficient statistic  $S = X_1 + X_2 + \dots + X_n$ ,

(ii) Find a most powerful test at level  $a_0$ , and

(iii) Show directly that this test is unbiased.

(b) Repeat part (a) for  $\mathcal{H}_0: \beta = \beta_0$  versus  $\mathcal{H}_1: \beta = \beta_1$ , where  $\beta_1 > \beta_0$ , and hence generalize part (a) to find a most powerful test, and

(c) Show that if  $\varphi$  is a Neyman-Pearson test of the form

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } X_1 + X_2 + \dots + X_n > k \\ \psi, & \text{if } X_1 + X_2 + \dots + X_n = k \\ 0, & \text{otherwise,} \end{cases} \quad (3.4.2)$$

then the corresponding power function is a nondecreasing function of  $\beta$ .

**Solution.** The density  $f_{\mathbf{X}}(\mathbf{x}; \alpha, \beta)$  of  $\mathbf{X}$  is supported on the set of all  $n$ -dimensional vectors  $\mathbf{x}$  with positive components. If  $x_i > 0$  for  $i = 1, 2, \dots, n$ ,

$$\begin{aligned} f_{\mathbf{X}}(\mathbf{x}; \alpha, \beta) &= \prod_{i=1}^n \frac{1}{\Gamma(\alpha)\beta^\alpha} x_i^{\alpha-1} e^{-x_i/\beta} I_{(0, \infty)}(x_i) \\ &= \frac{1}{\Gamma(\alpha)^n} \left( \prod_{i=1}^n x_i \right)^{\alpha-1} \frac{1}{\beta^{n\alpha}} e^{-\sum_{i=1}^n x_i/\beta} \\ &= h(\mathbf{x}) \frac{1}{\beta^{n\alpha}} e^{-\sum_{i=1}^n x_i/\beta} \end{aligned} \quad (3.4.3)$$

where

$$h(\mathbf{x}) = \frac{1}{\Gamma(\alpha)^n} \left( \prod_{i=1}^n x_i \right)^{\alpha-1}.$$

(a) If  $\mathbf{x}$  has positive components,

$$\begin{aligned}
f(\mathbf{x}; \alpha, 2) > \tilde{k}f(\mathbf{x}; \alpha, 1) &\iff \frac{f(\mathbf{x}; \alpha, 2)}{f(\mathbf{x}; \alpha, 1)} > \tilde{k} \\
&\iff \frac{h(\mathbf{x}) \frac{1}{2^{n\alpha}} e^{-\sum_{i=1}^n x_i/2}}{h(\mathbf{x}) e^{-\sum_{i=1}^n x_i}} > \tilde{k} \\
&\iff e^{\sum_{i=1}^n x_i/2} > \tilde{k} 2^{n\alpha} \\
&\iff \sum_{i=1}^n x_i > 2 \log(\tilde{k} 2^{n\alpha}) \equiv k.
\end{aligned}$$

and it follows that a Neyman-Pearson can be described as

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } X_1 + X_2 + \cdots + X_n \geq k \\ 0, & \text{if } X_1 + X_2 + \cdots + X_n < k; \end{cases} \quad (3.4.4)$$

see (3.1.2). Notice that the event  $[f(\mathbf{X}; \alpha, 2) = \tilde{k}f(\mathbf{X}; \alpha, 1)] = [X_1 + X_2 + \cdots + X_n = k]$  has been incorporated to the rejection error, a choice that does not affect the size of the test, since  $X_1 + X_2 + \cdots + X_n$  has  $Gamma(n\alpha, \beta)$  distribution, which is continuous, and then the event has probability zero. The above expression shows that the Neyman-Pearson test depends only on the sufficient statistic  $S = X_1 + X_2 + \cdots + X_n$ . The power function of the test is  $\pi_\varphi(\beta) = P_\beta[X_1 + X_2 + \cdots + X_n \geq k]$ , and the level of this test for the problem  $\mathcal{H}_0: \beta = 1$  versus  $\mathcal{H}_1: \beta = 2$  is  $\pi_\varphi(1)$ . To obtain the level (size)  $a_0$ , the constant  $k$  must be selected in such a way that

$$a_0 = \pi(1) = P_1[X_1 + X_2 + \cdots + X_n > k]. \quad (3.4.5)$$

Notice that when  $\beta = 1$ ,  $S = X_1 + X_2 + \cdots + X_n \sim \Gamma(n\alpha, 1)$ , so that the density of  $S$  is given by

$$f_S(y) = \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} I_{(0, \infty)}(x).$$

Therefore, the number  $k$  in (3.4.5) must be selected as the (right-hand side) percentil  $p_{a_0}$  of size  $a_0$  for this density:

$$\int_{p_{a_0}}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} I_{(0, \infty)}(x) dx = a_0,$$

and the test of level  $a_0$  is obtained by replacing  $k$  by  $p_{a_0}$  in the above expression for the critical function  $\varphi$ ; the power function is

$$\pi(\beta) = P_\beta[X_1 + X_2 + \cdots + X_n > p_{a_0}].$$

Of course,  $\pi(1) = a_0$ , and it will be shown that  $\pi(2) > a_0$ . To achieve this goal, notice that if  $X_1, X_2, \dots, X_n$  is a sample of the  $Gamma(\alpha, \beta)$  distribution, then  $X_i/\beta$ ,  $i = 1, 2, \dots, n$

are *i.i.d.* with common distribution  $\text{Gamma}(\alpha, 1)$ , so that  $(X_1 + X_2 + \cdots + X_n)/\beta \sim \text{Gamma}(n\alpha, 1)$ , that is,

$$\frac{X_1 + X_2 + \cdots + X_n}{\beta} \quad \text{has density} \quad \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} I_{(0,\infty)}(x). \quad (3.4.6)$$

Therefore,

$$\pi(\beta) = P_\beta \left[ \frac{X_1 + X_2 + \cdots + X_n}{\beta} > \frac{p_{a_0}}{\beta} \right] = \int_{p_{a_0}/\beta}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} dx.$$

In particular,

$$\pi(2) = \int_{p_{a_0}/2}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} dx > \int_{p_{a_0}}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} dx = a_0 = \pi(1),$$

showing that the test (3.4.4) with  $k = p_{a_0}$  is unbiased for the testing problem  $\mathcal{H}_0: \beta = 1$  versus  $\mathcal{H}_1: \beta = 2$ .

(b) Consider the testing problem  $\mathcal{H}_0: \beta = \beta_0$  versus  $\mathcal{H}_1: \beta = \beta_1$ , where  $\beta_1 > \beta_0$ . Using (3.4.3), it follows that if  $\mathbf{x}$  has positive components,

$$\begin{aligned} f(\mathbf{x}; \alpha, \beta_1) > \tilde{k} f(\mathbf{x}; \alpha, \beta_0) &\iff \frac{f(\mathbf{x}; \alpha, \beta_1)}{f(\mathbf{x}; \alpha, \beta_0)} > \tilde{k} \\ &\iff \frac{h(\mathbf{x}) \frac{1}{\beta_1^{n\alpha}} e^{-\sum_{i=1}^n x_i/\beta_1}}{h(\mathbf{x}) \frac{1}{\beta_0^{n\alpha}} e^{-\sum_{i=1}^n x_i/\beta_0}} > \tilde{k} \\ &\iff e^{(1/\beta_0 - 1/\beta_1) \sum_{i=1}^n x_i} > \tilde{k} \left( \frac{\beta_1}{\beta_0} \right)^{n\alpha} \\ &\iff \sum_{i=1}^n x_i > \frac{\beta_0 \beta_1}{\beta_1 - \beta_0} \log \left( \tilde{k} \left( \frac{\beta_1}{\beta_0} \right)^{n\alpha} \right) \equiv k. \end{aligned}$$

Thus, incorporating the set  $\{\mathbf{x} \mid f_{\mathbf{X}}(\mathbf{x}; \alpha, \beta_1) = \tilde{k} f_{\mathbf{X}}(\mathbf{x}; \alpha, \beta_0)\}$  to the rejection region, the Neyman-Pearson test for the present testing problem can be written as in (3.4.4), just in terms of the sufficient statistic  $S = X_1 + X_2 + \cdots + X_n$ . To determine the value of  $k$  to obtain a test of size  $a_0$ , notice that the power function of the test is given by  $\pi(\beta) = P_\beta[X_1 + X_2 + \cdots + X_n \geq k]$ , and then  $k$  must be selected in such a way that

$$a_0 = \pi(\beta_0) = P_{\beta_0}[X_1 + X_2 + \cdots + X_n > k]. \quad (3.4.7)$$

Recalling that  $(X_1 + X_2 + \cdots + X_n)/\beta$  has the  $\text{Gamma}(n\alpha, 1)$  when  $\beta$  is the true parameter value, it follows that

$$\pi(\beta) = P_\beta \left[ \frac{X_1 + X_2 + \cdots + X_n}{\beta} > \frac{k}{\beta} \right] = \int_{k/\beta}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} dx,$$

so that (3.4.7) is equivalent to

$$a_0 = \int_{k/\beta_0}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} dx,$$

that is,

$$\frac{k}{\beta_0} = p_{a_0},$$

the right percentil of order  $a_0$  of the  $Gamma(\alpha, 1)$  distribution. Thus,  $k = \beta_0 p_{a_0}$ , and the Neyman-Person test is given by

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } X_1 + X_2 + \cdots + X_n \geq \beta_0 p_{a_0} \\ 0, & \text{if } X_1 + X_2 + \cdots + X_n < \beta_0 p_{a_0}. \end{cases}$$

Now, it will be shown that this is an unbiased test. Indeed,

$$\begin{aligned} \pi(\beta_1) &= P_{\beta_1}[X_1 + X_2 + \cdots + X_n > \beta_0 p_{a_0}] \\ &= P_{\beta_1} \left[ \frac{X_1 + X_2 + \cdots + X_n}{\beta_1} > \frac{\beta_0 p_{a_0}}{\beta_1} \right] \\ &= \int_{\beta_0 p_{a_0}/\beta_1}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} I_{(0,\infty)}(x) dx \end{aligned}$$

where (3.4.6) was used to set the second equality; since  $\beta_0 < \beta_1$ , it follows that  $\beta_0 p_{a_0}/\beta_1 < p_{a_0}$ , and then

$$\pi(\beta_1) > \int_{p_{a_0}}^{\infty} \frac{1}{\Gamma(n\alpha)} x^{n\alpha-1} e^{-x} dx = a_0 = \pi(\beta_0),$$

showing that the test is unbiased.

(iii) As already mentioned,  $P_{\beta}[X_1 + X_2 + \cdots + X_n = k] = 0$ , so that the power function of the test (3.4.2) is given by

$$\begin{aligned} \pi(\beta) &= P_{\beta}[X_1 + X_2 + \cdots + X_n > k] + \psi P_{\beta}[X_1 + X_2 + \cdots + X_n = k] \\ &= P_{\beta}[X_1 + X_2 + \cdots + X_n \geq k]. \end{aligned}$$

Let  $\beta_0 < \beta_1$  be two positive numbers and set  $a_0 = \pi(\beta_0)$ , so that  $a_0 = P_{\beta_0}[X_1 + X_2 + \cdots + X_n \geq k]$ . In this case, as it was established in part (b),  $k = \beta_0 p_{a_0}$  and

$$\pi(\beta_1) = P_{\beta_1}[X_1 + X_2 + \cdots + X_n \geq \beta_0 p_{a_0}] > a_0 = \pi(\beta_0),$$

showing that  $\pi$  is increasing. □

## Chapter 4

### Uniqueness of Neyman-Pearson Tests

In this chapter the uniqueness of most powerful tests will be studied. The presentation begins with an example that shows explicitly that it is possible that the problem of testing a simple null hypothesis versus a simple alternative may admit several most powerful tests. Next, a Neyman-Pearson test is compared with other most powerful test and, finally, a criterion for the uniqueness of a most powerful test is obtained. Examples illustrating the different ideas are provided.

#### 4.1. An Example

In this section explicit examples will be presented to show that a most powerful test is not necessarily unique.

**Example 4.1.1.** Consider the problem of testing

$$\mathcal{H}_0: \theta = 1 \text{ versus } \mathcal{H}_1: \theta = 2 \tag{4.1.1}$$

using a test of size  $\alpha = .05$  based on a single observation  $X$  of the *Uniform*  $(0, \theta)$  distribution, where  $\theta \in \{1, 2\}$ ; for this problem, it was shown in Example 3.4.3 that the test specified by

$$\varphi(x) = \begin{cases} 1, & \text{if } x \in [1, 2) \\ .05, & \text{if } x \in (0, 1). \end{cases}$$

is most powerful. The corresponding power function is given by

$$\pi_{\varphi}(\theta) = E_{\theta}[\varphi(X)] = \int_0^{\theta} \frac{1}{\theta} \varphi(x) dx = \begin{cases} \int_0^1 .05 dx, & \text{if } \theta = 1 \\ \int_0^1 \frac{1}{2}(.05) dx + \int_1^2 \frac{1}{2}(1) dx, & \text{if } \theta = 2, \end{cases}$$

that is,

$$\pi_{\varphi}(1) = .05, \quad \text{and} \quad \pi_{\varphi}(2) = .525. \quad (4.1.2)$$

Now, different tests with the same power function as  $\varphi$  will be constructed.

(i) Define the critical function  $\tilde{\varphi}$  by

$$\tilde{\varphi}(x) = I_{(.95, \infty)}(x) = \begin{cases} 1, & \text{if } x > .95, \\ 0, & \text{if } x < .95. \end{cases}$$

The power function associated to  $\tilde{\varphi}$  is

$$\pi_{\tilde{\varphi}}(\theta) = E_{\theta}[\tilde{\varphi}(X)] = \int_0^{\theta} \frac{1}{\theta} \tilde{\varphi}(x) dx = \begin{cases} \int_0^1 \tilde{\varphi}(x) dx, & \text{if } \theta = 1 \\ \int_0^2 \frac{1}{2} \tilde{\varphi}(x) dx, & \text{if } \theta = 2 \end{cases}$$

that is,

$$\pi_{\tilde{\varphi}}(1) = \int_{.95}^2 dx = .05 \quad \text{and} \quad \pi_{\tilde{\varphi}}(2) = \int_{.95}^2 \frac{1}{2} dx = \frac{2 - .95}{2} = .525,$$

and then  $\tilde{\varphi}$  has the same power function as  $\varphi$ ; see (4.1.2). Therefore,  $\tilde{\varphi}$  is also a most powerful test for the problem (4.1.1).

(ii) Consider now critical function  $\hat{\varphi}$  by

$$\hat{\varphi}(x) = I_{(0, .05)}(x) + I_{(1, \infty)}(x) = \begin{cases} 1, & \text{if } 0 < x < .05 \text{ or } x > .1, \\ 0, & \text{otherwise.} \end{cases}$$

The power function corresponding to  $\hat{\varphi}$  is

$$\pi_{\hat{\varphi}}(\theta) = E_{\theta}[\hat{\varphi}(X)] = \int_0^{\theta} \frac{1}{\theta} \hat{\varphi}(x) dx = \begin{cases} \int_0^1 \hat{\varphi}(x) dx, & \text{if } \theta = 1 \\ \int_0^2 \frac{1}{2} \hat{\varphi}(x) dx, & \text{if } \theta = 2. \end{cases}$$

More explicitly,

$$\pi_{\hat{\varphi}}(1) = \int_0^{.05} dx = .05 \quad \text{and} \quad \pi_{\hat{\varphi}}(2) = \int_0^{.05} \frac{1}{2} dx + \int_1^2 \frac{1}{2} dx = .025 + .5 = .525,$$

showing that  $\hat{\varphi}$  has the same power function as  $\varphi$ , and then  $\hat{\varphi}$  is also a most powerful test for the problem (4.1.1).

Summarizing, three most powerful test of size  $\alpha = .05$  for the problem (4.1.1) has been constructed. On the other hand, notice that for any  $a \in (0, 1)$ , the function  $\varphi_1 = a\varphi + (1 - a)\tilde{\varphi}$  takes values in  $(0, 1)$ , and then is a critical function. The corresponding power function is

$$\begin{aligned} \pi_{\varphi_a}(\theta) &= E_{\theta}[\varphi_a(X)] \\ &= E_{\theta}[a\varphi(X) + (1 - a)\tilde{\varphi}(X)] \\ &= aE_{\theta}[\varphi(X)] + (1 - a)E_{\theta}[\tilde{\varphi}(X)] \\ &= a\pi_{\varphi}(\theta) + (1 - a)\pi_{\tilde{\varphi}}(\theta) \\ &= \pi_{\varphi}(\theta) \end{aligned}$$

where the last equality is due to the fact that  $\tilde{\varphi}$  and  $\varphi$  have the same critical function. Consequently,  $\varphi_\alpha$  is also a most powerful test for (4.1.1), showing that this problem has an infinite number of most powerful tests.  $\square$

## 4.2. Comparing two Tests

As already observed, in general the problem of testing a simple null hypothesis versus a simple alternative may admit several most powerful tests. In this section the relation between two most powerful tests is studied and it is shown that, under mild conditions, a most powerful test is unique. Throughout this remainder  $\mathbf{X}$  is a random vector whose distribution is  $P_{\theta_0}$  or  $P_{\theta_1}$ , and the following testing problem is considered:

$$\mathcal{H}_0: \theta = \theta_0 \quad \text{versus} \quad \mathcal{H}_1: \theta = \theta_1 \quad (4.2.1)$$

Recall that it is supposed that both  $P_{\theta_0}$  or  $P_{\theta_1}$  are both continuous or discrete, and the corresponding densities or probability functions are denoted as  $f(\mathbf{x}; \theta_0)$  and  $f(\mathbf{x}; \theta_1)$ , respectively. A relation between two most powerful tests is established in the following theorem.

**Theorem 4.2.1.** Consider the testing problem (4.2.1) and, given  $\alpha \in (0, 1)$ , let  $\varphi_{k, \psi}$  be the Neyman-Pearson test of size  $\alpha$ , where  $k \geq 0$  and  $\psi: \mathcal{X} \rightarrow [0, 1]$ , and define  $\mathcal{D}$  as the the region where  $f(\mathbf{x}; \theta_1)$  and  $kf(\mathbf{x}; \theta_0)$  are different, that is,

$$\mathcal{D} = \{\mathbf{x} \in \mathcal{X} \mid f(\mathbf{x}; \theta_1) > kf(\mathbf{x}; \theta_0)\} \cup \{\mathbf{x} \in \mathcal{X} \mid f(\mathbf{x}; \theta_1) < kf(\mathbf{x}; \theta_0)\}. \quad (4.2.2)$$

With this notation, if  $\tilde{\varphi}$  is other most powerful test of size  $\alpha$ , then

$$\tilde{\varphi} \text{ and } \varphi_{k, \psi} \text{ coincide on the region } \mathcal{D}.$$

More precisely,

$$P_\theta[[\mathbf{X} \in \mathcal{D}] \cap [\varphi_{k, \psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})]] = P_\theta[\mathbf{X} \in \mathcal{D}], \quad \theta = \theta_0, \theta_1. \quad (4.2.3)$$

**Remark 4.2.1.** (a) Suppose that  $P_\theta[\mathcal{D}] \neq 0$ . In this case, notice that the equality in (4.2.3) is equivalent to

$$P_\theta[\varphi_{k, \psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X}) \mid \mathbf{X} \in \mathcal{D}] = \frac{P_\theta[[\mathbf{X} \in \mathcal{D}] \cap [\varphi_{k, \psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})]]}{P_\theta[\mathbf{X} \in \mathcal{D}]} = 1.$$

In words, this equality means that, under the condition that  $\mathbf{X} \in \mathcal{D}$  has been observed, with probability 1 the critical functions  $\tilde{\varphi}$  and  $\varphi_{k, \psi}$  coincide.

(b) The following simple analytical facts will be useful:

(i) If  $G$  is a nonnegative function defined on a region  $\mathcal{X} \subset \mathbb{R}^n$ , then

$$\int_{\mathcal{X}} G(\mathbf{x}) d\mathbf{x} = 0 \Rightarrow \int_{\mathcal{A}} d\mathbf{x} = 0, \quad \text{where } \mathcal{A} = \{\mathbf{x} \in \mathcal{X} \mid G(\mathbf{x}) \neq 0\}$$

(ii) For  $\mathcal{A} \subset \mathbb{R}^n$

$$\int_{\mathcal{A}} d\mathbf{x} = 0 \Rightarrow \int_{\mathcal{A}} f(\mathbf{x}) d\mathbf{x} = 0 \quad \text{for any } f: \mathcal{A} \rightarrow \mathbb{R}.$$

□

The proof of Theorem 4.2.1 is particularly simple when the observation vector  $\mathbf{X}$  is discrete, and for this reason the argument is presented in two parts.

**Proof of Theorem 4.2.1.** The backbone of the argumentation is the relation

$$0 \leq [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)], \quad \mathbf{x} \in \mathcal{X}; \quad (4.2.4)$$

established in the proof of Theorem 3.1.1. To begin with, recall that the Neyman-Pearson test  $\varphi_{k,\psi}$  is most powerful for the problem (4.2.1) at level  $\alpha$ . Since  $\tilde{\varphi}$  is also most powerful at the significance level  $\alpha$ , it follows that the power functions of these tests coincide at  $\theta = \theta_1$ , that is,

$$E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] = \pi_{\tilde{\varphi}}(\theta_1) = \pi_{\varphi_{k,\psi}}(\theta_1) = E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})]$$

*i.e.*,

$$E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] = 0.$$

On the other hand, by construction, the size of the test  $\varphi_{k,\psi}$  is  $\alpha$ , that is,  $E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] = \alpha$  whereas, since  $\tilde{\varphi}$  is most powerful at size  $\alpha$ , it follows that  $E_{\theta_0}[\tilde{\varphi}(\mathbf{X})] \leq \alpha$ ; see Definition 2.5.3. Consequently,  $E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})] \geq 0$  and then, recalling that  $k$  is nonnegative number,

$$-k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]] \leq 0.$$

Combining these two last displays it follows that

$$E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] - k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]] \leq 0. \quad (4.2.5)$$

From this point, it is convenient to analyze the discrete and continuous cases separately.

**Case 1:** The observation vector  $\mathbf{X}$  is discrete.

Taking the summation over  $\mathbf{x} \in \mathcal{X}$  in both sides of (4.2.4) it follows that

$$\begin{aligned}
0 &\leq \sum_{\mathbf{x} \in \mathcal{X}} [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] \\
&= \sum_{\mathbf{x} \in \mathcal{X}} [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})]f(\mathbf{x}; \theta_1) - k \sum_{\mathbf{x} \in \mathcal{X}} [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})]f(\mathbf{x}; \theta_0) \\
&= \sum_{\mathbf{x} \in \mathcal{X}} \varphi_{k,\psi}(\mathbf{x})f(\mathbf{x}; \theta_1) - \sum_{\mathbf{x} \in \mathcal{X}} \tilde{\varphi}(\mathbf{x})f(\mathbf{x}; \theta_1) \\
&\quad - k \left( \sum_{\mathbf{x} \in \mathcal{X}} \varphi_{k,\psi}(\mathbf{x})f(\mathbf{x}; \theta_0) - \sum_{\mathbf{x} \in \mathcal{X}} \tilde{\varphi}(\mathbf{x})f(\mathbf{x}; \theta_0) \right) \\
&= E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] - k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]]
\end{aligned} \tag{4.2.6}$$

Combining this relation with (4.2.5) it follows that

$$E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] - k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]] = 0,$$

an equality that, *via* (4.2.6), is equivalent to

$$\sum_{\mathbf{x} \in \mathcal{X}} [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] = 0.$$

Since all the terms in this last summation are nonnegative, by (4.2.4), it follows that

$$[\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] = 0, \quad \mathbf{x} \in \mathcal{X}.$$

Since  $[f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] \neq 0$  when  $\mathbf{x} \in \mathcal{D}$ , it follows that

$$\mathbf{x} \in \mathcal{D} \Rightarrow \varphi_{k,\psi}(\mathbf{x}) = \tilde{\varphi}(\mathbf{x}),$$

so that the inclusion  $[\mathbf{X} \in \mathcal{D}] \subset [\varphi_{k,\psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})]$  holds. Consequently,

$$[\mathbf{X} \in \mathcal{D}] \cap [\varphi_{k,\psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})] = [\mathbf{X} \in \mathcal{D}],$$

an equality that immediately leads to to (4.2.3).

**Case 2:** The observation vector  $\mathbf{X}$  is continuous.

The argument is similar to the one used in the discrete case. Taking the integral over  $\mathbf{x} \in \mathcal{X}$  in both sides of (4.2.4) and paralleling the above argument it follows that

$$\begin{aligned}
0 &\leq \int_{\mathbf{x} \in \mathcal{X}} [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] d\mathbf{x} \\
&= E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] - k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]],
\end{aligned}$$

a relation that together with (4.2.5) yields that

$$E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_1}[\tilde{\varphi}(\mathbf{X})] - k[E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] - E_{\theta_0}[\tilde{\varphi}(\mathbf{X})]] = 0,$$

and then

$$\int_{\mathbf{x} \in \mathcal{X}} [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] = 0.$$

Since the product in this integral is nonnegative, Remark 4.2.1(b) yields that

$$\int_{\mathbf{x} \in \mathcal{A}} d\mathbf{x} = 0,$$

and then

$$P_{\theta_0}[\mathbf{X} \in \mathcal{A}] = \int_{\mathbf{x} \in \mathcal{A}} f(\mathbf{x}; \theta_0) d\mathbf{x} = 0 = \int_{\mathbf{x} \in \mathcal{A}} f(\mathbf{x}; \theta_1) d\mathbf{x} = P_{\theta_1}[\mathbf{X} \in \mathcal{A}], \quad (4.2.7)$$

where

$$\begin{aligned} \mathcal{A} &= \{\mathbf{x} \in \mathcal{X} \mid [\varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x})][f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0)] \neq 0\} \\ &= \{\mathbf{x} \in \mathcal{X} \mid \varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x}) \neq 0\} \cap \{\mathbf{x} \in \mathcal{X} \mid f(\mathbf{x}; \theta_1) - kf(\mathbf{x}; \theta_0) \neq 0\} \\ &= \{\mathbf{x} \in \mathcal{X} \mid \varphi_{k,\psi}(\mathbf{x}) - \tilde{\varphi}(\mathbf{x}) \neq 0\} \cap \mathcal{D}; \end{aligned}$$

see (4.2.2) for the last equality. It follows that the event  $[\mathbf{X} \in \mathcal{A}]$  can be expressed as

$$[\mathbf{X} \in \mathcal{A}] = [\varphi_{k,\psi}(\mathbf{X}) \neq \tilde{\varphi}(\mathbf{X})] \cap [\mathbf{X} \in \mathcal{D}]$$

and then (4.2.7) yields that

$$P_{\theta}[[\varphi_{k,\psi}(\mathbf{X}) \neq \tilde{\varphi}(\mathbf{X})] \cap [\mathbf{X} \in \mathcal{D}]] = 0, \quad \theta = \theta_0, \theta_1.$$

Therefore, for  $\theta = \theta_0, \theta_1$ ,

$$\begin{aligned} P_{\theta}[\mathbf{X} \in \mathcal{D}] &= P_{\theta}[[\varphi_{k,\psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})] \cap [\mathbf{X} \in \mathcal{D}]] + P_{\theta}[[\varphi_{k,\psi}(\mathbf{X}) \neq \tilde{\varphi}(\mathbf{X})] \cap [\mathbf{X} \in \mathcal{D}]] \\ &= P_{\theta}[[\varphi_{k,\psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})] \cap [\mathbf{X} \in \mathcal{D}]] \end{aligned}$$

establishing (4.2.3). □

**Corollary 4.2.1.** Consider the testing problem

$$\mathcal{H}_0: \theta = \theta_0 \quad \text{versus} \quad \mathcal{H}_1: \theta = \theta_1, \quad (4.2.8)$$

and let  $\varphi_{k,\psi}$  be (the critical function of a) Neyman-Pearson test for this problem. In this case  $\varphi_{k,\psi}$  is an unbiased test, that is,

$$\pi_{\varphi_{k,\psi}}(\theta_0) \leq \pi_{\varphi_{k,\psi}}(\theta_1). \quad (4.2.9)$$

**Proof.** Theorem 3.1.1 establishes that the test  $\varphi_{k,\psi}$  is most powerful for the problem (4.2.8) with size  $\pi_{\varphi_{k,\psi}}(\theta_0)$ , and consequently it is unbiased, by Lemma , that is, the probability

of rejecting  $\mathcal{H}_0$  when it is true—which is given by  $\pi_{\varphi_{k,\psi}}(\theta_0)$ —is less than or equal to the probability  $\pi_{\varphi_{k,\psi}}(\theta_1)$  of rejecting the null hypothesis when it is false, which is the desired conclusion.  $\square$

As an immediate consequence, the following result on the uniqueness of a most powerful test is obtained.

**Corollary 4.2.2.** Consider the testing problem (4.2.1) and suppose that, for each  $k \in [0, \infty)$ ,

$$P_\theta \left[ \frac{f(\mathbf{X}; \theta_1)}{f(\mathbf{X}; \theta_0)} = k \right] = 0, \quad \theta = \theta_0, \theta_1.$$

In this case, a Neyman-Pearson test  $\varphi_{k,\psi}$  of size  $\alpha$  is, essentially, the unique most powerful test with level  $\alpha$ . More precisely, if  $\tilde{\varphi}$  is other most powerful test at level  $\alpha$ , then

$$P_\theta[\varphi_{k,\psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})] = 1, \quad \theta = \theta_0, \theta_1.$$

**Proof.** With the notation in (4.2.2), notice that

$$P_\theta[\mathbf{X} \in \mathcal{D}^c] = P_\theta \left[ \frac{f(\mathbf{X}; \theta_1)}{f(\mathbf{X}; \theta_0)} = k \right] = 0,$$

so that  $P_\theta[\mathbf{X} \in \mathcal{D}] = 1$ . It follows that (4.2.3) is equivalent to  $P_\theta[\varphi_{k,\psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})] = 1$  for  $\theta = \theta_0, \theta_1$ .  $\square$

### 4.3. Strict Unbiasedness

In Corollary 4.2.1 it was show that any Neyman-Pearson test  $\varphi_{k,\psi}$  for the problem (4.2.1) is unbiased, that is,

$$E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] \leq E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})].$$

The main objective of this section is to show that, in general, the inequality in this relation is strict, a result that is formally stated as follows.

**Theorem 4.3.1.** Let  $\mathbf{X}$  be a random vector with density or probability function  $f(\mathbf{x}; \theta)$ , where  $\theta \in \{\theta_0, \theta_1\}$  and, given  $\alpha \in (0, 1)$ , let  $\phi_{k,\psi}$  be a Neyman-Pearson test of level  $\alpha$  for the problem

$$\mathcal{H}_0: \theta = \theta_0 \quad \text{versus} \quad \mathcal{H}_1: \theta = \theta_1.$$

In this case the test  $\phi_{k,\psi}$  is *strictly unbiased*, that is,

$$E_{\theta_0}[\varphi_{k,\psi}(\mathbf{X})] < E_{\theta_1}[\varphi_{k,\psi}(\mathbf{X})]. \quad (4.3.1)$$

The proof of this result is based on Theorem 4.2.1 and uses Assumption 2.1.1.

**Proof.** Given  $\alpha \in (0, 1)$  let  $\varphi_{k, \psi}$  be the Neyman-Pearson test of size  $\alpha$ . By (4.2.1), the inequality  $E_{\theta_0}[\varphi_{k, \psi}(\mathbf{X})] \leq E_{\theta_1}[\varphi_{k, \psi}(\mathbf{X})]$  holds. Thus, to establish the desired conclusion it is sufficient to show that

$$E_{\theta_0}[\varphi_{k, \psi}(\mathbf{X})] = E_{\theta_1}[\varphi_{k, \psi}(\mathbf{X})] \quad (4.3.2)$$

does not occur. Proceeding by contradiction, *suppose* that this equality holds. Now, defining  $\tilde{\varphi}(\mathbf{x}) = \alpha$  for every  $\mathbf{x} \in \mathcal{X}$ , it follows that

$$\alpha = E_{\theta_0}[\tilde{\varphi}(\mathbf{X})] = E_{\theta_1}[\tilde{\varphi}(\mathbf{X})],$$

so that  $\tilde{\varphi}$  is also a most powerful test with size  $\alpha$ . Then, Theorem 4.2.1 yields that

$$P_{\theta}[\{\mathbf{X} \in \mathcal{D}\} \cap \{\varphi_{k, \psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})\}] = P_{\theta}[\mathbf{X} \in \mathcal{D}], \quad \theta = \theta_0, \theta_1,$$

where  $\mathcal{D}$  is given in (4.2.2). Notice now that on the event  $\{\mathbf{X} \in \mathcal{D}\}$ , one of the inequalities  $f(\mathbf{X}; \theta_1) > kf(\mathbf{X}; \theta_0)$  or  $f(\mathbf{X}; \theta_1) < kf(\mathbf{X}; \theta_0)$ , and in these cases  $\varphi_{k, \psi}(\mathbf{X}) = 1$  or  $\varphi_{k, \psi}(\mathbf{X}) = 0$ , respectively. Since  $\tilde{\varphi}(\mathbf{X})$  attains only the value  $\alpha \in (0, 1)$ , it follows that the equality  $\varphi_{k, \psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})$  can not occur. In short,

$$\{\mathbf{X} \in \mathcal{D}\} \cap \{\varphi_{k, \psi}(\mathbf{X}) = \tilde{\varphi}(\mathbf{X})\} = \emptyset,$$

and combining this and the previous display it follows that

$$P_{\theta}[\mathbf{X} \in \mathcal{D}] = 0, \quad \theta = \theta_0, \theta_1,$$

that is,

$$P_{\theta}[f(\mathbf{X}; \theta_1) = kf(\mathbf{X}; \theta_0)] = P_{\theta}[\mathbf{X} \in \mathcal{D}^c] = 1, \quad \theta = \theta_0, \theta_1,$$

an equality that leads to

$$P_{\theta}[A] = P_{\theta}[A \cap \{f(\mathbf{X}; \theta_1) = kf(\mathbf{X}; \theta_0)\}], \quad A \subset \mathcal{X}, \quad \theta = \theta_0, \theta_1, \quad (4.3.3)$$

To continue, suppose that  $\mathbf{X}$  is discrete. and notice that, for every  $A \subset \mathbb{R}^n$ ,

$$\begin{aligned} P_{\theta_1}[A] &= P_{\theta_1}[A \cap \{f(\mathbf{X}; \theta_1) = kf(\mathbf{X}; \theta_0)\}] \\ &= \sum_{\mathbf{y} \in A \cap \{\mathbf{x} | f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}} f(\mathbf{y}; \theta_1) \\ &= \sum_{\mathbf{y} \in A \cap \{\mathbf{x} | f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}} kf(\mathbf{y}; \theta_0) \\ &= k \sum_{\mathbf{y} \in A \cap \{\mathbf{x} | f(\mathbf{x}; \theta_1) = kf(\mathbf{x}; \theta_0)\}} f(\mathbf{y}; \theta_0) \\ &= kP_{\theta_0}[A \cap \{f(\mathbf{X}; \theta_1) = kf(\mathbf{X}; \theta_0)\}] \\ &= kP_{\theta_0}[A] \end{aligned}$$

Since  $1 = P_{\theta_0}[\mathcal{X}] = P_{\theta_1}[\mathcal{X}]$ , setting  $A = \mathcal{X}$  in the above display it follows that

$$1 = P_{\theta_1}[\mathcal{X}] = kP_{\theta_0}[\mathcal{X}] = k,$$

and then

$$P_{\theta_1}[A] = P_{\theta_0}[A] \text{ for every } A,$$

that is, the distributions  $P_{\theta_1}$  and  $P_{\theta_0}$  coincide, contradicting Assumption 2.1.1. Therefore, (4.3.2) does not occur, a fact that, as already mentioned, establishes (4.3.1). When  $\mathbf{X}$  is continuous, a similar argument—replacing the summation by integrals—allows to obtain the desired conclusion.  $\square$

The identifiability condition in Assumption 2.1.1 is practically satisfied in all models considered in the literature (with exceptions arising in the study of experimental designs). For instance, in Example 3.4.1 the problem of testing  $\mathcal{H}_0: \mu = \mu_0$  versus  $\mathcal{H}_1: \mu = \mu_1$  based on a sample  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  of the  $\mathcal{N}(\mu, \sigma_0^2)$  distribution was considered, and it was observed that the most powerful test satisfies that  $\pi(\mu_0) < \pi(\mu_1)$ ; the reason behind the strict inequality is that the model is identifiable.

#### 4.4. Monotone Likelihood Ratio

In this section a property of (one-parameter) statistical models that is useful to determine the structure of most powerful tests is studied. Such a property concerns the behavior of the quotient of two densities or probability functions and is stated as follows:

**Definition 4.4.1.** Consider a statistical model

$$\mathbf{X} \sim P_\theta, \quad \theta \in \Theta,$$

where  $\Theta \subset \mathbb{R}$ , and suppose that all the distributions  $P_\theta$  are discrete or continuous, and let  $f(\mathbf{x}; \theta)$  be the probability function or density corresponding a  $P_\theta$ . In this context, the model  $\mathbf{X} \sim P_\theta$ —or the family  $\{f(\cdot; \theta)\}_{\theta \in \Theta}$ —has *monotone likelihood ratio* if for some statistic  $T = T(\mathbf{X})$  the following property holds:

For every pair  $\theta_0, \theta_1 \in \Theta$  with  $\theta_0 < \theta_1$ , there exists an *increasing* function  $g_{\theta_0, \theta_1}(\cdot)$  such that

$$\frac{f(\mathbf{x}; \theta_1)}{f(\mathbf{x}; \theta_0)} = g_{\theta_0, \theta_1}(T(\mathbf{x}));$$

in this case  $T$  is referred to as the *test statistic*.

The models with monotone likelihood ratio arise frequently in applications.

**Example 4.4.1.** (i) Suppose that  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of the  $\mathcal{N}(\mu, \sigma_0^2)$  distribution, where  $\mu \in \mathbb{R}$  and  $\sigma_0^2 > 0$  is a known constant. In this case,

$$\begin{aligned} f(\mathbf{x}; \mu) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_0^2}} e^{-(x_i - \mu)^2 / 2\sigma_0^2} \\ &= \frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-[\sum_{i=1}^n x_i^2 + n\mu^2] / (2\sigma_0^2)} e^{\mu \sum x_i / \sigma_0^2}, \end{aligned}$$

so that

$$\begin{aligned} \frac{f(\mathbf{x}; \mu_1)}{f(\mathbf{x}; \mu_0)} &= \frac{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-[\sum_{i=1}^n x_i^2 + n\mu_1^2] / (2\sigma_0^2)} e^{\mu_1 \sum x_i / \sigma_0^2}}{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-[\sum_{i=1}^n x_i^2 + n\mu_0^2] / (2\sigma_0^2)} e^{\mu_0 \sum x_i / \sigma_0^2}} \\ &= e^{(\mu_0^2 - \mu_1^2) / (2\sigma_0^2)} e^{n(\mu_1 - \mu_0) \sum x_i / \sigma_0^2} \\ &= g_{\mu_0, \mu_1}(T(\mathbf{x})) \end{aligned}$$

where

$$T(\mathbf{x}) = \sum x_i, \quad \text{and} \quad g_{\mu_0, \mu_1}(t) = e^{(\mu_0^2 - \mu_1^2) / (2\sigma_0^2)} e^{(\mu_1 - \mu_0)t / \sigma_0^2};$$

since  $g_{\mu_0, \mu_1}(\cdot)$  is increasing, it follows that the family of normal densities with known variance has monotone likelihood ratio, and that the  $T = \sum_{i=1}^n X_i$ —or, equivalently, the sample mean  $\bar{\mathbf{X}}$ —is a corresponding test statistic.

(ii) let  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be a sample of the *Bernoulli*( $p$ ) distribution, where  $p \in (0, 1)$ . In this case,  $\mathbf{X}$  takes values on the set  $\mathcal{X} = \{0, 1\}^n$  consisting of all vectors  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  such that  $x_i = 0, 1$  for  $i = 1, 2, \dots, n$ . In this case, for  $\mathbf{x} \in \mathcal{X}$  and  $p \in (0, 1)$

$$\begin{aligned} f(\mathbf{x}; p) &= \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} \\ &= \prod_{i=1}^n (1-p) \left( \frac{p}{1-p} \right)^{x_i} \\ &= (1-p)^n \left( \frac{p}{1-p} \right)^{\sum_{i=1}^n x_i} \end{aligned}$$

so that, for  $p_1 > p_0$

$$\begin{aligned} \frac{f(\mathbf{x}; p_1)}{f(\mathbf{x}; p_0)} &= \frac{(1-p_1)^n \left( \frac{p_1}{1-p_1} \right)^{\sum_{i=1}^n x_i}}{(1-p_0)^n \left( \frac{p_0}{1-p_0} \right)^{\sum_{i=1}^n x_i}} \\ &= \left( \frac{1-p_1}{1-p_0} \right)^n \left( \frac{p_1/1-p_1}{p_0/1-p_0} \right)^{\sum_{i=1}^n x_i} \\ &= g_{p_0, p_1}(T(\mathbf{x})) \end{aligned}$$

where

$$T(\mathbf{x}) = \sum_{i=1}^n x_i, \quad \text{and} \quad g_{p_0, p_1}(t) = \left( \frac{1-p_1}{1-p_0} \right)^n \left( \frac{p_1/1-p_1}{p_0/1-p_0} \right)^t;$$

notice that, since  $p_1 > p_0$ ,  $g_{p_0, p_1}(\cdot)$  is increasing, and then the family of Bernoulli distributions has monotone likelihood ratio with  $T = \sum_{i=1}^n X_i$  as the test statistic.

(iii) Consider a sample  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  of the *Geometric*( $p$ ) distribution, where  $p \in (0, 1)$ . In this context, the set of possible values of  $\mathbf{X}$  is  $\mathcal{X} = \{0, 1, 3, \dots\}^n$  consisting of all vectors  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  whose components are nonnegative integers. For each  $\mathbf{x} \in \mathcal{X}$  and  $p \in (0, 1)$

$$\begin{aligned} f(\mathbf{x}; , p) &= \prod_{i=1}^n (1-p)^{x_i-1} p \\ &= \prod_{i=1}^n \left( \frac{p}{1-p} \right) (1-p)^{x_i} \\ &= \left( \frac{p}{1-p} \right)^n (1-p)^{\sum_{i=1}^n x_i}. \end{aligned}$$

Therefore, for  $p_1 > p_0$

$$\begin{aligned} \frac{f(\mathbf{x}; , p_1)}{f(\mathbf{x}; , p_0)} &= \frac{\left( \frac{p_1}{1-p_1} \right)^n (1-p_1)^{\sum_{i=1}^n x_i}}{\left( \frac{p_0}{1-p_0} \right)^n (1-p_0)^{\sum_{i=1}^n x_i}} \\ &= \left( \frac{p_1(1-p_0)}{p_0(1-p_1)} \right)^n \left( \frac{1-p_0}{1-p_1} \right)^{-\sum_{i=1}^n x_i} \\ &= g_{p_0, p_1}(T(\mathbf{x})) \end{aligned}$$

where

$$T(\mathbf{x}) = -\sum_{i=1}^n x_i, \quad \text{and} \quad g_{p_0, p_1}(t) = \left( \frac{p_1(1-p_0)}{p_0(1-p_1)} \right)^n \left( \frac{1-p_0}{1-p_1} \right)^t;$$

recalling that,  $p_1 > p_0$ , it follows that  $g_{p_0, p_1}(\cdot)$  is increasing, and then the present geometric model has monotone likelihood ratio with test statistic given by  $T = -\sum_{i=1}^n X_i$ .

(iv) Suppose that  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of the  $\mathcal{N}(\mu_0, \sigma)$  distribution, where  $\mu_0$  is a known constant and  $\sigma^2 \in (0, \infty)$  is unknown. In this case,

$$\begin{aligned} f(\mathbf{x}; , \sigma^2) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(x_i-\mu_0)^2/2\sigma^2} \\ &= \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\sum_{i=1}^n (x_i-\mu_0)^2/2\sigma^2} \end{aligned}$$

so that, for  $\sigma_1^2 > \sigma_0^2$ ,

$$\begin{aligned} \frac{f(\mathbf{x}; \sigma_1^2)}{f(\mathbf{x}; \sigma_0^2)} &= \frac{\frac{1}{(2\pi\sigma_1^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu_0)^2 / 2\sigma_1^2}}{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu_0)^2 / 2\sigma_0^2}} \\ &= \left(\frac{\sigma_0^2}{\sigma_1^2}\right)^{n/2} e^{[(1/\sigma_0^2) - (1/\sigma_1^2)] \sum_{i=1}^n (x_i - \mu_0)^2} \\ &= g_{\sigma_0^2, \sigma_1^2} \left( \sum_{i=1}^n (x_i - \mu_0)^2 \right) \end{aligned}$$

where

$$T(\mathbf{x}) = \sum_{i=1}^n (x_i - \mu_0)^2, \quad \text{and} \quad g_{\sigma_0^2, \sigma_1^2}(t) = \left(\frac{\sigma_0^2}{\sigma_1^2}\right)^{n/2} e^{[(1/\sigma_0^2) - (1/\sigma_1^2)] t},$$

since  $g_{\mu_0, \mu_1}(\cdot)$  is increasing, it follows that the family of normal densities with known mean has monotone likelihood ratio, and that

$$T(\mathbf{X}) = \sum_{i=1}^n (X_i - \mu_0)^2$$

is a test statistic for the family. □

## 4.5. Exponential Families

The examples presented above are particular cases of the following result, establishing that, under mild conditions, when sampling an *exponential family*, the collection of possible distributions of the observation vector has a monotone likelihood ratio.

**Theorem 4.5.1.** Let  $\mathcal{E} = \{f(\mathbf{x}; \cdot, \theta), \theta \in \Theta\}$  be a family of densities or probability functions, and suppose that  $\mathcal{E}$  is an *exponential family* with one-parameter, so that  $\Theta \subset \mathbb{R}$  and, for each  $\theta \in \Theta$

$$f(\mathbf{x}; \theta) = h(\mathbf{x}) e^{c(\theta)S(\mathbf{x}) + b(\theta)}. \quad (4.5.1)$$

Suppose that  $c(\theta)$  is an increasing function and that

$$\mathbf{X} = (X_1, X_2, \dots, X_n) \text{ is a sample of } f(\cdot; \theta), \quad \theta \in \Theta.$$

In this context, the family of possible distributions of  $\mathbf{X}$  has monotone likelihood ratio.

**Proof.** Notice that if  $\theta$  is the parameter value, then the density or probability function of  $\mathbf{X}$  is

$$\begin{aligned} f_{\mathbf{X}}(\mathbf{x}; \theta) &= \prod_{i=1}^n f(x_i, \theta) \\ &= \prod_{i=1}^n h(x_i) e^{c(\theta)S(x_i) + b(\theta)} = e^{nb(\theta) + c(\theta) \sum_{i=1}^n S(x_i)} \prod_{i=1}^n h(x_i). \end{aligned}$$

Thus, for  $\theta_1 > \theta_0$

$$\begin{aligned} \frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} &= \frac{e^{nb(\theta_1)+c(\theta_1)} \sum_{i=1}^n S(x_i) \prod_{i=1}^n h(x_i)}{e^{nb(\theta_0)+c(\theta_0)} \sum_{i=1}^n S(x_i) \prod_{i=1}^n h(x_i)} \\ &= e^{n[b(\theta_1)-b(\theta_0)]+[c(\theta_1)-c(\theta_0)] \sum_{i=1}^n S(x_i)} \\ &= g_{\theta_0, \theta_1}(T(\mathbf{x})) \end{aligned}$$

where

$$T(\mathbf{x}) = \sum_{i=1}^n S(x_i), \quad \text{and} \quad g_{\theta_0, \theta_1}(t) = e^{n[b(\theta_1)-b(\theta_0)]+[c(\theta_1)-c(\theta_0)]t}.$$

Recalling that  $c(\cdot)$  is increasing, it follows that  $g_{\theta_0, \theta_1}(\cdot)$  is also an increasing function.. Thus, the family  $\{f_{\mathbf{X}}(\cdot; \theta)\}_{\theta \in \Theta}$  of possible distributions of  $\mathbf{X}$  has monotone likelihood ratio, with test statistic given by  $T = \sum_{i=1}^n S(X_i)$ .  $\square$

**Remark 4.5.1.** In the context of Theorem 4.5.1 the test statistic  $T$  of the family of possible distributions of the vector  $\mathbf{X}$  coincides with the minimal sufficient statistic  $\sum_{i=1}^n S(X_i)$  for the parameter  $\theta$ .  $\square$

**Example 4.4.1**[Continued.] In case (i)  $\mathbf{X}$  is a sample of size  $n$  of the  $\mathcal{N}(\mu, \sigma_0^2)$  distribution. The corresponding density is given by

$$f(x; \mu) = \frac{1}{\sqrt{2\pi\sigma_0^2}} e^{-(x-\mu)^2/[2\sigma_0^2]} = h(x)e^{c(\mu)x+b(\mu)},$$

where

$$h(x) = \frac{1}{\sqrt{2\pi\sigma_0^2}} e^{-x^2/[2\sigma_0^2]}, \quad c(\mu) = \mu/[\sigma_0^2], \quad \text{and} \quad b(\mu) = -\mu^2/[2\sigma_0^2].$$

These expressions show that the collection of normal densities with known variance is a one-parameter exponential family, with  $S(x) = x$ . Then, Theorem 4.5.1 yields that the collection of possible distribution of the sample  $\mathbf{X}$  form a family with monotone likelihood ratio, and that  $T = \sum_{i=1}^n S(X_i) = \sum_{i=1}^n X_i$  is a test statistic. These conclusions were obtained before in a direct manner. Similarly, the samples in parts (ii)–(iv) were obtained from an exponential family, and the monotone likelihood property, as well as the expressions for the corresponding test statistics can be obtained directly from Theorem 4.5.1.  $\square$

The following example shows that a collection of distributions may have the monotone likelihood ratio property even when it is not an exponential family.

**Example 4.5.1.** (i) Suppose the  $\mathbf{X}$  is a sample of size  $n$  of the *Uniform*( $0, \theta$ ) distribution, where  $\theta > 0$ . The set  $\mathcal{X}$  of all possible values of  $\mathbf{X}$  consists of all possible the vectors with positive components, and if  $\theta$  is the true parameter value, the density of  $\mathbf{X}$  is

$$f_{\mathbf{X}}(\mathbf{x}; \theta) = \prod_{i=1}^n \frac{1}{\theta} I_{(0, \theta)}(x_i) = \frac{1}{\theta^n} I_{(0, \theta)}(\max x_i), \quad \mathbf{x} \in \mathcal{X}.$$

On the other hand, if  $\theta$  is equal to  $\theta_0$  or  $\theta_1$  where  $\theta_1 > \theta_0 > 0$ , then the components of  $\mathbf{X}$  take values in the interval  $(0, \theta_1)$ , and in this case,  $\max X_i$  also is restricted to that interval. With this in mind, notice that

$$\begin{aligned} \frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} &= \frac{[1/\theta_1^n] I_{(0, \theta_1)}(\max x_i)}{[1/\theta_0^n] I_{(0, \theta_0)}(\max x_i)} \\ &= \begin{cases} \theta_0^n / \theta_1^n, & \text{if } \max x_i < \theta_0 \\ \infty & \text{if } \theta_0 \leq \max x_i < \theta_1. \end{cases} \end{aligned}$$

Consequently,

$$\frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} = g_{\theta_0, \theta_1}(\max x_i), \quad \mathbf{x} \in (0, \theta_1)^n, \quad (4.5.2)$$

where the function  $g_{\theta_0, \theta_1}(\cdot)$  is defined in  $(0, \theta_1)$  by the following expression:

$$g_{\theta_0, \theta_1}(t) = \begin{cases} \theta_0^n / \theta_1^n, & \text{if } 0 < t < \theta_0 \\ \infty & \text{if } \theta_0 \leq t < \theta_1. \end{cases}$$

It is clear that this mapping is increasing in its domain, so that (4.5.2) yields that the collection  $\{f_{\mathbf{X}}(\mathbf{x}; \theta)\}$  of possible distributions of  $\mathbf{X}$  has monotone likelihood ratio and that  $T = \max X_i$  is a test statistic.

(ii) Consider now a sample  $\mathbf{X}$  of size  $n$  of the translated exponential density

$$f(x; \theta) = e^{-(x-\theta)} I_{(\theta, \infty)}(x)$$

where  $\theta \in \mathbb{R}$ . If  $\theta$  is the true parameter the density of  $\mathbf{X}$  is

$$f_{\mathbf{X}}(\mathbf{x}; \theta) = \prod_{i=1}^n e^{-(x_i-\theta)} I_{(\theta, \infty)}(x_i) = e^{n\theta - \sum_{i=1}^n x_i} \prod_{i=1}^n I_{(\theta, \infty)}(x_i),$$

that is,

$$f_{\mathbf{X}}(\mathbf{x}; \theta) = e^{n\theta - \sum_{i=1}^n x_i} I_{(\theta, \infty)}(\min x_i),$$

When  $\theta$  is equal to  $\theta_0$  or  $\theta_1$  where  $\theta_1 > \theta_0$ , then the components of  $\mathbf{X}$  take values in the interval  $(\theta_0, \infty)$ , and if  $\mathbf{x} \in (\theta_0, \infty)^n$ , then

$$\begin{aligned} \frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} &= \frac{e^{n\theta_1 - \sum_{i=1}^n x_i} \prod_{i=1}^n I_{(\theta_1, \infty)}(\min x_i)}{e^{n\theta_0 - \sum_{i=1}^n x_i} \prod_{i=1}^n I_{(\theta_0, \infty)}(\min x_i)} \\ &= \begin{cases} e^{n[\theta_1 - \theta_0]}, & \text{if } \theta_1 < \min x_i \\ 0, & \text{if } \theta_0 \leq \min x_i < \theta_1. \end{cases} \end{aligned}$$

Consequently,

$$\frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} = g_{\theta_0, \theta_1}(\min x_i), \quad \mathbf{x} \in (\theta_0, \infty)^n, \quad (4.5.3)$$

where the function  $g_{\theta_0, \theta_1}(\cdot)$  is defined in  $(\theta_0, \infty)$  by the following expression:

$$g_{\theta_0, \theta_1}(t) = \begin{cases} e^{n[\theta_1 - \theta_0]}, & \text{if } \theta_1 < \min x_i \\ 0, & \text{if } \theta_0 \leq \min x_i < \theta_1. \end{cases}$$

This mapping is increasing in its domain, and in this case (4.5.3) yields that the collection  $\{f_{\mathbf{X}}(\mathbf{x}; \theta)\}$  of possible distributions of  $\mathbf{X}$  has monotone likelihood ratio, and the corresponding test statistic is  $T = \min X_i$ .  $\square$

## 4.6. Testing Composite Hypothesis

In this section it is shown that the monotone likelihood ratio property of a statistical model has important implications for the problem of hypothesis testing. The main objectives are to establish the following conclusions:

- (i) For a model with the monotone likelihood ratio property with test statistic  $T$ , a Neyman-Pearson test for testing a simple null hypothesis versus a simple alternative can be expressed in terms of  $T$ , and
- (ii) Such a test is *uniformly most powerful* for certain testing problems involving composite hypothesis.

**Lemma 4.6.1.** Let  $\{f(\mathbf{x}; \theta)\}_{\theta \in \Theta}$  be a collection of densities or probability functions with monotone likelihood ratio, and let  $T$  be the corresponding test statistic. Consider the testing problem

$$\mathcal{H}_0: \theta = \theta_0 \text{ versus } \mathcal{H}_1: \theta = \theta_1. \quad (4.6.1)$$

where  $\theta_1 > \theta_0$ . For each  $k, \nu \in \mathbb{R}$ , define  $\varphi_{k, \nu}^*: [-\infty, \infty] \rightarrow [0, 1]$  as follows

$$\varphi_{k, \nu}^*(t) = \begin{cases} 1, & \text{if } t > k \\ \nu, & \text{if } t = k \\ 0, & \text{if } t < k \end{cases} \quad (4.6.2)$$

- (i) The critical function

$$\tilde{\varphi}_{k, \nu}(\mathbf{X}) = \varphi_{k, \nu}^*(T(\mathbf{X}))$$

is a Neyman-Pearson test for the testing problem (4.6.1). Moreover,

- (ii) Given  $\alpha \in (0, 1)$ ,  $k, \nu \in \mathbb{R}$  can be selected in such a way that the level of  $\tilde{\varphi}_{k, \nu}$  is  $\alpha$ , that is,  $\alpha = E_{\theta_0}[\tilde{\varphi}_{k, \nu}(X)] = E_{\theta_0}[\varphi_{k, \nu}^*(T(\mathbf{X}))]$ . Moreover,  $k$  and  $\nu$  depend only on  $\theta_0$ .

**Proof.** It must be proved that there exist a constant  $\tilde{k}$  and a function  $\psi$  such that the Neyman-Pearson test  $\varphi_{\tilde{k}, \psi}(\mathbf{X})$  in (3.1.2) coincides with  $\varphi_{k^*, \nu}(T(X))$ . To achieve this goal, notice that

$$\frac{f(\mathbf{x}; \theta_1)}{f(\mathbf{x}; \theta_0)} = g_{\theta_0, \theta_1}(T(\mathbf{x})), \quad (4.6.3)$$

where  $g_{\theta_0, \theta_1}(\cdot)$  is an increasing function. Now define the constant  $\tilde{k}$  by

$$\tilde{k} = g_{\theta_0, \theta_1}(k),$$

as well as the sets  $I_-, I_0, I_+$  as follows:

$$\begin{aligned} I_- &= \{t \mid g_{\theta_0, \theta_1}(t) < \tilde{k}\}, \\ I_0 &= \{t \mid g_{\theta_0, \theta_1}(t) = \tilde{k}\}, \\ I_+ &= \{t \mid g_{\theta_0, \theta_1}(t) > \tilde{k}\}; \end{aligned}$$

and observe that these sets are intervals, are disjoint and their union is  $\mathbb{R}$ . Next, notice that  $k \in I_0$  whereas, since  $g_{\theta_0, \theta_1}(\cdot)$  is increasing,  $I_-$  lays entirely to the left of  $I_0$ , that is,  $a < b$  when  $a \in I_-$  and  $b \in I_0$ ; similarly,  $I_+$  is located to the right of  $I_0$ . Recalling that  $k \in I_0$ , it follows that

$$t \in I_- \Rightarrow t < k, \quad \text{and} \quad t \in I_+ \Rightarrow t > k. \quad (4.6.4)$$

Finally, define the function  $\psi$  as follows:

$$\psi(\mathbf{x}) = \begin{cases} 1, & \text{if } T(\mathbf{x}) > k \\ \nu, & \text{if } T(\mathbf{x}) = k \\ 0, & \text{if } T(\mathbf{x}) < k \end{cases} \quad (4.6.5)$$

It will be verified that

$$\varphi_{k^*, \nu}^*(T(\mathbf{X})) = \varphi_{\tilde{k}, \psi}(\mathbf{X}).$$

this objective will be reached by analyzing the following three exhaustive cases:

**Case 1:**  $f(\mathbf{X}; \theta_1)/f(\mathbf{X}; \theta_0) > \tilde{k}$ .

In this context  $\varphi_{\tilde{k}, \psi}(\mathbf{X}) = 1$ , by (3.1.2). On the other hand, using (4.6.3) it follows that  $g_{\theta_0, \theta_1}(T(\mathbf{X})) > \tilde{k}$ ; in this case  $T(\mathbf{X}) \in I_+$ , an inclusion that implies that  $T(\mathbf{X}) > k$  (by 4.6.4), and then  $\varphi_{k^*, \nu}^*(T(\mathbf{X})) = 1$ ; see (4.6.2).

**Case 2:**  $f(\mathbf{X}; \theta_1)/f(\mathbf{X}; \theta_0) = \tilde{k}$ .

In this situation the specification of a Neyman-Pearson test yields that  $\varphi_{\tilde{k}, \psi}(\mathbf{X}) = \psi(\mathbf{X})$ , and then the specification of  $\psi$  in (4.6.5) leads to

$$\varphi_{\tilde{k}, \psi}(\mathbf{X}) = \begin{cases} 1, & \text{if } T(\mathbf{X}) > k \\ \nu, & \text{if } T(\mathbf{X}) = k \\ 0, & \text{if } T(\mathbf{X}) < k; \end{cases}$$

comparing this expression with (4.6.2) it follows that  $\varphi_{\tilde{k},\psi}(\mathbf{X}) = \varphi_{k,\nu}^*(\mathbf{X})$ .

**Case 3:**  $f(\mathbf{X}; \theta_1)/f(\mathbf{X}; \theta_0) < \tilde{k}$ .

In this context  $\varphi_{\tilde{k},\psi}(\mathbf{X}) = 0$ , by (3.1.2), whereas using (4.6.3) it follows that  $g_{\theta_0,\theta_1}(T(\mathbf{X})) < \tilde{k}$ ; therefore,  $T(\mathbf{X}) \in I_-$  and then  $T(\mathbf{X}) < k$  (by 4.6.4), and it follows that  $\varphi_{k,\nu}^*(T(\mathbf{X})) = 0$ , by (4.6.2).

In short it has been shown that, in any possible circumstance,  $\varphi_{k,\nu}^*(T(\mathbf{X})) = \varphi_{\tilde{k},\psi}(\mathbf{X})$ , establishing part (i). To verify part (ii) notice that the size of  $\tilde{\varphi}_{k,\nu}(\mathbf{X})$  is given by

$$E_{\theta_0}[\tilde{\varphi}_{k,\nu}(\mathbf{X})] = \nu P_{\theta_0}[T(\mathbf{X}) = k] + P_{\theta_0}[T(\mathbf{X}) > k]$$

To achieve the desired level  $\alpha$  it is sufficient to select

$$k = \min\{z \mid P_{\theta_0}[T > z] \leq \alpha\}$$

and

$$\nu = \begin{cases} 1, & \text{if } P_{\theta_0}[T = k] = 0 \\ \frac{\alpha - P_{\theta_0}[T > k]}{P_{\theta_0}[T = k]}, & \text{if } P_{\theta_0}[T = k] > 0; \end{cases}$$

notice that  $k$  and  $\nu$  depend only on  $\theta_0$ . □

The previous result implies that certain testing problems involving composite hypothesis admit a most powerful test.

**Theorem 4.6.1.** Let  $\{f(\mathbf{x}; \theta)\}_{\theta \in \Theta}$  be a collection of densities or probability functions with monotone likelihood ratio, and let  $T$  be the corresponding test statistic. Given  $\alpha \in (0, 1)$  select  $k$  and  $\nu$  such that the test  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  satisfies

$$E_{\theta_0}[\varphi_{k,\nu}^*(T(\mathbf{X}))] = \alpha,$$

where

$$\varphi_{k,\nu}^*(T(\mathbf{X})) = \begin{cases} 1, & \text{if } T(\mathbf{X}) > k \\ \nu, & \text{if } T(\mathbf{X}) = k \\ 0, & \text{if } T(\mathbf{X}) < k. \end{cases}$$

In this case,  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  is a uniformly most powerful test for each one of the following testing problems:

- (i)  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$ , where  $\theta_1 > \theta_0$ ;
- (ii)  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ ;
- (iii)  $\mathcal{H}_0: \theta \leq \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ .

**Proof.** (i) By Lemma 4.6.1 the critical function test  $\varphi_{k,\nu}^*(T(\mathbf{x}))$  is a Neyman-Pearson test for  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$  at level  $\alpha$ , and then it is most powerful, by Theorem 3.1.1.

(ii) Since  $\varphi_{k,\nu}^*(T(\mathbf{x}))$  is most powerful with level  $\alpha$  for  $\mathcal{H}_0:\theta = \theta_0$  versus  $\mathcal{H}_1:\theta = \theta_1$ , where  $\theta_1 > \theta_0$  is arbitrary, the test is *uniformly most powerful* for testing  $\mathcal{H}_0:\theta = \theta_0$  versus  $\mathcal{H}_1:\theta > \theta_0$  at level  $\alpha$ ,

(iii) The critical function  $\varphi_{k,\nu}^*(T(\mathbf{x}))$  is a Neyman-Pearson test for  $\mathcal{H}_0:\theta = \tilde{\theta}_0$  versus  $\mathcal{H}_1:\theta = \tilde{\theta}_1$ , where the points  $\tilde{\theta}_0$  and  $\tilde{\theta}_1$  with  $\tilde{\theta}_1 > \tilde{\theta}_0$  are arbitrary; since the test is unbiased, by Corollary 4.2.1, it follows that  $E_{\tilde{\theta}_0}[\varphi_{k,\nu}^*(T(\mathbf{X}))] \leq E_{\tilde{\theta}_1}[\varphi_{k,\nu}^*(T(\mathbf{X}))]$ , so that the power function of the test is increasing. Hence,

$$\max_{\theta \leq \theta_0} E_{\theta}[\varphi_{k,\nu}^*(T(\mathbf{X}))] = E_{\theta_0}[\varphi_{k,\nu}^*(T(\mathbf{X}))],$$

so that  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  has size  $\alpha$  when the null hypothesis is  $\mathcal{H}_0:\theta \leq \theta_0$ . Suppose now that  $\tilde{\varphi}$  is an arbitrary test with size  $\alpha$  when the null hypothesis is  $\mathcal{H}_0:\theta \leq \theta_0$ , that is,

$$\max_{\theta \leq \theta_0} E_{\theta}[\tilde{\varphi}(\mathbf{X})] \leq \alpha. \quad (4.6.6)$$

In this case  $E_{\theta_0}[\tilde{\varphi}(\mathbf{X})] \leq \alpha$ , and the fact, established in part (ii), that  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  is a most powerful test with size  $\alpha$  for the problem  $\mathcal{H}_0:\theta = \theta_0$  versus  $\mathcal{H}_1:\theta > \theta_0$ , yields that

$$E_{\theta}[\tilde{\varphi}(\mathbf{X})] \leq E_{\theta}[\varphi_{k,\nu}^*(T(\mathbf{X}))], \quad \theta > \theta_0;$$

since this relation holds for every test satisfying (4.6.6), it follows that  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  is a level- $\alpha$  *uniformly most powerful* test for the problem  $\mathcal{H}_0:\theta \leq \theta_0$  versus  $\mathcal{H}_1:\theta > \theta_0$ .  $\square$

An argument similar to the one used to establish the previous theorem yields the following result.

**Theorem 4.6.2.** Let  $\{f(\mathbf{x};\theta)\}_{\theta \in \Theta}$  be a collection of densities or probability functions with monotone likelihood ratio, and let  $T$  be the corresponding test statistic. Given  $\alpha \in (0, 1)$  select  $k$  and  $\nu$  such that the test  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  satisfies

$$E_{\theta_0}[\varphi_{k,\nu}^*(T(\mathbf{X}))] = \alpha,$$

where

$$\varphi_{k,\nu}^*(T(\mathbf{X})) = \begin{cases} 1, & \text{if } T(\mathbf{X}) < k \\ \nu, & \text{if } T(\mathbf{X}) = k \\ 0, & \text{if } T(\mathbf{X}) > k. \end{cases}$$

In this case,  $\varphi_{k,\nu}^*(T(\mathbf{X}))$  is a uniformly most powerful test for each one of the following testing problems:

- (i)  $\mathcal{H}_0:\theta = \theta_0$  versus  $\mathcal{H}_1:\theta = \theta_1$ , where  $\theta_1 < \theta_0$ ;
- (ii)  $\mathcal{H}_0:\theta = \theta_0$  versus  $\mathcal{H}_1:\theta < \theta_0$ ;

(iii)  $\mathcal{H}_0: \theta \geq \theta_0$  versus  $\mathcal{H}_1: \theta < \theta_0$ .

**Remark 4.6.1.** It is convenient to summarize the content of the preceding theorems: If the statistical model  $\mathbf{X} \sim P_\theta$ ,  $\theta \in \Theta$  has monotone likelihood ratio with test statistic  $T = T(\mathbf{X})$ , then several testing problems have *uniformly most powerful* tests at a given level  $\alpha$ . Those problems include the following:

(i)  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$ , where  $\theta_1 < \theta_0$ ;

(ii)  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta < \theta_0$ ;

(iii)  $\mathcal{H}_0: \theta \geq \theta_0$  versus  $\mathcal{H}_1: \theta < \theta_0$ .

(i)'  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta = \theta_1$ , where  $\theta_1 > \theta_0$ ;

(ii)'  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ ;

(iii)'  $\mathcal{H}_0: \theta \leq \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ .

In the first group, all the alternative values are located to the left of a parameter corresponding to the null hypothesis, whereas in the second group the alternative parameters are located to the right of any parameter satisfying the condition stipulated by the null hypothesis. The above testing problems are called *unilateral*, and the most powerful test at a given level  $\alpha \in (0, 1)$  is constructed as follows:

(1) The null hypothesis is rejected if  $T(\mathbf{X}) > k$  or  $T(\mathbf{X}) < k$  when the alternative values are located to the right or to the left of the null parameters, respectively, and

(2) The test randomizes the decision when  $T(\mathbf{X}) = k$  is observed with rejection probability equal to a constant  $\nu \in [0, 1]$ ;

(3) The values of  $k$  and  $\nu \in [0, 1]$  are determined in such a way that

$$P_{\theta_0}[T(\mathbf{X}) > k] + \nu P_{\theta_0}[T(\mathbf{X}) = k] = \alpha,$$

for alternative values of the parameter located to the right of  $\theta_0$ , or

$$P_{\theta_0}[T(\mathbf{X}) < k] + \nu P_{\theta_0}[T(\mathbf{X}) = k] = \alpha$$

when the alternative values of the parameter are located to the left of  $\theta_0$ ; in the former case  $k$  is the smallest of all the numbers  $z$  such that  $P_{\theta_0}[T(\mathbf{X}) > z] \leq \alpha$ , whereas in the second case  $k$  is the largest of all numbers  $z$  satisfying  $P_{\theta_0}[T(\mathbf{X}) < z] \leq \alpha$ . Notice that if  $T$  has a continuous distribution then  $P_{\theta_0}[T(\mathbf{X}) = k] = 0$ , and  $k$  is a number satisfying

$$P_{\theta_0}[T(\mathbf{X}) < k] = \alpha \quad \text{or} \quad P_{\theta_0}[T(\mathbf{X}) > k] = \alpha$$

for alternative values located to the left or to the right of  $\theta_0$ , respectively, whereas the selection of  $\nu$  is not important and  $\nu = 1$  is a common choice.  $\square$

## 4.7. Applications

The above construction will be illustrated below.

**Example 4.7.1.** (i) Suppose the  $\mathbf{X}$  is a sample of size 10 of the *Uniform*(0,  $\theta$ ) distribution, where  $\theta > 0$ . In Example 4.5.1 it was shown that the family of densities of the observation vector  $\mathbf{X}$  has monotone likelihood ratio with test statistic given by

$$T = \max X_i$$

Consider the following testing problems:

(a)  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$

(b)  $\mathcal{H}_0: \theta \geq \theta_0$  versus  $\mathcal{H}_1: \theta < \theta_0$

In each case, the problem is to construct the most powerful test of size  $\alpha$ .

• (a) In this context the alternative values are larger than  $\theta_0$ , so that the rejection region is  $\max X_i > k$ ; since  $T = \max X_i$  has a continuous distribution,  $k$  is selected in such a way that  $P_{\theta_0}[\max X_i > k] = \alpha$ . To find  $k$  it is necessary to use the distribution of  $T = \max X_i$  under the condition that  $\theta_0$  is the true parameter value. In that case, the density of  $T = \max X_i$  is given by

$$f_T(t) = \frac{nt^{n-1}}{\theta_0^n} I_{(0, \theta_0)}(t)$$

and then

$$P_{\theta_0}[\max X_i > k] = \int_k^{\theta_0} \frac{nt^{n-1}}{\theta_0^n} dt = 1 - \left(\frac{k}{\theta_0}\right)^n$$

Thus,  $k$  satisfies the following equation:

$$\alpha = 1 - \left(\frac{k}{\theta_0}\right)^n,$$

whose solution is

$$k = \theta_0(1 - \alpha)^{1/n}$$

and then, selecting  $\nu = 1$ , the desired test has the following critical function:

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \max x_i > \theta_0(1 - \alpha)^{1/n} \\ 0, & \text{otherwise.} \end{cases}$$

• (b) In this case the alternative values are located to the left of  $\theta_0$ , and then the rejection region is determined by the relation  $\max X_i < k$ , where  $k$  satisfies

$$P_{\theta_0}[\max X_i < k] = \alpha$$

Using the above expression for the density of  $\max X_i$ , it follows that

$$\alpha = P_{\theta_0}[\max X_i < k] = \int_0^k \frac{nt^{n-1}}{\theta_0^n} dt = \frac{k^n}{\theta_0^n}.$$

so that

$$k = \theta_0 \alpha^{1/n};$$

taking  $\nu = 1$ , the most powerful test is specified by

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \max x_i < \theta_0 \alpha^{1/n} \\ 0, & \text{otherwise.} \end{cases}$$

(ii) Let  $\mathbf{X}$  be a sample of size  $n$  of the translated exponential density

$$f(x; \theta) = e^{-(x-\theta)} I_{(\theta, \infty)}(x)$$

where  $\theta \in \mathbb{R}$ . It was verified in Example 4.5.1 the the family of possible distributions of  $\mathbf{X}$  has monotone likelihood ratio with test statistic  $T = \min X_i$ . With this information, construct most powerful test of size  $\alpha \in (0, 1)$  for each one of the following testing problems.

(a)  $\mathcal{H}_0: \theta \leq \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$

(b)  $\mathcal{H}_0: \theta = \theta_0$  versus  $\mathcal{H}_1: \theta < \theta_0$

• (a) In this case the alternative values are larger than  $\theta_0$ , so that the rejection region is  $T = \min X_i > k$ ; since  $\min X_i$  has a continuous distribution,  $k$  is selected in such a way that  $P_{\theta_0}[\min X_i > k] = \alpha$ . To determine  $k$ , recall that, when  $\theta_0$  is the true parameter value,  $n[\min X_i - \theta_0] \sim \text{Exponential}(1)$ , that is,

$$n[(\min X_i) - \theta_0] \quad \text{has density} \quad e^{-x} I_{(0, \infty)}(x).$$

Therefore,

$$P_{\theta_0}[\min X_i > k] = P_{\theta_0}[n[(\min X_i) - \theta_0] > n(k - \theta_0)] = \int_{n(k-\theta_0)}^{\infty} e^{-x} dx = e^{-n(k-\theta_0)}$$

and then the equality  $P_{\theta_0}[\min X_i > k] = \alpha$  is equivalent to

$$e^{-n(k-\theta_0)} = \alpha,$$

so that

$$k = \theta_0 - \frac{\log(\alpha)}{n}$$

and, setting  $\nu = 1$ , the most powerful test is given by the following critical function:

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \min x_i \geq \theta_0 - \log(\alpha)/n, \\ 0, & \text{otherwise.} \end{cases}$$

- (b) The alternative values are less than  $\theta_0$ , so that the rejection region is determined by the relation  $\min X_i < k$ , where  $k$  satisfies

$$P_{\theta_0}[\min X_i < k] = \alpha$$

Using the expression for the density of  $\max X_i$ , it follows that

$$\alpha = P_{\theta_0}[n[(\min X_i) - \theta_0] < n(k - \theta_0)] = \int_0^{n(k-\theta_0)} e^{-x} dx = 1 - e^{-n(k-\theta_0)}$$

so that

$$k = \theta_0 - \frac{\log(1 - \alpha)}{n};$$

taking  $\nu = 1$ , that the test specified by

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \min x_i < \theta_0 - \log(1 - \alpha)/n \\ 0, & \text{otherwise.} \end{cases}$$

is most powerful with level  $\alpha$ .

#### 4.8. Additional Examples

In this section complementary examples illustrating the result previously established will be presented, including both continuous and discrete statistical models.

**Exercise 4.8.1.** (a) Let  $X_1, X_2, \dots, X_5$  be a random sample of size 5 from the Poisson distribution with mean  $\lambda$ . Use the Neyman-Pearson Lemma to find a most powerful test for  $\mathcal{H}_0: \lambda = 1$  versus  $\mathcal{H}_1: \lambda = 2$  using a significance level  $\alpha = 0.05$ . Find the power function of this test.

(b) Let  $X_1, X_2, \dots, X_n$  be a random sample of the *Poisson*( $\lambda$ ) distribution. Show explicitly that any Neyman-Pearson test for

$$\mathcal{H}_0: \lambda = \lambda_0 \quad \text{versus} \quad \mathcal{H}_1: \lambda = \lambda_1 \tag{4.8.1}$$

specified in (3.1.2) with the constant  $\psi$  given in (3.2.13), is based on  $S = X_1 + X_2 + \dots + X_n$ , which is the minimal sufficient statistic for  $\lambda$ ; also show that, if  $\lambda_0$  is fixed and  $\lambda_1 > \lambda_0$  is arbitrary, then such a Neyman-Pearson test of a given level  $\alpha$  for the problem (4.8.1) depends only on  $\lambda_0$ .

(c) Generalize the test in part (b) to find a most powerful test for  $\mathcal{H}_0: \lambda = \lambda_0$  versus  $\mathcal{H}_1: \lambda > \lambda_0$ ; also find an expression for the power function of test and show directly that it is unbiased.

**Solution.** The probability function of a random sample  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  of the Poisson distribution with mean  $\lambda$  is given by

$$f(\mathbf{x}; \lambda) = \prod_{i=1}^n e^{-\lambda} \frac{\lambda^{x_i}}{x_i!} = e^{-n\lambda} \frac{\lambda^{\sum_{i=1}^n x_i}}{x_1! x_2! \cdots x_n!}$$

where the components of  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  are nonnegative integers, a condition that is assumed from this point onwards. It follows that for  $\lambda_0, \lambda_1 > 0$

$$\frac{f(\mathbf{x}; \lambda_1)}{f(\mathbf{x}; \lambda_0)} = \frac{e^{-n\lambda_1} \frac{\lambda_1^{\sum_{i=1}^n x_i}}{x_1! x_2! \cdots x_n!}}{e^{-n\lambda_0} \frac{\lambda_0^{\sum_{i=1}^n x_i}}{x_1! x_2! \cdots x_n!}} = e^{-n(\lambda_1 - \lambda_0)} \left( \frac{\lambda_1}{\lambda_0} \right)^{\sum_{i=1}^n x_i}. \quad (4.8.2)$$

(a) When the sample size  $n$  is equal to 5, a most powerful test with level  $\alpha = .05$  for  $\mathcal{H}_0: \lambda = 1$  versus  $\mathcal{H}_1: \lambda = 2$  is determined as follows: Notice that

$$\frac{f(\mathbf{x}; \lambda_1)}{f(\mathbf{x}; \lambda_0)} = \frac{f(\mathbf{x}; 2)}{f(\mathbf{x}; 1)} = e^{-5(2-1)} \left( \frac{2}{1} \right)^{\sum_{i=1}^5 x_i} > \tilde{k}$$

is equivalent to

$$\sum_{i=1}^5 x_i > k$$

for a certain constant  $k$ , which must be selected as the smallest number such that, under  $\mathcal{H}_0$ , the probability of observing  $X_1 + X_2 + \cdots + X_5 > k$  does not exceed .05. To determine such a constant, recall that, when  $\lambda = 1$ ,  $X_1 + X_2 + \cdots + X_5 \sim \text{Poisson}(5)$ , and a table of this distribution is shown below.

$k$	$P[Y = k]$	$P[Y \leq k]$	$P[Y > k]$
0	0.0067	0.0067	0.9933
1	0.0337	0.0404	0.9596
2	0.0842	0.1247	0.8753
3	0.1404	0.2650	0.7350
4	0.1755	0.4405	0.5595
5	0.1755	0.6160	0.3840
6	0.1462	0.7622	0.2378
7	0.1044	0.8666	0.1334
8	0.0653	0.9319	0.0681
9	0.0363	0.9682	0.0318
10	0.0181	0.9863	0.0137
11	0.0082	0.9945	0.0055
12	0.0034	0.9980	0.0020
13	0.0013	0.9993	0.0007
14	0.0005	0.9998	0.0002
15	0.0002	0.9999	0.0001

This table shows that

$$P[X_1 + X_2 + \cdots + X_5 > 9] = .0318$$

and  $P[X_1 + X_2 + \cdots + X_5 > 8] = .0681$ , and then  $k = 9$ . Now, the constant  $\psi$  such that

$$P_1[X_1 + X_2 + \cdots + X_5 > 9] + \psi P_1[X_1 + X_2 + \cdots + X_5 = 9] = \alpha = .05$$

will be determined; this equation is equivalent to  $.0318 + \psi(.0363) = .05$ , so that  $\psi = .5014$ .

The Neyman-Pearson test of level .05 described (3.2.13) is

$$\varphi_{9,.5014}(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^5 x_i > 9, \\ .5014, & \text{if } \sum_{i=1}^5 x_i = 9, \\ 0, & \text{if } \sum_{i=1}^5 x_i < 9; \end{cases}$$

this is a most powerful test of level .05 for testing the null hypothesis that  $\lambda = 1$  versus the alternative  $\lambda = 2$ .

(b) Relation (4.8.2) shows that  $f(\mathbf{x}; \lambda_1)/f(\mathbf{x}; \lambda_0)$  depends only on  $S = X_1 + X_2 + \cdots + X_n$ , so that the regions  $\{\mathbf{x} | f(\mathbf{x}; \lambda_1)/f(\mathbf{x}; \lambda_0) > k\}$  and  $\{\mathbf{x} | f(\mathbf{x}; \lambda_1)/f(\mathbf{x}; \lambda_0) = k\}$  are specified in terms of  $S$ . It follows that the critical function  $\varphi_{k,\psi}$  in (3.1.2), with  $\psi$  equal a constant as specified in (3.2.13), is a function of  $S$ . Suppose now that  $\lambda_1 > \lambda_0$ . In this case, (4.8.2) shows that  $f(\mathbf{x}; \lambda_1)/f(\mathbf{x}; \lambda_0)$  is a *strictly increasing function* of  $S$ , so that the relations  $f(\mathbf{x}; \lambda_1)/f(\mathbf{x}; \lambda_0) > \tilde{k}$  and  $f(\mathbf{x}; \lambda_1)/f(\mathbf{x}; \lambda_0) = \tilde{k}$  for a given nonnegative number  $\tilde{k}$  are equivalent to  $S > k$  and  $S = k$  for a certain constant  $k \geq 0$ , respectively. To construct the Neyman-Pearson test with level  $\alpha$  the number  $k$  is selected as the minimum value that satisfies the condition  $P_{\lambda_0}[S > k] \leq \alpha$ ; if  $k^*$  is such a value, the constant  $\psi^*$  is chosen in such a way that  $P_{\lambda_0}[S > k^*] + \psi^* P_{\lambda_0}[S = k^*] = \alpha$ , and the Neyman-Pearson test  $\varphi_{k^*,\psi^*}$  is most powerful for the problem (4.8.1). Notice now two aspects of this construction: (i) The condition  $\lambda_1 > \lambda_0$  implied that the rejection region is of the form  $\{\mathbf{x} | S(\mathbf{x}) > k\}$ , whereas (ii) the specification of the appropriate constants  $k^*$  and  $\psi^*$  depended only on  $\lambda_0$ . Therefore, as soon as  $\lambda_1 > \lambda_0$ , the most powerful test for (4.8.2), depends only on  $\lambda_0$ .

(c) The test  $\varphi_{k^*,\psi^*}$  of size  $\alpha$  is uniformly most powerful for  $\mathcal{H}_0: \lambda = \lambda_0$  versus  $\mathcal{H}_1: \lambda > \lambda_0$ . Indeed, let  $\varphi$  be a test of size  $\alpha$  for this problem. In this case  $E_{\lambda_0}[\varphi(\mathbf{X})] = \alpha$ , and then  $\varphi$  is also a test of size  $\alpha$  for  $\mathcal{H}_0: \lambda = \lambda_0$  versus  $\mathcal{H}_1: \lambda = \lambda_1$  for every  $\lambda_1 > \lambda_0$ ; since  $\varphi_{k^*,\psi^*}$  is a most powerful test of size  $\alpha$  for this last problem, it follows that

$$E_{\lambda_1}[\varphi_{k^*,\psi^*}(\mathbf{X})] \geq E_{\lambda_1}[\varphi(\mathbf{X})];$$

since this relation holds for every  $\lambda_1 > \lambda_0$ , it follows that  $\varphi_{k^*,\psi^*}$  is a uniformly most powerful test of size  $\alpha$  for  $\mathcal{H}_0: \lambda = \lambda_0$  versus  $\mathcal{H}_1: \lambda > \lambda_0$ .  $\square$

**Exercise 4.8.2.** In Example 3.4.1 a sample  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  of the  $\mathcal{N}(\mu, \sigma^2)$  distribution was considered and, assuming that  $\sigma^2$  is known, for  $\mu_1 > \mu_0$  the testing problem

$$\mathcal{H}_0: \mu = \mu_0 \quad \text{versus} \quad \mathcal{H}_1: \mu = \mu_1,$$

was considered. It was shown that the Neyman-Pearson test with level  $\alpha \in (0, 1)$  is given by

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \bar{\mathbf{x}} > \mu_0 + z_{1-\alpha}\sigma/\sqrt{n}, \\ 0, & \text{otherwise.} \end{cases} \quad (4.8.3)$$

(a) Show that the power function  $\pi(\mu) = E_\mu[\varphi(\mathbf{x})]$  of this test is strictly increasing.

(b) Prove that the test (4.8.3) is level  $\alpha$  uniformly most powerful for each one of the following testing problems:

(i)  $\mathcal{H}_0: \mu = \mu_0$  versus  $\mathcal{H}_1: \mu > \mu_0$ ;

(ii)  $\mathcal{H}_0: \mu \leq \mu_0$  versus  $\mathcal{H}_1: \mu > \mu_0$ ;

**Solution.** If  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a sample of the  $\mathcal{N}(\mu, \sigma^2)$  distribution, then

$$\sqrt{n} \frac{\bar{\mathbf{X}} - \mu}{\sigma} \sim \mathcal{N}(0, 1).$$

(a) Notice that  $\pi(\mu) = E_\mu[\varphi(\mathbf{X})] = P_\mu[\bar{\mathbf{X}} > \mu_0 + z_{1-\alpha}\sigma/\sqrt{n}]$ , and then above display yields that

$$\pi(\mu) = P_\mu \left[ \sqrt{n} \frac{\bar{\mathbf{X}} - \mu}{\sigma} > \sqrt{n} \frac{\mu_0 - \mu}{\sigma} + z_{1-\alpha} \right] = 1 - \Phi \left( \sqrt{n} \frac{\mu_0 - \mu}{\sigma} + z_{1-\alpha} \right),$$

where  $\Phi$  is the cumulative distribution function of the standard normal distribution; it follows that  $\pi(\cdot)$  is strictly increasing, since so is  $\Phi(\cdot)$ .

(b) (i) Recall that  $\varphi$  is a level  $\alpha$  most powerful test for  $\mathcal{H}_0: \mu = \mu_0$  versus  $\mathcal{H}_1: \mu = \mu_1$ . where  $\mu_1 > \mu_0$  is arbitrary. Thus, if  $\tilde{\varphi}$  is a critical function such that  $\pi_{\tilde{\varphi}}(\mu_0) = E_{\tilde{\varphi}}[\tilde{\varphi}(\mathbf{X})] \leq \alpha$ , then  $\pi_\varphi(\mu_1) \geq \pi_{\tilde{\varphi}}(\mu_1)$  for any  $\mu_1 > \mu_0$  and it follows that  $\varphi$  is a level  $\alpha$  *uniformly most powerful* test for  $\mathcal{H}_0: \mu = \mu_0$  versus  $\mathcal{H}_1: \mu > \mu_0$ .

(ii) Next, consider the testing problem  $\mathcal{H}_0: \mu \leq \mu_0$  versus  $\mathcal{H}_1: \mu > \mu_0$  and notice that, since  $\pi_\varphi(\cdot)$  is monotone increasing,  $\pi_\varphi(\mu) \leq \pi_\varphi(\mu_0) = \alpha$  for every  $\mu < \mu_0$ , so that  $\varphi$  has size  $\alpha$  when the null hypothesis is  $\mathcal{H}_0: \mu \leq \mu_0$ . To conclude, let  $\tilde{\varphi}$  be a test of size at most  $\alpha$ , that is,

$$\pi_{\tilde{\varphi}}(\mu) \leq \alpha, \quad \mu \leq \mu_0.$$

In particular,  $\pi_{\tilde{\varphi}}(\mu_0) \leq \alpha$ , that is,  $\tilde{\varphi}$  has size at most  $\alpha$  when the null hypothesis is  $\mathcal{H}_0: \mu = \mu_0$ , and the above conclusion (i) yields that  $\pi_\varphi(\mu) \geq \pi_{\tilde{\varphi}}(\mu)$  for every  $\mu > \mu_0$ , showing that  $\varphi$  is a level  $\alpha$  uniformly most powerful test for the problem  $\mathcal{H}_0: \mu \leq \mu_0$  versus  $\mathcal{H}_1: \mu > \mu_0$ .  $\square$

**Exercise 4.8.3.** Let  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be a sample of the  $\mathcal{N}(\mu, \sigma^2)$ , where  $\sigma^2 > 0$  and  $\mu$  is known.

(a) Using the uniqueness property of a Neyman-Pearson test, verify directly that there is no uniformly most powerful  $\alpha$ -level test for testing  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 \neq \sigma_0^2$ .

(b) Show that the power function of a Neyman-Pearson test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$ , where  $\sigma_1^2 > \sigma_0^2$ , is a function of  $c = \sigma_1^2/\sigma_0^2$ .

**Solution.** Recalling that  $\mu$  is known, the density of the sample  $\mathbf{X}$  when  $\sigma^2 > 0$  is the parameter value is given by

$$f(\mathbf{x}; \sigma^2) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(x_i - \mu)^2/(2\sigma^2)} = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2/(2\sigma^2)} \quad (4.8.4)$$

Therefore,

$$\begin{aligned} \frac{f(\mathbf{x}; \sigma_1^2)}{f(\mathbf{x}; \sigma_0^2)} &= \frac{\frac{1}{(2\pi\sigma_1^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2/(2\sigma_1^2)}}{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2/(2\sigma_0^2)}} \\ &= \frac{\sigma_0^2}{\sigma_1^2} e^{-[\sigma_0^2/\sigma_1^2 - 1] \sum_{i=1}^n (x_i - \mu)^2/(2\sigma_0^2)} \end{aligned} \quad (4.8.5)$$

From this expression it follows that

(i) If  $\sigma_1^2 > \sigma_0^2$ , then  $f(\mathbf{x}; \sigma_1^2)/f(\mathbf{x}; \sigma_0^2)$  is a strictly increasing function of  $\sum_{i=1}^n (x_i - \mu)^2$ , so that, given a nonnegative constant  $\tilde{k}$ ,

$$\frac{f(\mathbf{x}; \sigma_1^2)}{f(\mathbf{x}; \sigma_0^2)} > \tilde{k} \iff \sum_{i=1}^n (x_i - \mu)^2 > k$$

for a certain constant  $k$ . It follows that a Neyman-Pearson test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  where  $\sigma_1^2 > \sigma_0^2$  is given by

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n (x_i - \mu)^2 \geq k \\ 0, & \text{otherwise.} \end{cases}$$

To achieve a desired significance level  $\alpha$ , the constant  $k$  must be selected in such a way that

$$P_{\sigma_0^2} \left[ \sum_{i=1}^n (X_i - \mu)^2 > k \right] = \alpha;$$

since  $\sum_{i=1}^n (X_i - \mu)^2/\sigma_0^2 \sim \chi_n^2$  when  $\sigma_0^2$  is the true parameter value, it follows that  $k = \sigma_0^2 \chi_{n,1-\alpha}^2$ , where  $\chi_{n,1-\alpha}^2$  is the percentile of order  $1 - \alpha$  of the chi squared distribution with  $n$  degrees of freedom. In short, the Neyman-Pearson  $\alpha$ -level most powerful test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  is given by

$$\tilde{\varphi}(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n (x_i - \mu)^2 \geq \sigma_0^2 \chi_{n,1-\alpha}^2 \\ 0, & \text{otherwise.} \end{cases} \quad (4.8.6)$$

Notice that this test is (essentially) unique, since  $\sum_{i=1}^n (X_i - \mu)^2$  has a continuous distribution.

(ii) If  $\sigma_1^2 < \sigma_0^2$ , then (4.8.5) yields that  $f(\mathbf{x}; \sigma_1^2)/f(\mathbf{x}; \sigma_0^2)$  is a strictly decreasing function of  $\sum_{i=1}^n (x_i - \mu)^2$ ; thus, given a nonnegative constant  $\tilde{k}$ ,

$$\frac{f(\mathbf{x}; \sigma_1^2)}{f(\mathbf{x}; \sigma_0^2)} > \tilde{k} \iff \sum_{i=1}^n (x_i - \mu)^2 < k$$

for a certain constant  $k$ , and then a Neyman-Pearson test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  where  $\sigma_1^2 < \sigma_0^2$  is given by

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n (x_i - \mu)^2 < k \\ 0, & \text{otherwise} \end{cases}$$

and, to achieve a significance level  $\alpha$ , the constant  $k$  must be selected in such a way that

$$P_{\sigma_0^2} \left[ \sum_{i=1}^n (X_i - \mu)^2 < k \right] = \alpha;$$

thus, since  $\sum_{i=1}^n (X_i - \mu)^2 / \sigma_0^2 \sim \chi_n^2$  under the condition  $\sigma^2 = \sigma_0^2$ , it follows that  $k = \sigma_0^2 \chi_{n,\alpha}^2$ , where  $\chi_{n,\alpha}^2$  is the percentil of order  $\alpha$  of the chi squared distribution with  $n$  degrees of freedom. Summarizing, the Neyman-Pearson  $\alpha$ -level most powerful test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  is specified by

$$\hat{\varphi}(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n (x_i - \mu)^2 \leq \sigma_0^2 \chi_{n,\alpha}^2 \\ 0, & \text{otherwise;} \end{cases} \quad (4.8.7)$$

as before, since  $\sum_{i=1}^n (X_i - \mu)^2$  has a continuous distribution, this test is (essentially) unique.

(a) The argument is by contradiction. Suppose that  $\varphi$  is an  $\alpha$ -level uniformly most powerful test for

$$\mathcal{H}_0: \sigma^2 = \sigma_2^2 \quad \text{versus} \quad \mathcal{H}_1: \sigma^2 \neq \sigma_1^2 \quad (4.8.8)$$

In this case  $\varphi$  is also a level  $\alpha$  most powerful test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  and the argument (i) above shows that

$$\varphi = \tilde{\varphi}.$$

Similarly, when  $\sigma_1^2 < \sigma_0^2$ ,  $\varphi$  is also a level- $\alpha$  most powerful test for  $\mathcal{H}_0: \sigma^2 = \sigma_2^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  and the the above argument (ii) shows that

$$\varphi = \tilde{\tilde{\varphi}},$$

a relation that together with the previous display yields that  $\tilde{\varphi} = \tilde{\tilde{\varphi}}$ ; this equality is a contradiction, since the tests  $\tilde{\varphi}$  and  $\tilde{\tilde{\varphi}}$  do not coincide. Consequently, a most powerful test  $\varphi$  of level  $\alpha$  for the testing problem (4.8.8) does not exist.

(b) As already noted in the argument (i) presented above, when  $\sigma_1^2 > \sigma_0$  the test  $\tilde{\varphi}$  in (4.8.6) has size  $\alpha$  and is most powerful for the problem  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$ ; since  $\sigma_1^2 > \sigma_0^2$  is arbitrary, it follows that  $\tilde{\varphi}$  is *uniformly most powerful* for the problem  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 > \sigma_0^2$ . The corresponding power function is

$$\pi_{\tilde{\varphi}}(\sigma^2) = P_{\sigma^2} \left[ \sum_{i=1}^n (X_i - \mu)^2 > \sigma_0^2 \chi_{n,1-\alpha} \right]$$

and, using that  $\sum_{i=1}^n (X_i - \mu)^2 / \sigma^2 \sim \chi_n^2$  when  $\sigma^2$  is the true parameter value, it follows that

$$\begin{aligned} \pi_{\tilde{\varphi}}(\sigma^2) &= P_{\sigma^2} \left[ \frac{\sum_{i=1}^n (X_i - \mu)^2}{\sigma^2} > \frac{\sigma_0^2}{\sigma^2} \chi_{n,1-\alpha} \right] \\ &= \int_{(\sigma_0^2/\sigma^2)\chi_{n,1-\alpha}}^{\infty} \frac{1}{2^{n/2}\Gamma(n/2)} x^{n/2-1} e^{-x/2} dx \\ &= 1 - G_n((\sigma_0^2/\sigma^2)\chi_{n,1-\alpha}), \end{aligned}$$

where  $G_n(\cdot)$  is the cumulative distribution function of the  $\chi_n^2$  distribution, showing that  $\pi_{\tilde{\varphi}}$  is a function of  $\sigma_0^2/\sigma^2$ .  $\square$

**Exercise 4.8.4.** Based on a sample size of size  $n$  from a normal population with known mean  $\mu$  and unknown variance  $\sigma^2$ , it is desired to test  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 > \sigma_0^2$ . Use the idea of the quotient of maximum likelihoods to determine a uniformly most powerful test for this problem, and determine the power function.

**Solution.** Recall that  $\mu$  is known and notice that the density of the sample  $\mathbf{X}$  when  $\sigma^2 > 0$  is the parameter value is given by

$$f(\mathbf{x}; \sigma^2) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(x_i - \mu)^2 / (2\sigma^2)} = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2 / (2\sigma^2)} \quad (4.8.9)$$

Therefore,

$$\begin{aligned} \frac{f(\mathbf{x}; \sigma_1^2)}{f(\mathbf{x}; \sigma_0^2)} &= \frac{\frac{1}{(2\pi\sigma_1^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2 / (2\sigma_1^2)}}{\frac{1}{(2\pi\sigma_0^2)^{n/2}} e^{-\sum_{i=1}^n (x_i - \mu)^2 / (2\sigma_0^2)}} \\ &= \frac{\sigma_0^2}{\sigma_1^2} e^{[1 - \sigma_0^2/\sigma_1^2] \sum_{i=1}^n (x_i - \mu)^2 / (2\sigma_0^2)} \end{aligned} \quad (4.8.10)$$

This expression shows that, if  $\sigma_1^2 > \sigma_0^2$ , then  $f(\mathbf{x}; \sigma_1^2)/f(\mathbf{x}; \sigma_0^2)$  is a strictly increasing function of  $\sum_{i=1}^n (x_i - \mu)^2 / \sigma_0^2$ , so that, given a nonnegative constant  $\tilde{k}$ ,

$$\frac{f(\mathbf{x}; \sigma_1^2)}{f(\mathbf{x}; \sigma_0^2)} > \tilde{k} \iff \sum_{i=1}^n (x_i - \mu)^2 > k$$

for a certain constant  $k$ . It follows that a Neyman-Pearson test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  where  $\sigma_1^2 > \sigma_0^2$  is given by

$$\varphi(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n (x_i - \mu)^2 \geq k \\ 0, & \text{otherwise.} \end{cases}$$

To achieve a desired significance level  $\alpha$ , the constant  $k$  must be selected in such a way that

$$P_{\sigma_0^2} \left[ \sum_{i=1}^n (X_i - \mu)^2 > k \right] = \alpha;$$

since  $\sum_{i=1}^n (X_i - \mu)^2 / \sigma_0^2 \sim \chi_n^2$  when  $\sigma_0^2$  is the true parameter value, it follows that  $k = \sigma_0^2 \chi_{n,1-\alpha}^2$ , where  $\chi_{n,1-\alpha}^2$  is the percentile of order  $1 - \alpha$  of the chi squared distribution with  $n$  degrees of freedom. In short, the Neyman-Pearson  $\alpha$ -level most powerful test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_1: \sigma^2 = \sigma_1^2$  is given by

$$\tilde{\varphi}(\mathbf{x}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n (x_i - \mu)^2 \geq \sigma_0^2 \chi_{n,1-\alpha}^2 \\ 0, & \text{otherwise.} \end{cases} \quad (4.8.11)$$

Since this test does not depend on  $\sigma_1^2 > \sigma_0^2$ , it follows that it achieves that largest power at each  $\sigma_1^2 \in (\sigma_0^2, \infty)$ , so that  $\tilde{\varphi}$  is a level  $\alpha$  most powerful test for  $\mathcal{H}_0: \sigma^2 = \sigma_0^2$  versus  $\mathcal{H}_0: \sigma^2 > \sigma_0^2$ .  $\square$

**Exercise 4.8.5.** For each one of the following combinations of hypothesis and underlying distribution, find an  $\alpha$ -level uniformly most powerful test, if one exists. Assume a random sample  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  of size  $n$  is available for testing.

(i)  $\mathcal{H}_0: \theta \leq \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ ,  $f(x; \theta) = \theta x^{-(\theta+1)} I_{(1, \infty)}$ .

(ii)  $\mathcal{H}_0: \theta \geq \theta_0$  versus  $\mathcal{H}_1: \theta < \theta_0$ ,  $f(x; \theta) = \frac{1}{\theta} x^{(1-\theta)/\theta} I_{(0, 1)}$ .

Also, find the power function in each case.

**Solution.** (i) Notice that  $\mathbf{X}$  takes values in  $\mathcal{X} = (1, \infty)^n$ . For each  $\mathbf{x} \in \mathcal{X}$ , under the condition that  $\theta$  is the parameter value the density of  $\mathbf{X}$  is

$$f_{\mathbf{X}}(\mathbf{x}; \theta) = \theta^n \left( \prod_{i=1}^n x_i \right)^{-(\theta+1)}$$

For  $\theta_1 > \theta_0 > 0$ ,

$$\frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} = \frac{\theta_1^n \left( \prod_{i=1}^n x_i \right)^{-(\theta_1+1)}}{\theta_0^n \left( \prod_{i=1}^n x_i \right)^{-(\theta_0+1)}} = \left( \frac{\theta_1}{\theta_0} \right)^n \left( \prod_{i=1}^n x_i \right)^{-(\theta_1 - \theta_0)}$$

and then

$$\frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} = g_{\theta_0, \theta_1}(T(\mathbf{x}))$$

where

$$T(\mathbf{x}) = \left( \prod_{i=1}^n x_i \right)^{-1} \quad \text{and} \quad g_{\theta_0, \theta_1}(t) = \left( \frac{\theta_1}{\theta_0} \right)^n t^{\theta_1 - \theta_0};$$

observing that  $g_{\theta_0, \theta_1}(\cdot)$  is an increasing function, since  $\theta_1 > \theta_0$ , it follows that the family of possible densities of  $X$  has monotone likelihood ratio with test statistic given by  $T = (\prod_{i=1}^n x_i)^{-1}$ . It follows that there exists a *uniformly most powerful* test with level  $\alpha \in (0, 1)$  for the problem  $\mathcal{H}_0: \theta \leq \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ , which is given by

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } (\prod_{i=1}^n X_i)^{-1} \geq k, \\ 0, & \text{otherwise.} \end{cases}$$

or, equivalently,

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n X_i \leq -\log(k), \\ 0, & \text{otherwise.} \end{cases} \quad (4.8.12)$$

To attain the level  $\alpha$  the constant  $k$  must be selected in such a way that

$$\alpha = P_{\theta_0} \left[ \sum_{i=1}^n \log(X_i) \leq -\log(k) \right]. \quad (4.8.13)$$

To determine  $k$ , notice that if  $X$  has density  $f(x; \theta) = \theta x^{-(\theta+1)} I_{(1, \infty)}(x)$ , then  $Y = \log(X)$  takes values in  $(0, \infty)$  with probability 1,  $X = e^Y$ , and the density of  $Y$  is given by

$$\begin{aligned} f_Y(y; \theta) &= f(x; \theta) \left| \frac{dx}{dy} \right| \\ &= \theta x^{-(\theta+1)} I_{(1, \infty)}(x) \left| \frac{d e^y}{dy} \right| \\ &= \theta (e^y)^{-(\theta+1)} I_{(1, \infty)}(e^y) e^y \\ &= \theta e^{-\theta y} I_{(0, \infty)}(y), \end{aligned}$$

that is,  $Y = \log(X) \sim \text{Exponential}(\theta)$ , and then

$$2\theta \log(X) \sim \text{Exponential}(1/2) = \text{Gamma}(1, 1/2) = \chi_2^2.$$

It follows that, if  $X_1, X_2, \dots, X_n$  is a sample of the density  $f(x; \theta)$ , then

$$2\theta \sum_{i=1}^n \log(X_i) \sim \chi_{2n}^2.$$

Consequently, when  $\theta_0$  is the true parameter value,  $2\theta_0 \log(X_i)$ ,  $i = 1, 2, \dots, n$  is a sample of the  $\chi_2^2$  distribution, and then  $2\theta_0 \sum_{i=1}^n \log(X_i) \sim \chi_{2n}^2$ . Thus, from (4.8.13) it follows that

$$\alpha = P_{\theta_0} \left[ 2\theta_0 \sum_{i=1}^n \log(X_i) \leq -2\theta_0 \log(k) \right] = P_{\theta_0} [W \leq -2\theta_0 \log(k)]$$

where  $W \sim \chi_{2n}^2$ . Then,

$$-2\theta_0 \log(k) = \chi_{2n,\alpha}^2$$

where the right-hand side is the quantile of order  $\alpha$  of the  $\chi_{2n}^2$  distribution. Therefore

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n \log(X_i) \leq \chi_{2n,\alpha}^2 / [2\theta_0], \\ 0, & \text{otherwise,} \end{cases}$$

and the corresponding power function is

$$\begin{aligned} \pi(\theta) &= P_\theta \left[ \sum_{i=1}^n \log(X_i) \leq \frac{\chi_{2n,\alpha}^2}{2\theta_0} \right] \\ &= P_\theta \left[ 2\theta \sum_{i=1}^n \log(X_i) \leq \frac{\theta}{\theta_0} \chi_{2n,\alpha}^2 \right] \end{aligned}$$

and then

$$\pi(\theta) = P \left[ W \leq \frac{\theta}{\theta_0} \chi_{2n,\alpha}^2 \right], \quad \theta > 0,$$

where  $W \sim \chi_{2n}^2$ .

(ii) Observe that  $\mathbf{X}$  takes values in  $\mathcal{X} = (0, 1)^n$ . For each  $\mathbf{x} \in \mathcal{X}$ , under the condition that  $\theta$  is the parameter value the density of  $\mathbf{X}$  is

$$f_{\mathbf{X}}(\mathbf{x}; \theta) = \frac{1}{\theta^n} \left( \prod_{i=1}^n x_i \right)^{-(1-\theta)/\theta}$$

For  $\theta_1 > \theta_0 > 0$ ,

$$\frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} = \frac{\frac{1}{\theta_1^n} \left( \prod_{i=1}^n x_i \right)^{-(1-\theta_1)/\theta_1}}{\frac{1}{\theta_0^n} \left( \prod_{i=1}^n x_i \right)^{-(1-\theta_0)/\theta_0}} = \left( \frac{\theta_0}{\theta_1} \right)^n \left( \prod_{i=1}^n x_i \right)^{(1/\theta_0 - 1/\theta_1)}$$

and then

$$\frac{f_{\mathbf{X}}(\mathbf{x}; \theta_1)}{f_{\mathbf{X}}(\mathbf{x}; \theta_0)} = g_{\theta_0, \theta_1}(T(\mathbf{x}))$$

where

$$T(\mathbf{x}) = \prod_{i=1}^n x_i \quad \text{and} \quad g_{\theta_0, \theta_1}(t) = \left( \frac{\theta_0}{\theta_1} \right)^n t^{1/\theta_0 - 1/\theta_1};$$

using that since  $\theta_1 > \theta_0$  it follows that since  $1/\theta_0 > 1/\theta_1$ , and then  $g_{\theta_0, \theta_1}(\cdot)$  is an increasing function. Therefore, the family of possible densities of  $X$  has monotone likelihood ratio with test statistic given by  $T = \prod_{i=1}^n X_i$ , a fact that implies the existence of a *uniformly*

most powerful at each level  $\alpha \in (0, 1)$  for the problem  $\mathcal{H}_0: \theta \leq \theta_0$  versus  $\mathcal{H}_1: \theta > \theta_0$ . Such a test is given by

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \prod_{i=1}^n X_i \leq k, \\ 0, & \text{otherwise.} \end{cases}$$

or, equivalently,

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n \log(X_i) \leq \log(k), \\ 0, & \text{otherwise.} \end{cases} \quad (4.8.14)$$

To attain the level  $\alpha$  the constant  $k$  must be selected in such a way that

$$\alpha = P_{\theta_0} \left[ \sum_{i=1}^n \log(X_i) \leq \log(k) \right]. \quad (4.8.15)$$

To determine  $k$ , notice that if  $X$  has density  $f(x; \theta) = (1/\theta)x^{-(1-\theta)/\theta} I_{(0,1)}(x)$ , then  $Y = -\log(X)$  takes values in  $(0, \infty)$  with probability 1,  $X = e^{-Y}$ , and the density of  $Y$  is given by

$$\begin{aligned} f_Y(y; \theta) &= f(x; \theta) \left| \frac{dx}{dy} \right| \\ &= (1/\theta)x^{(1-\theta)/\theta} I_{(0,1)}(x) \left| \frac{d e^{-y}}{dy} \right| \\ &= (1/\theta)(e^{-y})^{-(1-\theta)/\theta} I_{(0,1)}(e^{-y}) e^{-y} \\ &= (1/\theta)e^{-y/\theta} I_{(0,\infty)}(y), \end{aligned}$$

that is,  $Y = -\log(X) \sim \text{Exponential}(\lambda = 1/\theta)$ , and then

$$\frac{-2}{\theta} \log(X) \sim \text{Exponential}(1/2) = \text{Gamma}(1, 1/2) = \chi_2^2.$$

It follows that, if  $X_1, X_2, \dots, X_n$  is a sample of the density  $f(x; \theta)$ , then

$$\frac{-2}{\theta} \sum_{i=1}^n \log(X_i) \sim \chi_{2n}^2.$$

Consequently, when  $\theta_0$  is the true parameter value,  $-(2/\theta_0) \log(X_i)$ ,  $i = 1, 2, \dots, n$  is a sample of the  $\chi_2^2$  distribution, and then  $-(2/\theta_0) \sum_{i=1}^n \log(X_i) \sim \chi_{2n}^2$ . Thus, from (4.8.15) it follows that

$$\begin{aligned} \alpha &= P_{\theta_0} \left[ \sum_{i=1}^n \log(X_i) \leq \log(k) \right] \\ &= P_{\theta_0} \left[ -\frac{2}{\theta_0} \sum_{i=1}^n \log(X_i) \geq -\frac{2}{\theta_0} \log(k) \right] \\ &= P_{\theta_0} [W \geq -\frac{2}{\theta_0} \log(k)] \end{aligned}$$

where  $W \sim \chi_{2n}^2$ . Then,

$$-\frac{2}{\theta_0} \log(k) = \chi_{2n, 1-\alpha}^2$$

where the right-hand side is the quantile of order  $1 - \alpha$  of the  $\chi_{2n}^2$  distribution. Therefore

$$\varphi(\mathbf{X}) = \begin{cases} 1, & \text{if } \sum_{i=1}^n \log(X_i) \leq -\frac{\theta_0}{2} \chi_{2n,1-\alpha}^2, \\ 0, & \text{otherwise,} \end{cases}$$

and the corresponding power function is

$$\begin{aligned} \pi(\theta) &= P_\theta \left[ \sum_{i=1}^n \log(X_i) \leq -\frac{\theta_0}{2} \chi_{2n,1-\alpha}^2 \right] \\ &= P_\theta \left[ -\frac{2}{\theta} \sum_{i=1}^n \log(X_i) \geq \frac{\theta_0}{\theta} \chi_{2n,1-\alpha}^2 \right] \end{aligned}$$

and then

$$\pi(\theta) = P \left[ W \geq \frac{\theta_0}{\theta} \chi_{2n,1-\alpha}^2 \right], \quad \theta > 0,$$

where  $W \sim \chi_{2n}^2$ . □

## References

- [1]. T. M. Apostol (1980), *Mathematical Analysis*, Addison Wesley, Reading, MA
- [2]. A. A. Borovkov (1999), *Mathematical Statistics*, Gordon and Breach, New York
- [3]. E. Dudewicz y S. Mishra (1998). *Mathematical Statistics*, Wiley, New York.
- [4]. W. Fulks (1980), *Cálculo Avanzado*, Limusa, México, D. F.
- [5]. F. A. Graybill (2000), *Theory and Application of the Linear Model*, Duxbury, New York.
- [6]. F. A. Graybill (2001), *Matrices with Applications in Statistics* Duxbury, New York.
- [7]. D. A. Harville (2008), *Matrix Algebra Form a Statistician's Perspective*, Springer-Verlaf, New York.
- [8]. A. I. Khuri (2002), *Advanced Calculus with Applications in Statistics*, Wiley, New York.
- [9]. E. L. Lehmann and G. B. Casella, (1998), *Theory of Point Estimation*, Springer, New York.
- [10]. E. L. Lehmann and J. P. Romano, (1999), *Testing Statistical Hypothesis*, Springer, New York.
- [11]. M. Loève (1984), *Probability Theory, I*, Springer-Verlag, New York.
- [12]. D. C. Montgomery (2011), *Introduction to Statistical Quality Control*, 6th Edition, Wiley, New York.
- [13]. A. M. Mood, D. C. Boes and F. A. Graybill (1984), *Introduction to the Theory of Statistics*, McGraw-Hill, New York.
- [14]. W. Rudin (1984), *Real and Complex Analysis*, McGraw-Hill, New York.
- [15]. H. L. Royden (2003), *Real Analysis*, MacMillan, London.
- [16]. J. Shao (2010), *Mathematical Statistics*, Springer, New York.
- [17]. D. Wackerly, W. Mendenhall y R. L. Scheaffer (2009), *Mathematical Statistics with Applications*, Prentice-Hall, New York.